# Invariants of fast solutions of KdV -Burgers Equations 

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## 1 Introduction

We are concerned with invariants of the solutions of

$$
\begin{equation*}
\frac{d U_{k}}{d t}=U_{k}\left(U_{k-1}-U_{k+1}\right) \tag{1}
\end{equation*}
$$

with either cyclic boundary conditions

$$
\begin{equation*}
U_{0}=U_{N}, U_{N+1}=U_{1} \tag{2}
\end{equation*}
$$

or zero boundary conditions

$$
\begin{equation*}
U_{0}=0, U_{N+1}=0 \tag{3}
\end{equation*}
$$

The zero boundary condition case is discussed in Moser [3] for the related problem

$$
\begin{equation*}
\frac{d A_{k}}{d t}=A_{k}\left(A_{k-1}^{2}-A_{k+1}^{2}\right) \tag{4}
\end{equation*}
$$

which is obtained from eq. (1) by replacing $U_{k}$ with $A_{k}^{2}$ and rescaling $t$, while the cyclic boundary condition case is discussed in Goodman \& Lax [2] for even $N$.

Moser notes the existence of $\lceil N / 2\rceil$ polynomials of $A_{k}^{2}$ that are invariant and states that they are independent. They are the coefficients of the characteristic equation of an $N+1$ by $N+1$ zero-diagonal symmetric Jacobi matrix whose terms depend on the $A_{k}$. Goodman \& Lax discuss $N / 2$ invariants expressed as the traces of powers of an $N$ by $N$ zero-diagonal symmetric Jacobi matrix and mention an additional invariant and this has recently been discussed in [1]. Here we give an explicit form of the invariants in both cases (including the cyclic case for odd $N$ ), show that this form is equivalent to the forms in the cited work, and show that they are functionally independent.

## 2 An Explicit Form of the Invariants

From now on we will consider indices to be restricted to the range $1, \cdots, N$. References outside that range (that is, to 0 or $N+1$ ) will be handled by applying eq. (2) or eq. (3) depending on the boundary condition.

We define a pair of integers to be non adjacent if they differ by at least 2 . In the cyclic boundary condition case, integers 1 and $N$ are considered to be adjacent. We define an I-set of the integers to be any non-null set of integers that are mutually non-adjacent.

In particular, any singleton integer is an I-set, no I-set can contain more than $\lfloor N / 2\rfloor$ members ( $\lceil N / 2\rceil$ in the zero boundary case). There are either one, two, or three of these largest I-sets, depending on the boundary condition and the evenness of $N^{1}$.

It will be convenient to associate each I-set with an $N$-bit string that has a 1 entry in the $i$-th position if $i$ is in the $\mathbf{I}$-set. In this notation, an $\mathbf{I}$-set is simply a $N$-bit string that has at least one 0 between each 1 entry and, in the cyclic case, a 0 on at least one end of the string. There is a (1-1) correspondence between each such string and each I-set, so we will use the notations interchangeably.

Two I-sets are distinct if and only if at least one member is different. We define an $\mathbf{I}_{j}$-set to be an $\mathbf{I}$-set with exactly $j$ members, and $\mathbf{S}_{j}$ to be the set of all distinct $\mathbf{I}_{\mathbf{j}}$-sets.

## Theorem

The following polynomials are invariants of eq. (1)

$$
\begin{equation*}
\phi_{j}\left(U_{1}, U_{2}, \cdots, U_{N}\right)=\sum_{\mathbf{I} \in \mathbf{S}_{j}} \prod_{i \in \mathbf{I}} U_{i} \tag{5}
\end{equation*}
$$

## Proof

Differentiating eq. (5) and using eq. (1) we get

$$
\begin{equation*}
\frac{d \phi_{j}}{d t}=\sum_{\mathbf{I} \in \mathbf{S}_{j}} \sum_{k \in \mathbf{I}} \prod_{i \in \mathbf{I}} U_{i}\left(U_{k-1}-U_{k+1}\right) \tag{6}
\end{equation*}
$$

