

# Limits of Computation + Course Recap

**ORF 363/COS 323**

**Instructor: Amir Ali Ahmadi**

# Reminder: NP-hard and NP-complete problems

## Definition.

- A decision problem is said to be **NP-hard** if every problem in NP reduces to it via a polynomial-time reduction.  
(roughly means “harder than all problems in NP.”)

## Definition.

- A decision problem is said to be **NP-complete** if
  - (i) It is NP-hard
  - (ii) It is in NP.(roughly means “the hardest problems in NP.”)

## Remarks.

- NP-hardness is shown by a reduction from a problem that’s already known to be NP-hard.
- Membership in NP is shown by presenting an easily checkable certificate of the YES answer.
- NP-hard problems may not be in NP (or may not be known to be in NP as is often the case.)

# The complexity class NP

NP

NON-DETERMINISTIC

- ADDITION
- MULTIPLICATION
- LINEQ
- LP
- MAXFLOW
- MINCUT
- MATRIXPOS
- SHORTEST PATH
- SDP  $\epsilon$
- PRIMES
- ZEROSUMNASH
- PENONPAPER,...

- TSP
- MAXCUT
- STABLE SET
- SAT
- 3SAT
- PARTITION
- KNAPSACK
- IP
- COLORING
- VERTEXCOVER
- 3DMATCHING
- SUDOKU,...

EP

NP-complete

# Reductions

- A reduction from a decision problem A to a decision problem B is
  - a “general recipe” (aka an algorithm) for taking any instance of A and explicitly producing an instance of B, such that
  - the answer to the instance of A is YES if and only if the answer to the produced instance of B is YES.

▪ This enables us to answer A by answering B.

▪ Using reductions for showing NP-hardness:

- If A is known to be hard, then B must also be hard.

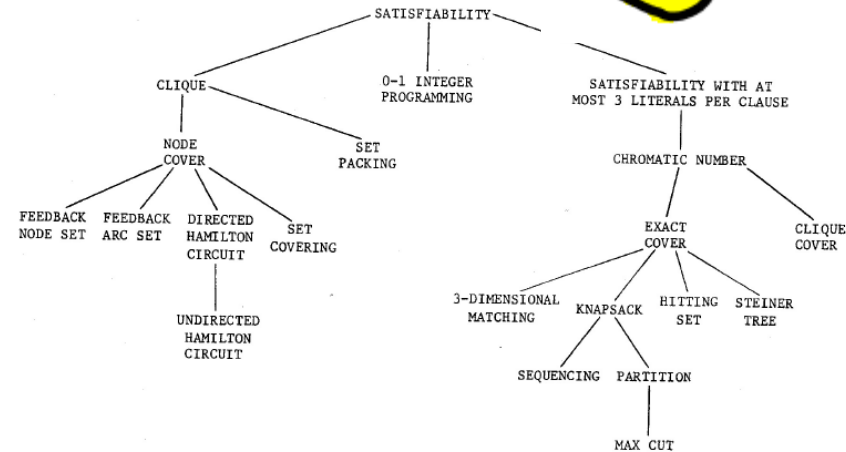
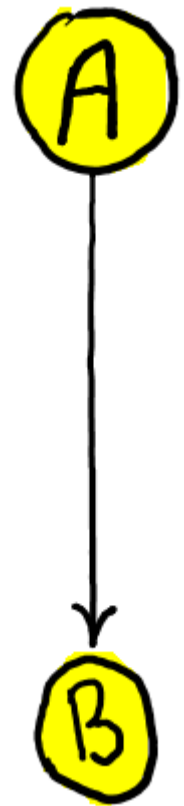


FIGURE 1 - Complete Problems

# P versus NP

- All NP-complete problems reduce to each other!
- If you solve one in polynomial time, you solve ALL in polynomial time!



- Assuming  $P \neq NP$ , no NP-complete problem can be solved in polynomial time.
- This shows **limits of efficient computation (under a complexity theoretic assumption)**

- **Today:** limits of computation in general (and under no assumptions)

# Matrix mortality

Consider a collection of  $m$   $n \times n$  matrices  $\{A_1, \dots, A_m\}$ .

We say the collection is **mortal** if there is a finite product out of the matrices (possibly allowing repetition) that gives the zero matrix.

Example 1:

$A_1 =$

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$A_2 =$

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

```
>> A1*A2
```

```
ans =
```

$$\begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix}$$

```
>> A1*A2*A1*A2
```

```
ans =
```

$$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Example from [W11].

Mortal.

# Matrix mortality

Consider a collection of  $m$   $n \times n$  matrices  $\{A_1, \dots, A_m\}$ .

We say the collection is **mortal** if there is a finite product out of the matrices (possibly allowing repetition) that gives the zero matrix.

Example 2:

$$A_1 = \begin{pmatrix} 1 & -2 \\ 3 & 0 \end{pmatrix} \quad A_2 = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix} \quad A_3 = \begin{pmatrix} 1 & 2 \\ 0 & -1 \end{pmatrix}$$

Not mortal. (How to prove that?)

- In this case, can just observe that all three matrices have nonzero determinant.
- Determinant of product = product of determinants.

But what if we aren't so lucky?

```
>> A1*A2*A3
ans =
     2     5
     0     3
>> A1*A2*A3*A1*A3
ans =
    17    38
     9    18
>> A2*A2*A3*A1*A3
ans =
     7    16
    -3    -6
>> A2*A2*A1*A3
ans =
     1     4
     3     6
>> ...
```

# Matrix mortality

## ▪ MATRIX MORTALITY

- **Input:** A set of  $m$   $n \times n$  matrices with integer entries.
- **Question:** Is there a finite product that equals zero?

