

# Z - Transform

D.T. signal:

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$z$  is complex  
May converge for some  $z$ .

Same as Laplace transform:  $z = e^s$

For Laplace,  $\text{Re}\{s\}$  determined convergence. i.e.  $s = \underline{\sigma} + i2\pi f$

$$z = e^s = \underbrace{e^{\sigma}} e^{i2\pi f}$$

$$|z| = e^{\sigma}$$

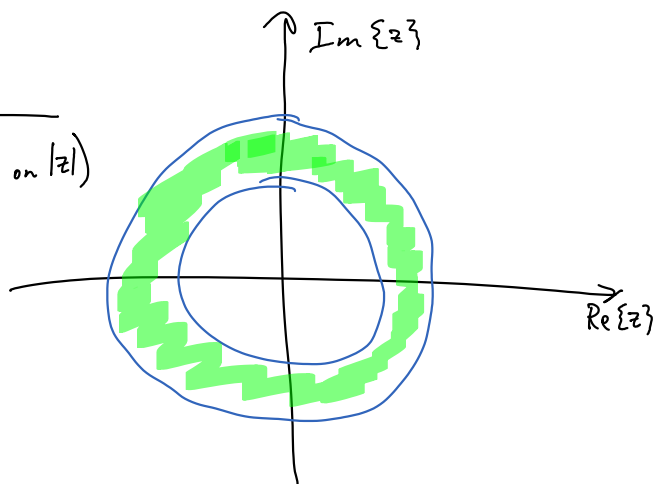
Let  $z = a e^{i2\pi f}$

$$X_z(a e^{i2\pi f}) = \sum_{n=-\infty}^{\infty} x[n] a^n e^{-i2\pi f n} = \mathcal{F}(x[n] a^{-n})$$

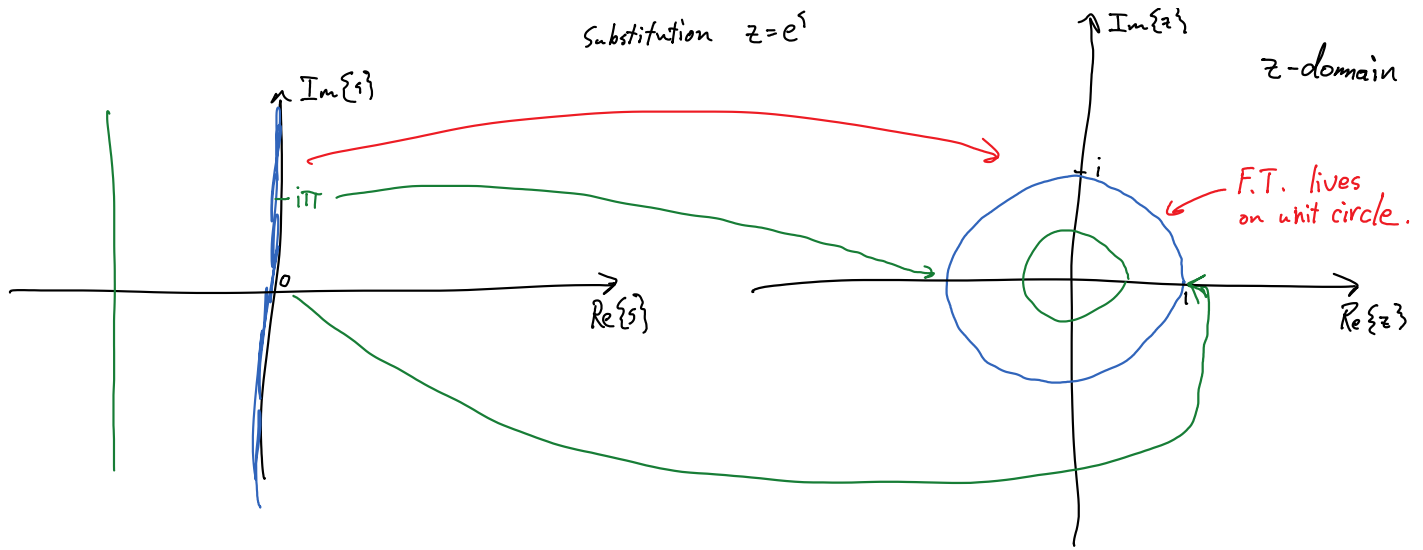
$$X_z(e^{i2\pi f}) = X_F(f)$$

ROC is a ring:

(i.e. convergence depends on  $|z|$ )



The  $s$ -plane has been wrapped in circles by  $z = e^s$ .



ROC : Rings defined by  $|z| \in (a, b)$

Right-sided:

ROC has no outward boundary.

Left-sided:

ROC has no inner boundary.  
(may have pole at  $z=0$ .)

Finite-duration:

ROC is the whole space (may have pole at  $z=0$ )

Stability:

$\Rightarrow$  Unit circle is in the ROC.

$\Leftarrow$  Unit circle is in interior of the ROC

Why substitute  $z = e^s$  for D.T.?