Working with the bit-string representation, differentiation doubles the number of products due to the $\left(U_{k-1}-U_{k+1}\right)$ factor and changes a zero to a one, once on the left and once on the right of an existing one in an $\mathbf{I}$ set since there is at least one zero between any pair of ones in an $\mathbf{I}$. There are two cases to consider: a single zero between a pair of ones, and two or more zeros. In the single zero case where part of the string contains $[\cdots 01010 \cdots]$ differentiation of the $U$ represented by the first 1 introduces the term $[\cdots 01110 \cdots]$ with a negative sign while differentiation of the $U$ represented by the second 1 introduces the term $[\cdots 01110 \cdots]$ with a positive sign. Hence they cancel. In the multiple zero case, where part of the string contains $[\cdots 0100 \cdots]$ differentiation of the $U$ represented by the its 1 introduces the term $[\cdots 0110 \cdots]$ with a negative sign. However, since all non-adjacent combinations are present in $S_{j}$ the term $[\cdots 0010 \cdots]$ is also present and differentiation of its $U$ introduces the term $[\cdots 0110 \cdots]$ with a positive sign. Hence all terms cancel and the expression is invariant. QED

[^0]In the cyclic case, the function

$$
\begin{equation*}
\phi_{0}=\prod_{i=1}^{N} U_{i} \tag{7}
\end{equation*}
$$

is also invariant, as can be seen by direct computation.

## Theorem

The invariants eq. (5) (plus eq. (7) in the cyclic case) are functionally independent.

## Proof

If the invariants were functionally dependent then there exists an $F$ such that

$$
F\left(\left\{\phi_{j}\right\}\right) \equiv 0
$$

Differentiating w.r.t. $U_{i}$ we have

$$
\sum_{j} \frac{\partial F}{\partial \phi_{j}} \frac{\partial \phi_{j}}{\partial U_{i}}=0, i=1, \cdots, N
$$

In other words, the Jacobian $J=\partial \phi_{j} / \partial U_{i}$ would not have full rank. We prove the theorem by showing that $J$ has full rank. We do this by setting $U_{i}=\epsilon^{i-1}$, deleting columns of $J$, and showing that there exists an $\epsilon_{0}$ such that the remaining square matrix is non-singular for all $\epsilon<\epsilon_{0}>0$.

In the cyclic case we have the additional invariant $\phi_{0}$. We place this in the last position so that it determines the last row of $J$, but in the presentation of the proof below this row is assumed absent unless it is specifically stated otherwise.

Each entry in the $j$-th row of $J$ is the sum of products of $j-1 U_{i}$ 's so is a sum of powers of $\epsilon$. We want to identify the smallest power present in each term. Clearly it comes from the entries with the lowest indexed $U_{i}$ 's. In the $j$-th row the lowest term that can be present is $U_{1} U_{3} \cdots U_{2 j-3}$ which will lead to a term $\epsilon^{(j-2)(j-1)}$ and this cannot appear in any column to the left of the $2 j-1$-st column. All elements to the left of this entry in this row will have a higher power of $\epsilon$ and no element to the right of it will have a lower power. (For $j=1$ this is a null statement since all elements in the first row are 1.) In the cyclic case, the last row of $J$ has $\epsilon^{N(N-1) / 2+1-j}$ in the $j$-th column, so its lowest power is in the last position.

Divide the $j$-th row by the lowest power of $\epsilon$ present in that row. This does not change the rank of the matrix. Now the matrix consisting of the odd-numbered columns (plus the last column in the cyclic even- $N$ case) has the following property: In each row elements to the left of the diagonal are $\mathrm{O}(\epsilon)$, the diagonal elements are $1+\mathrm{O}(\epsilon)$, while elements to the right of the diagonal are no larger than $1+\mathrm{O}(\epsilon)$. Hence, as $\epsilon \rightarrow 0$ the determinant of this matrix $\rightarrow 1$. Hence, there exists $\epsilon_{0}$ such that the matrix is non-singular for $0 \leq \epsilon \leq \epsilon_{0}$. Hence the invariants are independent.

## 3 Equivalence of Invariants to those of Moser and GoodmanLax

Defining $A_{j}=+\sqrt{U_{j}}$, Moser considers the $N+1$ by $N+1$ Jacobi matrix

$$
L=\left(\begin{array}{cccccc}
0 & A_{1} & 0 & & &  \tag{8}\\
A_{1} & 0 & A_{2} & & 0 & \\
& \cdot & \cdot & \cdot & & \\
& & \cdot & \cdot & . & \\
& 0 & & A_{N-1} & 0 & A_{N} \\
& & & 0 & A_{N} & 0
\end{array}\right)
$$

and shows that eq. (1) is an isospectral transformation of $L$ and hence that the coefficients of $L$ 's characteristic polynomial are invariants. Goodman \& Lax consider the $N$ by $N$ matrix

$$
L=\left(\begin{array}{cccccc}
0 & A_{1} & 0 & & & A_{N}  \tag{9}\\
A_{1} & 0 & A_{2} & & 0 & \\
& \cdot & \cdot & \cdot & & \\
& & \cdot & \cdot & \cdot & \\
& 0 & & A_{N-2} & 0 & A_{N-1} \\
A_{N} & & & 0 & A_{N-1} & 0
\end{array}\right)
$$

for even $N$ and show that the trace of the powers of $L$ are invariant. Note that because of the structure of $L$ only the even powers of $L$ have non-zero traces and only the coefficients of $\lambda^{N-2 n}, n=1,2, \cdots$ in the characteristic polynomial of $L$ yield meaningful invariants. (The above statement is not true for odd $N$ in the cyclic case.) These are, of course, related conditions on $L$ since the trace of a matrix is the sum of its eigenvalues.