**Thm.** MATRIX MORTALITY is **undecidable** already when

- $n = 3, m = 7,$

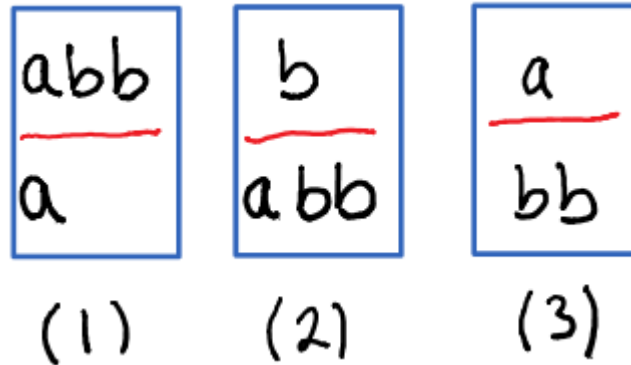
or

- $n = 21, m = 2.$

- This means that **there is no finite time algorithm** that can take as input two 21x21 matrices (or seven 3x3 matrices) and always give the correct yes/no answer to the question whether they are mortal.
- This is a definite statement.  
(It doesn't depend on complexity assumptions, like P vs. NP or anything like that.)
  - How in the world would someone prove something like this?
  - By a **reduction** from another undecidable problem!



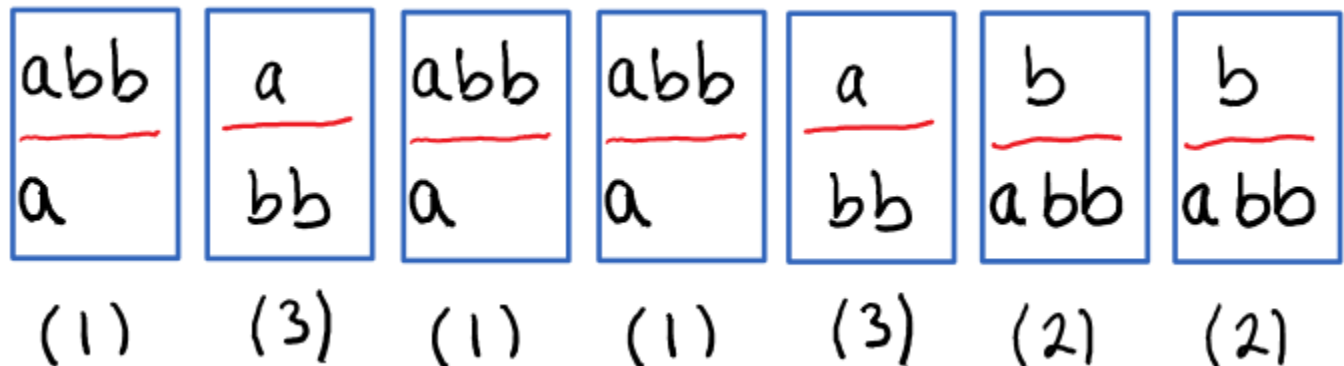
# The Post Correspondence Problem (PCP)



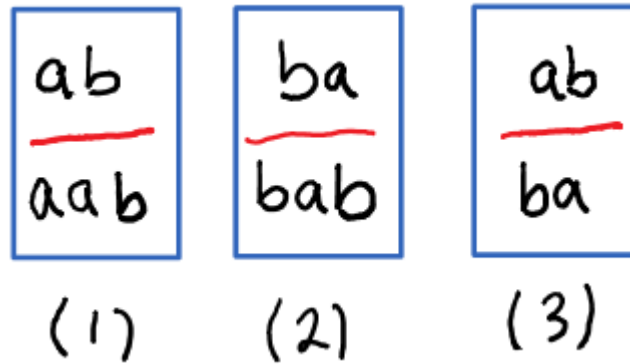
Emil Post  
(1897-1954)

Given a set of dominos such as the ones above, can you put them next to each other (repetitions allowed) in such a way that the top row reads the same as the bottom row?

Answer to this instance is **YES**:



# The Post Correspondence Problem (PCP)



Emil Post  
(1897-1954)

What about this instance?

Answer is **NO**. Why?

There is a length mismatch, unless we only use (3), which is not good enough.

**But what if we aren't so lucky?**

# The Post Correspondence Problem (PCP)

## ▪PCP

- Input:** A finite set of  $m$  domino types with letters  $a$  and  $b$  written on them.
- Question:** Can you put them next to each other (repetition allowed) to get the same word in the top and bottom row?



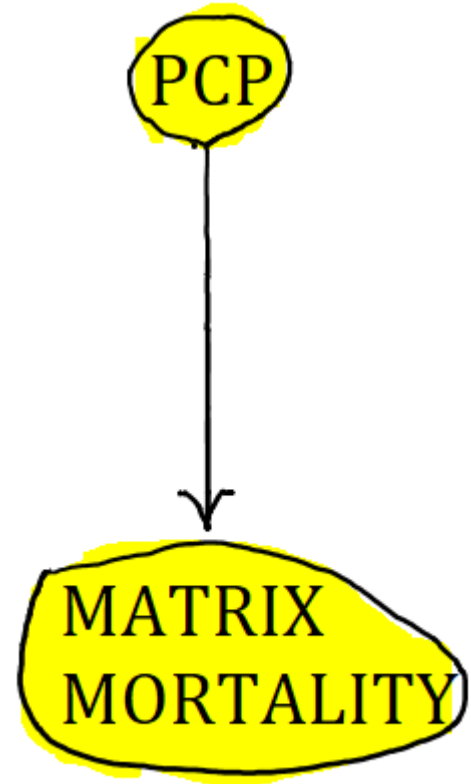
Emil Post  
(1897-1954)

**Thm.** PCP is **undecidable** already when  $m = 7$ .

- Again, we are **ruling out any finite time algorithm.**
- PCP is decidable for  $m = 2$ .
- Status unknown for  $2 < m < 7$ .