- 1.) Emphasizes periodicity
- 2.) Rational z-transforms

F.T. Notation from book: C.T.F.T.  $X(j\omega)$

D.T.F.T.  $X(e^{j2\pi f})$

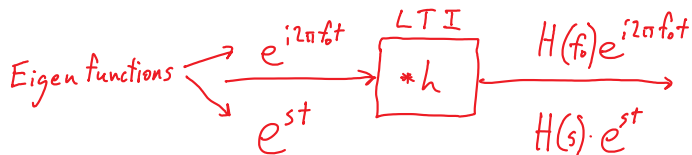
This notation comes from substituting into the Laplace and Z transform.

Properties of Laplace and Z-transforms:

Linearity:  $a x(t) + b y(t) \xrightarrow{\mathcal{L}} a X(s) + b Y(s)$

Convolution:  $x(t) * y(t) \xrightarrow{\mathcal{L}} X(s) \cdot Y(s)$

ROC is intersection.



Derivative Property:  $\frac{d}{dt} x(t) \xrightarrow{\mathcal{L}} s X(s)$

Integral Property:  $\int_{-\infty}^t x(\tau) d\tau \xrightarrow{\mathcal{L}} \frac{1}{s} X(s)$

No change to ROC.

not rational

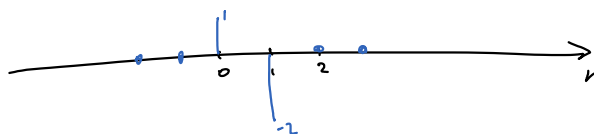
ROC:  $\text{Re}\{s\} > 0$  intersect with ROC of  $X(s)$ .

C.T. Time-shift Property:  $x(t-T) \xrightarrow{\mathcal{L}} e^{-Ts} X(s)$

D.T. Time-shift Property:  $x[n-N] \xrightarrow{\mathcal{Z}} z^{-N} X(z)$

rational

Example:  $x[n] = \delta[n] - 2\delta[n-1]$



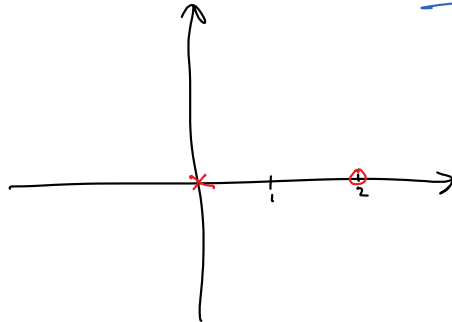
$$X(z) = \sum_{n=-\infty}^{\infty} (\delta[n] - 2\delta[n-1]) z^{-n}$$

$$= 1 - 2z^{-1}$$

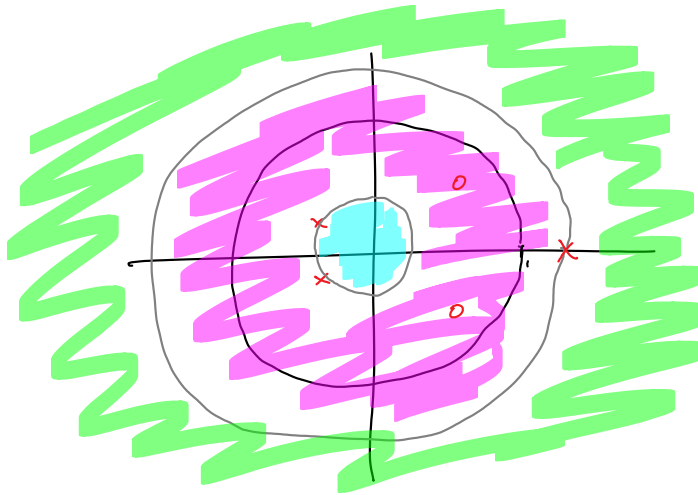
Is this rational?

Yes.

$$\frac{z-2}{z}$$



For rational z-transform: Poles are at the boundaries of ROC.



- left-sided.  
Not stable.
- Two-sided  
stable.
- right-sided  
not stable.  
causal.

What about causality?

For rational z-transform

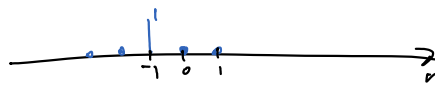
Right-sided  $\Rightarrow$  causal if and only if  $\# \text{zeros} \leq \# \text{poles}$ .

(Note: For rational Laplace transforms, right-sided  $\Leftrightarrow$  causal, unconditionally.)

Example:

$$x[n] = \delta[n+1]$$

non-causal



right-side

$$X(z) = z$$

$$\# \text{ zeros} = 1$$

$$\# \text{ poles} = 0$$

Justification:

Assume  $x[n]$  is non-causal

$$\sum_{n=-\infty}^{\infty} x[n] z^{-n} = x[-K] z^K + \dots$$

For some positive  $K$ .

↑  
order of numerator > order of denominator