It is convenient to re-order the rows and columns of $L$ placing the odd-numbered rows and columns first. When we do this for eq. (8) we get

$$
L=\left(\begin{array}{cc}
0 & B^{T}  \tag{10}\\
B & 0
\end{array}\right)
$$

where the matrix $B$ is

$$
B=\left(\begin{array}{ccccc}
A_{1} & A_{2} & 0 & &  \tag{11}\\
0 & A_{3} & A_{4} & & \\
& \cdot & \cdot & \cdot & \\
& & & A_{N-1} & A_{N}
\end{array}\right)
$$

if $N$ is even, or

$$
B=\left(\begin{array}{ccccc}
A_{1} & A_{2} & 0 & &  \tag{12}\\
0 & A_{3} & A_{4} & & \\
& \cdot & \cdot & \cdot & \\
& & & A_{N-2} & A_{N-1} \\
& & & & A_{N}
\end{array}\right)
$$

if $N$ is odd.

When we apply the renumbering to eq. (9) for even $N$ we get a similar structure with

$$
B=\left(\begin{array}{ccccc}
A_{1} & A_{2} & 0 & & 0  \tag{13}\\
0 & A_{3} & A_{4} & & \\
& \cdot & \cdot & \cdot & \\
& & & A_{N-3} & A_{N-2} \\
A_{N} & & & & A_{N-1}
\end{array}\right)
$$

Note that $L^{2}$ is block triangular with two blocks, $B B^{T}$ and $B^{T} B . B$ is either square or has one more column than row. $B B^{T}$ and $B^{T} B$ have the same eigenvalues if $B$ is square, otherwise $B^{T} B$ has an additional zero eigenvalue. Hence the eigenvalue set of $L^{2}$ consists of pairs of the eigenvalues of $B B^{T}$ plus a zero value if $N$ is odd. (The corresponding eigenvalues of $L$ occur in alternating sign pairs.) Thus, the Moser invariants are just the invariancy of the characteristic polynomial $C\left(B B^{T}\right)$. We will show that the coefficients of $C\left(B B^{T}\right)$ are the polynomials $\phi_{j}$ given in the previous section.

In the cyclic even $N$ case, Goodman and Lax note that the traces of $L^{2 n}$ are invariants for $n=1,2, \cdots N / 2$. Since

$$
\begin{equation*}
\operatorname{tr}\left(L^{2 n}\right)=2 \sum_{i=1}^{N / 2} \lambda_{i}^{n}\left(L^{2}\right) \tag{14}
\end{equation*}
$$

where $\left\{\lambda_{i}\left(L^{2}\right)\right\}$ is the set of $N / 2$ eigenvalues of $L^{2}$, this is equivalent to the conditions that the eigenvalues of $L^{2}$ are invariant, and hence that $C\left(B B^{T}\right)$ is invariant.

## 4 Coefficients of the Characteristic Polynomial

While the polynomials given in the first section are invariants for all cases, including a cyclic boundary and odd $N$, here we exclude that case so that we can study the $C\left(L^{2}\right)$ by studying $C\left(B B^{T}\right)$, If $N$ is even, $W=B B^{T}$ is

$$
W=\left(\begin{array}{ccccccc}
A_{1}^{2}+A_{2}^{2} & A_{2} A_{3} & 0 & \cdots & 0 & 0 & c A_{N} A_{1}  \tag{15}\\
A_{2} A_{3} & A_{3}^{2}+A_{4}^{2} & A_{4} A_{5} & \cdots & 0 & 0 & 0 \\
& & & \cdots & & & \\
0 & 0 & 0 & \cdots & A_{N-4} A_{N-3} & A_{N-3}^{2}+A_{N-2}^{2} & A_{N-2} A_{N-1} \\
c A_{N} A_{1} & 0 & 0 & \cdots & 0 & A_{N-2} A_{N-1} & A_{N-1}^{2}+A_{N}^{2}
\end{array}\right)
$$