# Reductions

- There is a rather simple reduction from PCP to MATRIX MORTALITY; see, e.g., [Wo11].
- This shows that if we could solve MATRIX MORTALITY in finite time, then we could solve PCP in finite time.
- It's impossible to solve PCP in finite time (because of another reduction!)
- Hence, it's impossible to solve MATRIX MORTALITY in finite time.
- Note that these reductions only need to be finite in length (not polynomial in length like before).



# Integer roots of polynomial equations

- Can you give me three positive integers  $x, y, z$  such that

$$x^2 + y^2 = z^2?$$

- Sure: 

(3, 4, 5)	(5, 12, 13)	(8, 15, 17)	(7, 24, 25)
(20, 21, 29)	(12, 35, 37)	(9, 40, 41)	(28, 45, 53)

And there are infinitely many more...

- How about  $x^3 + y^3 = z^3?$

- How about  $x^4 + y^4 = z^4?$

- How about  $x^5 + y^5 = z^5?$

Fermat's last theorem tells us the answer is NO to all these instances.

# Integer roots to polynomial equations

What about integer solutions to  $x^3 + y^3 + z^3 = 29$ ?

YES: (3,1,1)

What about  $x^3 + y^3 + z^3 = 30$ ?

Looped in MATLAB over all  $|x, y, z|$  less than 10 million  $\rightarrow$  no solution!

But the answer is YES!!  $(-283059965, -2218888517, 2220422932)$

What about  $x^3 + y^3 + z^3 = 33$ ?

No one knows!

# Integer roots of polynomial equations

## ■ POLY INT

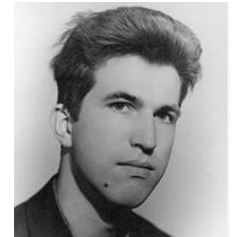
- **Input:** A polynomial  $p$  in  $n$  variables and of degree  $d$ .
- **Question:** Does it have an integer root?

- **Hilbert's 10<sup>th</sup> problem (1900):** Is there an algorithm for POLY INT?

- **Matiyasevich (1970)** – building on earlier work by Davis, Putnam, and Robinson:

**No!** The problem is undecidable.

- It's undecidable even in fixed degree and dimension (e.g.,  $d = 4, n = 58$ ).



From  
Logicomix

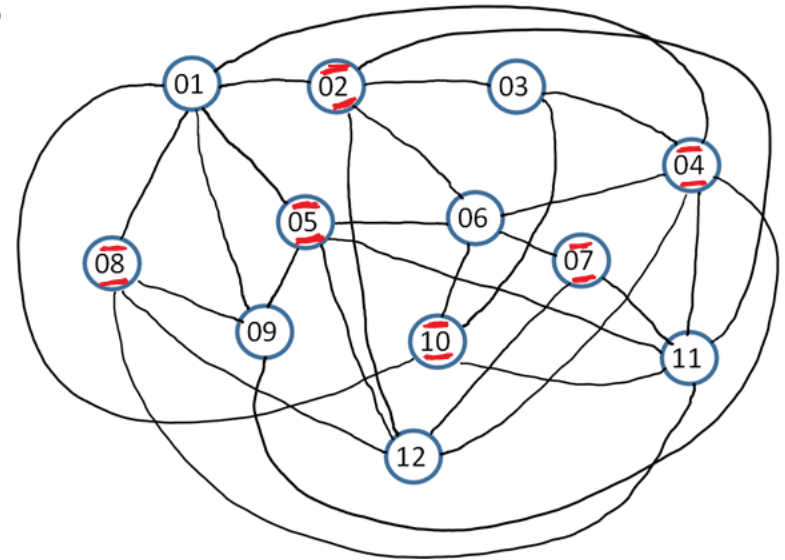
# Real/rational roots of polynomial equations

- If instead of integer roots, we were testing existence of **real roots**, then the problem would become decidable.
  - Such finite-time algorithms were developed in the past century (Tarski–Seidenberg )
- If instead we were asking for existence of **rational roots**,
  - We currently don't know if it's decidable!
- Nevertheless, both problems are **NP-hard**. For example for
  - A set of equations of degree 2
  - A single equation of degree 4.
  - Proof on the next slide.



# A simple reduction

- We give a simple reduction from STABLE SET to show that testing existence of a real (or rational or integer) solution to a set of quadratic equations is NP-hard.
- Contrast this to the case of linear equations which is in P.

