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Due on Thursday, November 14, 2024, at 1:30pm EST, on Gradescope

For all problems that involve coding, please include your code.

### Problem 1: Princeton's development plans

In the file `princetoncampus.png`, you can see a bird's eye view of our campus before the recent constructions with 6 residential colleges, and Dillon gym, marked by crosses.

Open this image using the following code once you've added the image to your Matlab path:

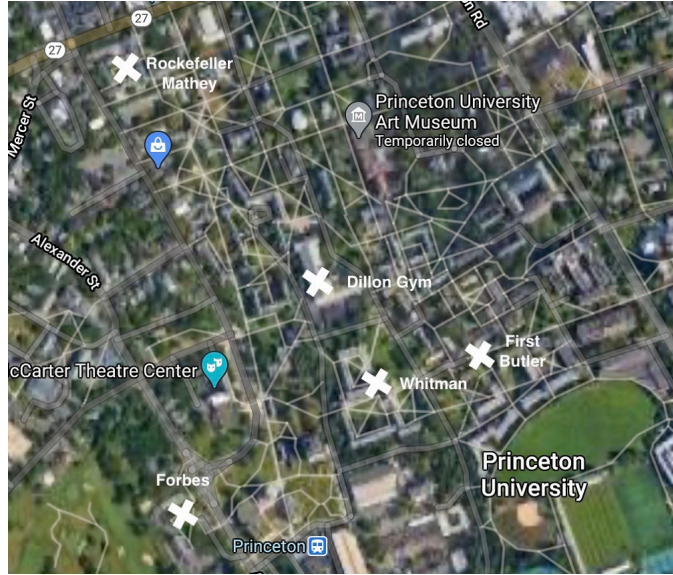
```
1 colleges = imread('princetoncampus.jpeg');  
2 imshow(colleges, 'InitialMagnification', 50);  
3 hold on
```

For Python users, you can use the following code in order to be consistent with Matlab.

```
1 import numpy as np  
2 import matplotlib.pyplot as plt  
3 from matplotlib.image import imread  
4  
5 colleges = imread('princetoncampus.jpeg')  
6 colleges_flipped = np.flipud(colleges)  
7 plt.imshow(colleges_flipped, origin='lower')
```

We have placed a grid (a coordinate system) on the image with  $(0,0)$  in the lower left corner. For those of you who want to see this grid, you can do so by copying the code given in `plotgrid.m/plotgrid.py` into Matlab/Python, but this is not mandatory.

On this grid, the colleges have the following coordinates:  $z_1 = (8, 34.5)$  for the regroupment Rockfeller-Mathey,  $z_2 = (12, 4)$  for Forbes,  $z_3 = (25, 13)$  Whitman,  $z_4 = (32, 15)$  for Butler. Dillon gym has coordinates  $z_5 = (21, 20)$ .



### Part 1: Unconstrained optimization

Princeton University wants to understand if the current location of Dillon gym is convenient for undergraduate students. To answer this question, the Princeton Trustees would like to know where a gym that minimizes the sum of distances squared to the residential colleges would be. The location of this gym is the solution to the following optimization problem:

$$\min_x \sum_{i=1}^4 \|x - z_i\|^2. \quad (1)$$

If the location of Dillon gym is considered “sufficiently” close to the optimal location, then they will not rebuild the gym; if it isn’t, then they will.

1. Solve this problem using CVX. Report the optimal solution  $x^*$  and the optimal value. To visualize where  $x^*$  is on the map, use the function `Circledraw.m` to plot a small circle (e.g. of radius 0.5) around the point. What building does this correspond to?

**Remark:** To plot a circle, download the file `Circledraw.m` into your Matlab directory. The command `Circledraw(x,y,r,'color')` will draw a circle of center  $(x,y)$ , of radius  $r$  and of color `color` (this could be `'r'` for red for example or `'magenta'`). Make sure you have opened the image in Matlab as said previously. The function `plot(x,y)` will *not* work here as we are working with a different coordinate system.

For Python users, you can use the following code in order to be consistent with Matlab.

```

1 from matplotlib.patches import Circle
2
3 scale = 22
4 circle = Circle((x*scale , y*scale) , r*scale , color='red' ,
5                 fill=False)
6 plt.gca().add_patch(circle)
7 plt.axis('off')
8 plt.show()

```

2. You are tired of using CVX as a black-box and want to implement your own solver. In this part of the question, we will solve (1) by implementing two variants of gradient descent. For each implementation, use a random point in  $[0, 1] \times [0, 1]$  as a starting point and stop the iterations when either  $\|\nabla f(x_k)\| < 10^{-5}$  or the iteration count has reached 100. (The function  $f$  here is the objective function.)

(a) Implement steepest descent with exact line search (a.k.a. the line minimization rule). How many steps does convergence take? Why?

(b) Implement steepest descent with constant stepsize for three different values of the stepsize:  $\alpha = \frac{1}{2}$ ,  $\alpha = \frac{1}{4}$  and  $\alpha = \frac{2}{9}$ . Plot the iterates you obtain on three different figures. For each step size, do the iterates (i) converge to the global minimum, (ii) oscillate, or (iii) diverge? Why?<sup>1</sup>

**Hint:** To make the analysis simpler, you may want to perform a change of variables so the minimum of  $f$  gets shifted to the origin in the new coordinates.

## Part 2: Constrained optimization

The state of New Jersey has recently enacted a law that requires all public buildings to be at a maximum distance of 8 from a fire hydrant. There is only one available fire hydrant for the gym at location (35, 28). Write down a new optimization problem (call it problem (2)) that resolves (1) with the fire hydrant constraint. Prove that the optimal solution to (2) must be attained on the boundary of the feasible set. Use CVX and report the optimal solution and the optimal value. On the same figure, plot the optimal solution to (2), the optimal solution to (1), and the boundary of the feasible set of (2). Does the plot make sense?

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<sup>1</sup>If you are wondering how rigorous your answer should be, we remind you that the answer to the question “why?” in mathematics is *always* a proof ;)

**Problem 2: Finding a Lyapunov function for a linear dynamical system**

Consider the linear dynamical system in two dimensions given by

$$x_{k+1} = Ax_k,$$

where

$$A = \begin{pmatrix} 0 & 2 \\ \frac{1}{4} & 0 \end{pmatrix}, x_k = \begin{pmatrix} w_k \\ v_k \end{pmatrix} \in \mathbb{R}^2,$$

and  $k = 0, 1, \dots$  is the index of time. We want to prove that the system is “stable”; i.e., that for all  $x_0 \in \mathbb{R}^2$ , we have  $x_k \rightarrow 0$  as  $k \rightarrow \infty$ .

Prove this property by finding an appropriate Lyapunov function for this system. (Hint: you can restrict your search to functions of the form  $V(w, v) = aw^2 + bv^2$ , where  $a, b \in \mathbb{R}$ .)