where $c=1$ for the cyclic case, 0 otherwise. If $N$ is odd (the zero boundary case) $B B^{T}$ is

$$
W=\left(\begin{array}{ccccccc}
A_{1}^{2}+A_{1}^{2} & A_{2} A_{3} & 0 & \cdots & 0 & 0 & 0  \tag{16}\\
A_{2} A_{3} & A_{3}^{2}+A_{4}^{2} & A_{4} A_{5} & \cdots & 0 & 0 & 0 \\
0 & & & \cdots & & & \\
0 & 0 & 0 & \cdots & A_{N-3} A_{N-2} & A_{N-2}^{2}+A_{N-1}^{2} & A_{N-1} A_{N} \\
0 & 0 & 0 & \cdots & 0 & A_{N-1} A_{N} & A_{N}^{2}
\end{array}\right)
$$

We write the characteristic polynomial of $W$ as

$$
\begin{equation*}
C(W)=\operatorname{det}(\lambda I-W)=\sum_{j=0}^{M}(-1)^{j} \lambda^{M-j} \sum_{q}\left\{P_{j q}\right\} \tag{17}
\end{equation*}
$$

where $M$ is the dimension of $W$ and $\left\{P_{j q}\right\}, q=1, \cdots$ is the set of all principal minors of $W$ of size $j$. There is a principal minor of size $j$ corresponding to each set of $j$ different integers from $1, \cdots, M$.

## Theorem

$$
\begin{equation*}
\sum_{q}\left\{P_{j q}\right\}=\sum_{\mathbf{I} \in \mathbf{W}_{j}} \prod_{i \in \mathbf{I}} U_{i}+2 \delta_{n j} \prod_{i=1}^{N} A_{i} \tag{18}
\end{equation*}
$$

where $\delta_{j k}$ is the Kroneker delta.
Proof
A principal minor, $P_{j q}$, of $W$ of size $j$ has the form

$$
P_{j .}=\operatorname{det}\left(\begin{array}{cccc}
T_{1} & 0 & \cdots & 0  \tag{19}\\
0 & T_{2} & \cdots & 0 \\
& & \cdots & \\
0 & 0 & \cdots & T_{k}
\end{array}\right)
$$

Except for two special cases, each $T_{i}$ is a tridiagonal matrix of the form in eq. (15) with $c$ $=0$ and indices ranging from $2 p_{j}-1$ to $2 q_{j}$ rather than from 1 to $N$. The first special case is the zero boundary case with odd $N$ where $T_{k}$ could have the form of eq. (16) with an initial index of $2 p_{j}$ instead of 1 . The second is the cyclic boundary with $j=N / 2$ when the principal minor is the whole matrix $\operatorname{det}(W)$ where $W$ is given in eq. (15) with $c=1$. Let us dispose of this case first. Define $d(c)=\operatorname{det}(W)$ for the $W$ in eq. (15). We have

$$
\begin{equation*}
d(1)=d(0)+2 \prod_{i=1}^{N} A_{i} \tag{20}
\end{equation*}
$$

This explains the second term on the rhs of eq. (18). From now on we can just consider the zero boundary case.

From eq. (19) we have $P_{j}=\prod_{i=1, \cdots k} \operatorname{det}\left(T_{i}\right)$. An important observation is that each $\operatorname{det}\left(T_{i}\right)$ in the product is a polynomial in a set of adjacent $\left\{A_{m}\right\}$ that are non-adjacent to all $\left\{A_{m}\right\}$ in any other $\operatorname{det}\left(T_{k}\right)$ in that product. This can be seen by considering the case $N=8$ for the zero boundary case and examining the $P_{3}$. obtained by removing the third row and column to get

$$
P_{3 .}=\operatorname{det}\left(\begin{array}{ccc}
A_{1}^{2}+A_{2}^{2} & A_{2} A_{3} & 0  \tag{21}\\
A_{2} A_{3} & A_{3}^{2}+A_{4}^{2} & 0 \\
0 & 0 & A_{7}^{2}+A_{8}^{2}
\end{array}\right)
$$

When there is a "break" in the integer sequence that determines the principal minor, the off diagonal element is missing and the indices of the $A$ 's in the next block are at least 3 larger.