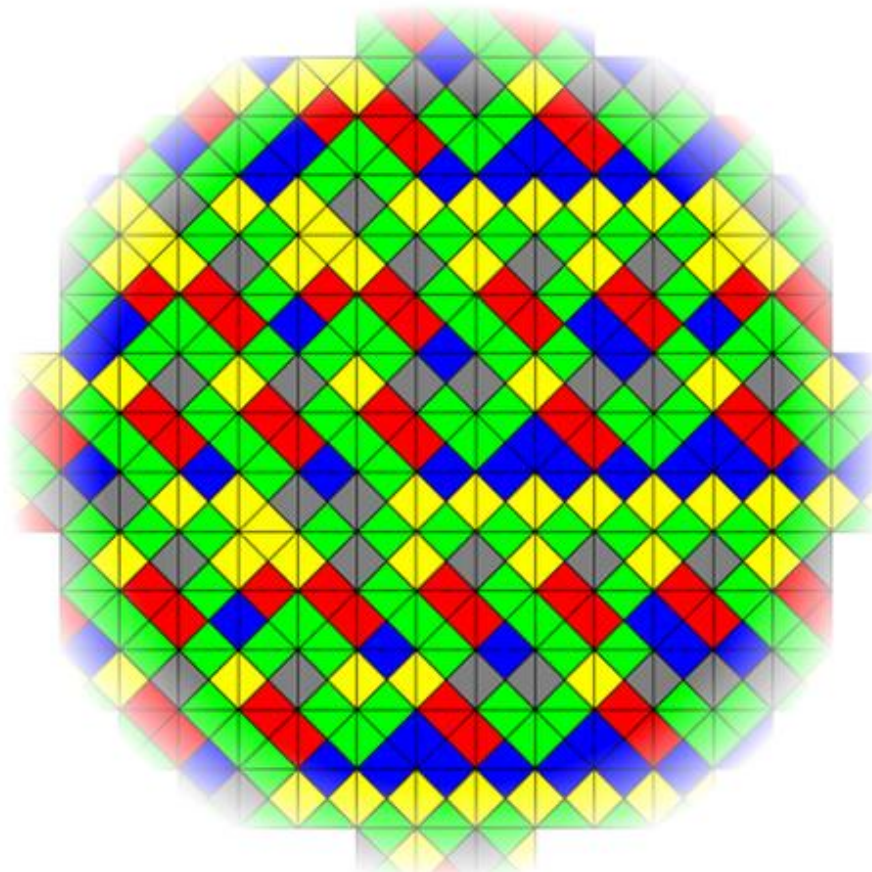
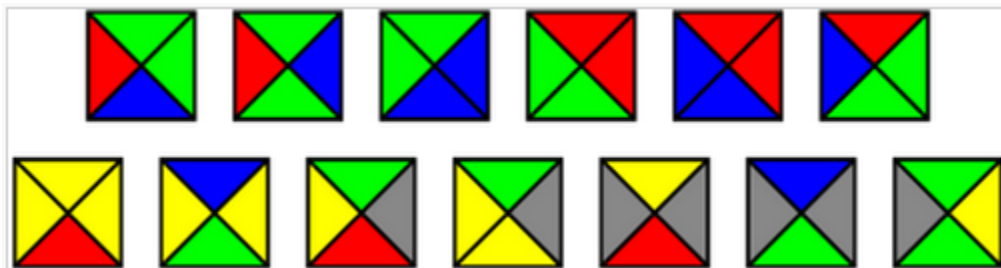


$$\begin{array}{l}
 \exists \text{ stable} \\
 \text{set of} \\
 \text{size } k
 \end{array}
 \Leftrightarrow
 \begin{array}{l}
 \exists x \text{ s.t.} \\
 \left[ \begin{array}{l}
 x_1 + \dots + x_n = k \\
 x_i + x_j \leq 1 \quad i, j \in E \\
 x_i \in \{0, 1\}
 \end{array} \right]
 \end{array}
 \Leftrightarrow
 \begin{array}{l}
 \exists x, z \text{ s.t.} \\
 \left[ \begin{array}{l}
 (x_1 + \dots + x_n - k)^2 = 0 \\
 1 - x_i - x_j = z_{ij}^2 \quad i, j \in E \\
 x_i(1 - x_i) = 0 \quad i = 1, \dots, n
 \end{array} \right]
 \end{array}$$

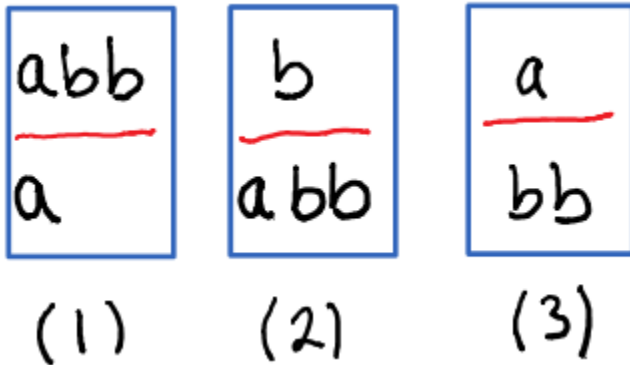
- How would you go from here to a single equation of degree 4?

# Tiling the plane

- Given a finite collection of tile types, can you tile the 2-dimensional plane such that the colors on all tile borders match.
- Cannot rotate or flip the tiles.
- The answer is YES, for the instance presented.
- But in general, the problem is undecidable.

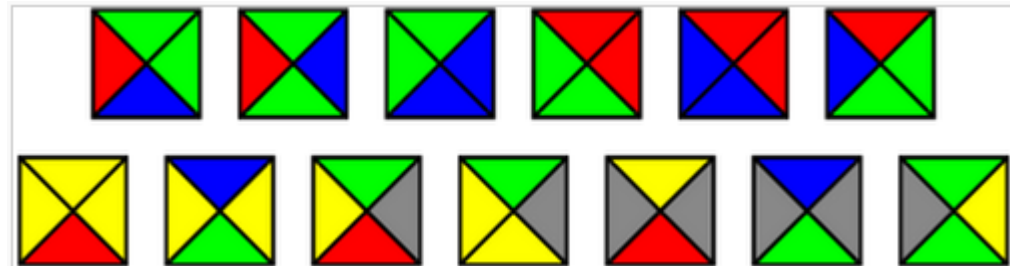


# All undecidability results are proven via reductions



$$\begin{array}{r}
 A1 = \\
 \begin{array}{r}
 1 \\
 3
 \end{array}
 \end{array}
 \quad
 \begin{array}{r}
 A2 = \\
 \begin{array}{r}
 -2 \\
 0
 \end{array}
 \end{array}
 \quad
 \begin{array}{r}
 A3 = \\
 \begin{array}{r}
 0 \\
 -1
 \end{array}
 \end{array}
 \quad
 \begin{array}{r}
 -1 \\
 0
 \end{array}
 \quad
 \begin{array}{r}
 1 \\
 0
 \end{array}
 \quad
 \begin{array}{r}
 2 \\
 -1
 \end{array}$$

$$x^3 + y^3 + z^3 = 33?$$



But what about the first undecidable problem?

# The halting problem

## ■ HALTING

■ **Input:** A file containing a computer program  $p$  and a file containing an input  $x$  to the computer program.

■ **Question:** Does  $p$  ever terminate (aka halt) when given input  $x$ ?

An instance of HALTING:

```
1  function gradient_descent(x)
2
3  %gradient descent with exact line search for minimizing a quadratic
4  %function.
5  Q=[8 0;0 17];
6  b=[136;154];
7  xvec=[];
8  while norm(Q*x-b,2)>10^-5
9      alpha=((Q*x-b)'*(Q*x-b))/((Q*x-b)'*Q*(Q*x-b));
10     x=x-alpha*(Q*x-b);
11     xvec=[xvec x];
12 end
```

→ Program  $p$

$x = [3; 63];$

# The halting problem

An instance of HALTING:

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12 end
```

→ Program  $p$

$x = [3; 63];$

- Both the program  $p$  and the input  $x$  can be represented with a finite number of bits.
- Can there be a program --- call it **terminates( $p,x$ )** --- that takes  $p$  and  $x$  as input and always outputs the correct yes/no answer to the question: does  $p$  halt on  $x$ ?
  - We'll show that the answer is no!
  - This will be a proof by contradiction.

# The halting problem is undecidable

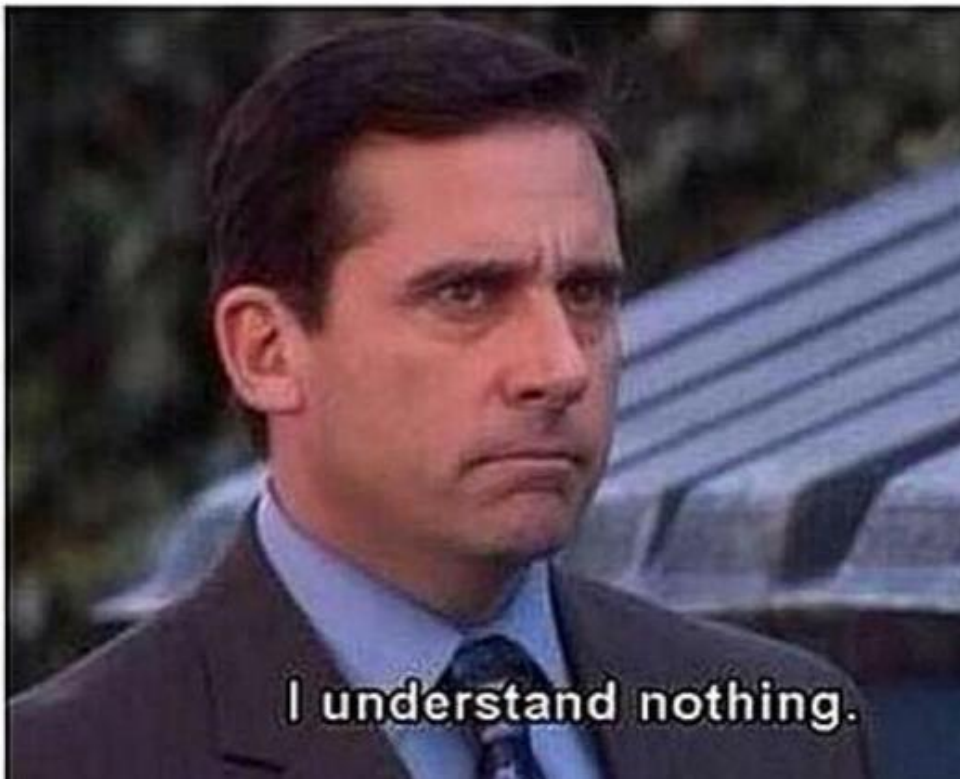
## Proof.

- Suppose there was such a program `terminates(p,x)`.
- We'll use it to create a new program `paradox(z)`:

```
function paradox(z)
1: if terminates(z,z)==1 goto line 1.
```

- The input  $z$  to `paradox` is a computer program.
- As a subroutine, `paradox` asks `terminates` to check whether a given computer program  $z$  halts when given itself as input. (This is perfectly legal as any program is just a finite number of bits.)
- Note that `paradox` halts on  $z$  if and only if  $z$  does not halt when given itself as input.
  - What happens if we run `paradox(paradox)` ?!
    - If `paradox` halts on itself, then `paradox` doesn't halt on itself.
    - If `paradox` doesn't halt on itself, then `paradox` halts on itself.
    - This is a contradiction  $\rightarrow$  `terminates` can't exist.

# Typical 1<sup>st</sup> time reaction to the proof of the halting problem



# The halting problem (1936)



**Alan Turing  
(1912-1954)**



# A simpler story to tell strangers at a bar...

(aka Russell's paradox)



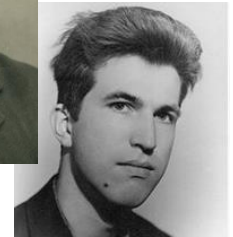
# The power of reductions (one last time)

A simple paradox/puzzle:



function `paradox(z)`  
1: if `terminates(z,z)` == 1 goto line 1.

(lots of nontrivial mathematics,  
including the formalization of the  
notion of an “algorithm”)



A fundamental  
algorithmic question:

## ▪ POLY INT

- **Input:** A polynomial  $p$  in  $n$  variables and degree  $d$ .
- **Question:** Does it have an integer root?

# A remarkable implication of this...

Take your favorite long-standing open problem in mathematics:

e.g.,

- Is there an odd perfect number? (an odd number whose proper divisors add up to itself?)
- Is every even integer  $>2$  the sum of two primes? (the Goldbach conjecture)

**In each case, you can explicitly write down a polynomial of degree 4 in 58 variables, such that if you could decide whether your polynomial has an integer root, you would have solved the open problem.**

## **Proof.**

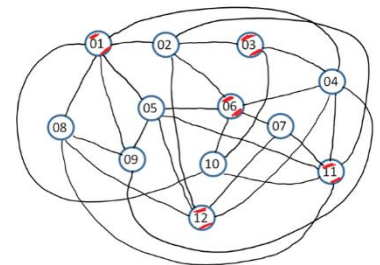
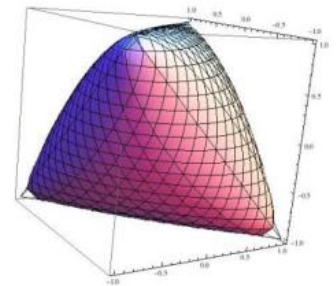
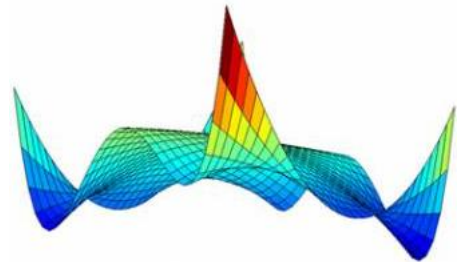
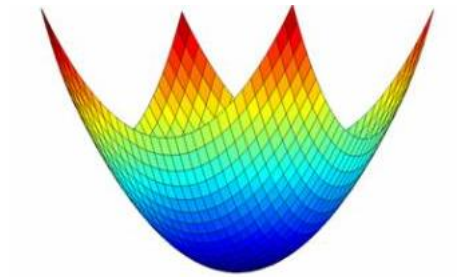
- 1) Write a code that looks for a counterexample.
- 2) Code does not halt if and only if the conjecture is true (one instance of the halting problem!)
- 3) Use the reduction to turn into an instance of POLY INT.

## A look back at ORF 363/COS 323



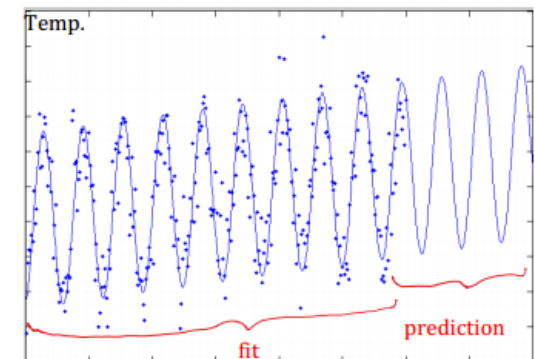
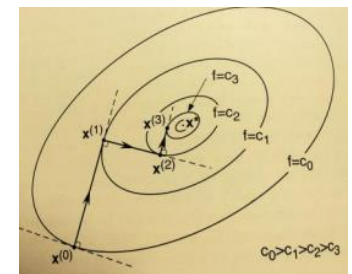
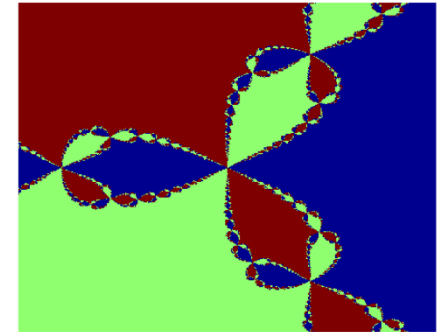
# Topics we covered in optimization

- Optimality conditions for unconstrained optimization
- Convex analysis
  - Convex sets and functions
  - Optimality conditions for constrained convex problems
  - Convexity detection and convexity-preserving rules
- Modeling a problem as a convex program
  - Solving it in CVX or CVXPY
- Algorithms for convex unconstrained optimization
- Algorithms for constrained linear optimization
- Semidefinite programming
- Convex relaxations for non-convex and combinatorial optimization
- Theory of NP-completeness
- Undecidability



# Topics we covered in numerical computing

- Least squares
  - Optimality conditions and normal equations
- Singular value decomposition
- Solving linear systems
- Iterative descent methods
- Root finding
  - Bisection, the secant method
  - The Newton method, Newton fractals
- Nonlinear least squares
  - The Gauss-Newton method
- Convergence analysis
  - Convergence rates of gradient descent and Newton
  - Condition number