The sum of the dimensions of the $T$ blocks is $j$ as each $T_{i}$ corresponds to each consecutive group of integers in the selection of $j$ from $1, \cdots, M$ that determines the particular $P_{j}$. Note that in the cyclic case, a $T_{i}$ may "wrap around" the end of $W$. For example, if $N=8$ $(M=4)$ with the third row and column removed, the sole $T$ after a reordering of row and
columns is

$$
T_{1}=\left(\begin{array}{ccc}
A_{7}^{2}+A_{8}^{2} & A_{8} A_{1} & 0  \tag{22}\\
A_{8} A_{1} & A_{1}^{2}+A_{2}^{2} & A_{2} A_{3} \\
0 & A_{2} A_{3} & A_{3}^{2}+A_{4}^{2}
\end{array}\right)
$$

We will show that if the dimension of $T_{i}$ is $m_{i}$ then $\operatorname{det}\left(T_{i}\right)$ consists of all products without adjacent members of $m_{i}$ different $A_{k}^{2}$ for the $A_{k}$ 's occurring in $T_{i}$. Since $P_{j}$. is the product of a set of $\operatorname{det}\left(T_{i}\right)$ where the $A_{k}$ members of different $T_{i}$ are non-adjacent, $P_{j}$ consists of products of $j=\sum_{i} m_{i}$ non-adjacent $A_{k}^{2}$ 's where the $k$ 's are the combination of $j$ integers from $1, \cdots, M$ that determine $P_{j}$. Since eq. (18) sums over all combinations, all products of $j$ non-adjacent $U_{i}=A_{i}^{2}$ are present, and each appears only once.

To complete the proof we need to show the
Lemma If the $M$ by $M$ matrix $W$ is as given in eq. (15) with $c=0$ or eq. (16) then

$$
\begin{equation*}
\operatorname{det}(W)=\sum_{I \in I_{M}} \prod_{i \in I} U_{i} \tag{23}
\end{equation*}
$$

where $I_{M}$ is a non-adjacent set of $M$ integers from $1, \cdots, N$.

## Proof

We proceed by induction. Let $w(M)$ be the $\operatorname{det}(W)$ when $W$ is $M$ by $M$ Defining $w(0)$ as 1 and the product of zero $U_{i}$ 's as 1 , it is clearly true for $M=0$. It is also trivially true for $M=1$ where $w(1)$ is either $U_{1}+U_{2}$ or $U_{1}$ corresponding to eq. (15) and eq. (16) respectively. For general $M$ we have

$$
\begin{equation*}
w(M)=W_{M M} w(M-1)-W_{M-1, M} W_{M, M-1} w(M-2) \tag{24}
\end{equation*}
$$

where $W_{M M}$ is either $A_{N-1}^{2}+A_{N}^{2}$ or $A_{N}^{2}$ and $W_{M-1, M}^{2}$ is either $A_{N-2}^{2} A_{N-1}^{2}$ or $A_{N-1}^{2} A_{N}^{2}$. In either case, the first term on the rhs of eq. (24) generates all products of $M$ different $U_{j}$ that are non-adjacent, but it also generates terms with a single adjacency, namely between $U_{L}$ and $U_{L-1}$ where $L$ is either $N-1$ or $N$. That is exactly the set of terms subtracted by the second term on the rhs of eq. (24). Thus $w(M)$ has the desired property. QED

This shows that the Goodman Lax invariants (the traces of even powers of $L$ ) plus the product of all $U_{i}$ ) are equivalent to the simple algebraic invariants given earlier when $N$ is even. These algebraic expressions are also invariant when $N$ is odd although there appears to be no corresponding matrix formulation.

In the zero boundary case we have shown that there is a simple algebraic representation of the invariants given by Moser.

## References

[1] Z. Artstein, C. W. Gear, I. G. Kevrekidis, M. Slemrod, and E. S. Titi, "Analysis and Computation of a discrete KDV-Burgers type equation with fast dispersion and slow diffusion," arXiv:0908.2752v1 [math.NA] 19 Aug 2009.
[2] J. Goodman and P. D. Lax, (1998) "On dispersive difference schemes: I," Comm Pure Appl. Math., 41 (1988) pp. 591-613
[3] J. Moser "Three integrable Hamiltonian systems connected with isospectral deformations," iin Dynamical Systems, Theory and Applications, Lecture Notes in Phys., 38, Springer, Berlin, 1975, pp 467-497.


[^0]:    ${ }^{1}$ For the cyclic case and even $N$ the two sets are $\{i+1, i+3, i+5, \cdots, i+N-1\}$ for $i=0$ or 1 . If $N$ is odd the three largest sets are $\{i+1, i+3, i+5, \cdots, i+N-2\}$ for $i=0,1$, or 2 . For the zero boundary case the largest is $\{i+1, i+3, i+5, \cdots, i+N-1\}$ for $i=0$ or 1 when $N$ is even, or $\{1,3,5, \cdots, N\}$ when $N$ is odd.