- Approximation and fitting

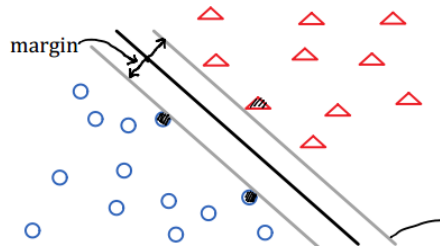


# Applications of these tools are ubiquitous...

Hey man,  
I'm tired of this homework for ORF 363. Let's go party tonight. We can always ask for an extension.

-J

Spam



## Support vector machines



Hillary vs. Bernie



Fairness in grading

k=130



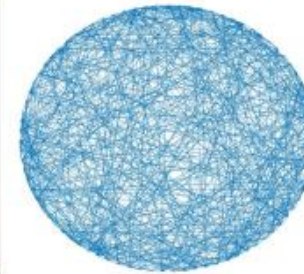
Original



Image compression



Optimal facility location

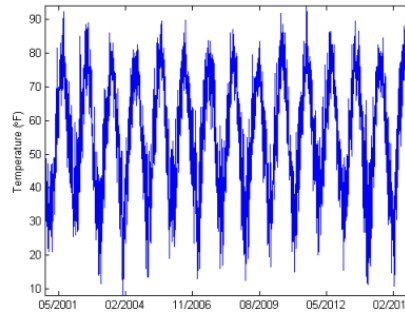


Event planning

## Scheduling

Doodle

	Mon 1	Tue 2	Wed 3	Thu 4	Fri 5	Sat 6	Sun 7
19 participants							
1 Woodrow Wilson							
2 F. Scott Fitzgerald	✓						
3 Richard Feynman							✓
4 Michelle Obama		✓					
5 Paul Volcker							✓
6 John Nash							
7 Terence Tao							✓
8 Ben Bernanke							
9 Paul Hogman					✓		
10 Andrew Wiles	✓						✓
11 Steve Forbes							✓
12 John Mizar	✓						
13 Kacivop Selma							✓
14 Albert Einstein							
15 George K. Miller							
16 Alan Turing							
17 Meg Whitman	✓						
18 Donald Rumsfeld							
19 Eugene O'Neill							✓



The Earth's orbit

Optimal control

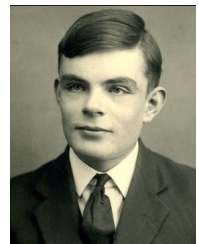
Minimum intensity radiation therapy

Bookmaking

Portfolio optimization

...

# We met lots of mathematicians!



Who is who?

And on what topic did they feature in this class?



# How to check if an optimization problem is easy?

- Check if it's convex!
- The functional form of convexity meant:
  - Objective a convex function (if you are minimizing)
  - Constraints: “Convex $\leq$ Concave”, “Affine $=0$ ”.
- If it is, then (most of the time) CVX can already solve it for you up to a reasonably large size.
- There are occasional exceptions:
- Nonconvex problems can be easy:
  - Singular value decomposition (best rank  $r$  approximation to a given matrix)
  - One can argue that there is “hidden convexity” (e.g., the dual is an SDP)
- Convex problems can be hard:
  - Optimizing over the set of nonnegative polynomials or copositive matrices
  - Not quite in functional form, but they can be made as such.
- Checking convexity may not be easy
- But the calculus of convex functions and convexity-preserving rules often suffice.

# How to check if an optimization problem is easy (formally)?

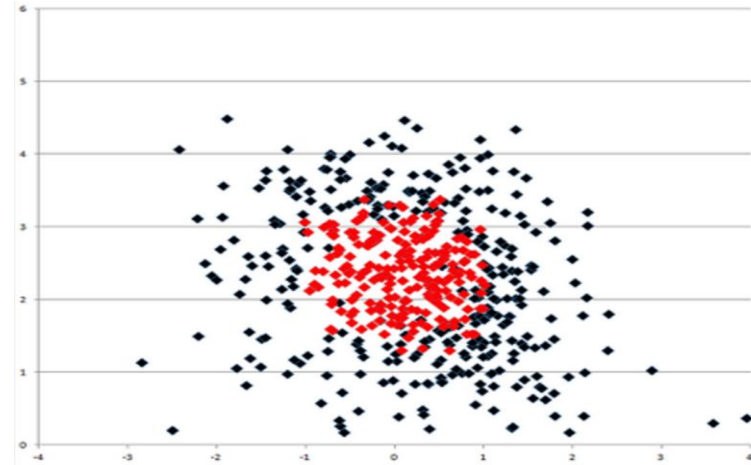
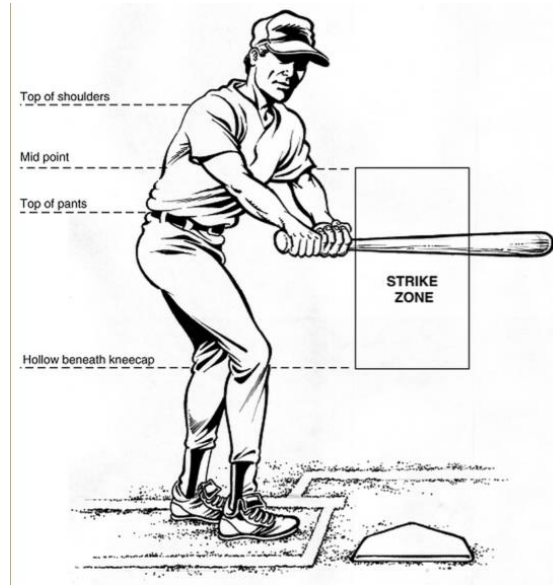
- Can you reduce it to a problem in P?
- If yes, then it's often easy
  - Unless the polynomial in the running time has high degree or large constants—often rare
- Can you show it's NP-hard?
- You must reduce a different NP-hard problem to it.
  - If you succeed, an exact efficient algorithm is out of the picture (unless  $P=NP$ )
- NP-hard problems still routinely solved in practice.
- Workarounds: heuristics, solving special cases exactly, convex relaxations.
- Convex optimization is often a powerful tool for approximating non-convex and NP-hard problems.
- We saw many examples in recent weeks; e.g., LP and SDP relaxations.

# Slide from lecture 1: Course objectives

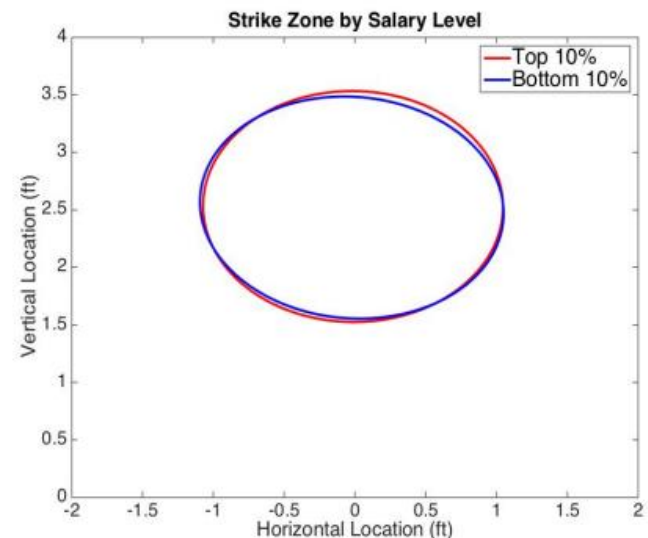
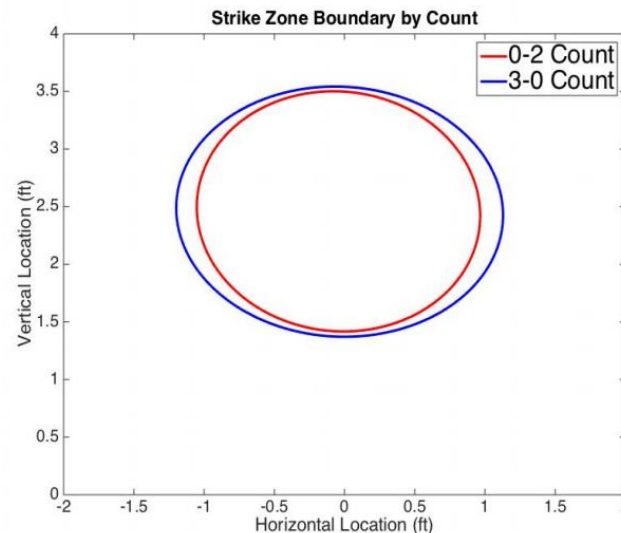
- The skills I hope you acquire:
  - Ability to view your own field through the lens of optimization and computation
    - To help you, we'll draw applications from operations research, statistics, economics, machine learning, engineering, ...
  - Learn about several topics in scientific computing
  - More mathematical maturity and ability for rigorous reasoning
    - There will be some proofs in lecture. Easier ones on homework.
  - Enhance your coding abilities
    - There will be a coding component on every homework and on the take-home final.
  - Ability to recognize hard and easy optimization problems
  - Ability to use optimization software
    - Understand the algorithms behind the software for some easier subclass of problems.

# An example: Jacob Eisenberg's work

- The “real strike zone” in major league baseball!



Robust minimum-volume ellipsoids obtained from *semidefinite programming*



# The final exam!

- Take-home. No collaboration allowed. Can only ask clarification questions as public questions on Ed Discussion. Can use all lecture notes, psets/previous exam solutions, and reference books of the course. Can only use “Google/ChatGPT” for problems with MATLAB/Python/software (although even that should not be needed).
- Exam will go out on **Saturday, December 14, 8AM EST.**
- Have to take it in **48 consecutive hours** (clock starts when you download).
- To be submitted on Gradescope as a single PDF file.
  - Keep an electronic copy of your exam.
- **Latest submission time is Thursday, December 19, 11:59PM EST** (University deadline).
- Don't forget that pset 8 is due Wednesday, December 11, at 1:30PM EST.

## What to study for the final?

- All the lecture notes.
- Psets 1-8, practice exams (we have posted several!).
- If you need extra reading, the last page of the notes points you to certain sections of the book for additional reading.
- Be comfortable with MATLAB/Python and CVX/CVXPY. Make sure your software is running.

# Some good news

- Undecidability from today's lecture won't be on the final.
- Theory of NP-completeness won't be on the final (but it is on HW 8).
- Lecture 10 (conjugate gradients), Lecture 12 (duality), and the "additional slides on applications of sum of squares optimization" are optional and not on the final.
- Six practice final exams (with solutions) are already posted.
- The TAs and I will hold office hours throughout reading period and up to the day of the day of the exam. Regular schedule (see syllabus, or slides of lecture 1).

- **In addition, we will have the following review sessions:**

Burak (pset 1&2) Friday Dec 6, 1:30-3:30 PM EST, Friend 008

George (pset 3&4) Monday Dec 9, 1:30-3:30 PM EST, Friend 008

Ben (pset 5&6) Tuesday Dec 10, 1:30-3:30 PM EST, Friend 008

Ben (psets 7&8) Wednesday Dec 11, 1:30-3:30 PM EST, Friend 008

Yixuan (past finals) Thursday Dec 12, 1:30-4:30 PM EST, Friend 008

**AAA (comprehensive review)** Friday Dec 13, 6-9 PM EST, Friend 008

**There will be pizza!**



# Last but not least...

- It was great having you all in my class.
- Thank you for making this an enjoyable and rewarding semester!
  
- Go make optimal decisions in your lives! (Make sure you optimize for the right objective functions!)
- And keep in touch!

AAA.

December 5, 2024

# Notes & References

## ■ Notes:

- Chapter 8 of [DPV08] mentions undecidability and the halting problem. Chapter 9 of [DPV08] is optional but a fun read.

## ■ References:

- [Wo11] M.M. Wolf. Lecture notes on undecidability, 2011.
- [Po08] B. Poonen. Undecidability in number theory, *Notices of the American Mathematical Society*, 2008.
- [DPV08] S. Dasgupta, C. Papadimitriou, and U. Vazirani. Algorithms. McGraw Hill, 2008.