

Problem Set #3  
Not to be handed in.

1. Use the Fourier series synthesis equation to calculate the time-domain representation of the following signals:
  - (a) (Continuous-time) The period of  $x(t)$  is  $T = 0.5$  and  $a_k = (1/2)^{|k|}$ . (Hint: Use the geometric series.) Also, express  $x(t)$  as an infinite sum of cosines.
  - (b) (Discrete-time) The period of  $x[n]$  is eight. However,  $a_k$  has period four, and the first four coefficients are  $a_0 = 0$ ,  $a_1 = 0$ ,  $a_2 = -1$ , and  $a_3 = 0$ . Is  $x[n]$  real?

2. *Continuous-time convolution.* Recall the continuous-time functions  $u(t)$  and  $\text{rect}(t)$  and define the function  $x(t)$  by

$$x(t) = \begin{cases} 2 & \text{if } 0 \leq t < 1 \\ -1 & \text{if } 1 \leq t < 2 \\ 0 & \text{otherwise} \end{cases}$$

Sketch each of the following convolved signals:

- (a)  $u(t) * u(t)$
  - (b)  $x(t) * u(t)$
  - (c)  $x(t) * \text{rect}(t)$
3. *Averaging system.* Suppose  $x[n]$  denotes the closing price of a stock on day  $n$ . To smooth out fluctuations, a tool often used by technical analysts is the 30-day moving average of the stock price. Let  $y[n]$  denote this 30-day moving average, where the average at time  $n$  uses the closing price on day  $n$  together with the previous 29 days.
  - (a) Write an expression for  $y[n]$  in terms of  $x[\cdot]$ .
  - (b)  $y[n]$  can be thought of as the output of an LTI system when the input is  $x[n]$ . What is the impulse response of this system?
  - (c) How does the impulse response change if instead of the “lagging” average above we use  $x[n]$  together with 15 days in the past and 14 days in the future?
  - (d) What is a practical problem of using the average of part (c)?

4. *Fourier Transform Properties.* In this exercise, you will derive Fourier properties as we did in class. Since these properties are all easily searchable, you must show work to get credit for this exercise. These properties are important for future use, and they will also help illuminate the similarities and differences of the different versions of the Fourier transform (i.e. CTFT, CTFS, DTFT, DTFS).

(a) Even and Odd signals

- i. Suppose  $x(t)$  is an even signal. Show that the CTFT  $X(f)$  is even. (Hint: Use the analysis equation and  $u$ -substitution.)
- ii. Suppose  $x(t)$  is an odd signal. Show that the CTFT  $X(f)$  is odd.
- iii. Suppose  $x(t)$  is even and real. Show that the CTFT  $X(f)$  is even and real. (Hint: Use  $X(f) + X(-f)$  with what you know about the transform of even signals, then write them in integral form and combine.)
- iv. Suppose  $x(t)$  is odd and real. Show that the CTFT is odd and *imaginary*.

By combining the previous properties with linearity we see that an even and imaginary signal  $x(t)$  transforms to an even and imaginary  $X(f)$ , and an odd and imaginary signal  $x(t)$  transforms to an odd and real  $X(f)$ . These properties are all true for the other variants of the Fourier transform as well (i.e. CTFS, DTFT, DTFS).

- v. Use the even/odd decomposition of a signal to show that if  $x(t)$  is real then  $X(f)$  is conjugate symmetric, which means that  $X(f) = X^*(-f)$ . (Another straightforward proof just involves taking the conjugate of the analysis equation.) What does this property imply about the magnitude and phase of the Fourier transform of a real signal?

(b) Derivative

The derivative property of the CTFT derived in lecture is

$$\frac{d}{dt}x(t) \xrightarrow{\mathcal{F}} i2\pi f X(f).$$

This property also holds for the CTFS. As an exercise, derive this property (both period and coefficients). That is, assume that  $x(t)$  has period  $T$  and corresponding coefficients  $\{a_k\}$ . What is the Fourier series of  $\frac{d}{dt}x(t)$ ?

(c) Difference function

Differentiation is not an operation that works in discrete-time, but we can define a similar difference operation  $x_\Delta[n]$  as

$$x_\Delta[n] = x[n] - x[n-1].$$

What is the DTFT of  $x_\Delta[n]$  in terms of  $X(f)$ ? How is this similar to the derivative property of the CTFT?

(d) Duality

By inspection of the CTFT equations (analysis and synthesis), we see that Fourier transform pairs can be reversed. That is, if the CTFT of  $x(t)$  is  $X(f)$ , then the Fourier transform of  $X(t)$  is  $x(-f)$ . Verify this by plugging  $x(-f)$  into the inverse CTFT (synthesis equation).

This same duality holds in other forms of the Fourier transform. The other easy case is the DTFS. Here we have that if  $x[n]$  has period  $N$ , and the DTFS coefficients are  $\{a_k\}$  (also with period  $N$ ), then the dual relationship is that the signal  $\tilde{x}[n] = a_n$  has Fourier series coefficients  $\{x[-k]/N\}$ .

What is the dual relationship for the other two cases—CTFS and DTFT? (Hint: Use the synthesis (forward) equation of one with the analysis (inverse) equation for the other.)

5. *Aliasing.*

Give another expression for the discrete-time signal  $\sin[n]$  in terms of another real-valued sinusoidal function with frequency less than one. Your steps will probably involve first using Euler's identity, then changing both terms using the aliasing property, and finally putting it back together with Euler's identity. Notice that we left  $2\pi$  out of the argument of  $\sin$  on purpose. Keep in mind that the frequency of the above sinusoid is not one.

6. *Delta functions.*

- (a) Sketch  $-\delta(t - 2) + 3\delta(3t)$ .
- (b) Sketch  $4\delta[n - 4] - 2\delta[n + 1]$ .
- (c) Evaluate  $\int_{-2\pi}^0 \cos(t)[\delta(t - \pi) + \delta(t + \pi)]dt$ . (Note the limits of the integral!)
- (d) Evaluate  $\int_{-\infty}^{\infty} e^t \delta(t - u)dt$ .
- (e) Consider a discrete-time function with  $x[-1] = 2$ ,  $x[2] = 5$ ,  $x[3] = 3$ , and  $x[n] = 0$  for all other  $n$ . Write an expression for  $x[n]$  in terms of the Kronecker delta function.

7. *Convolution and the Fourier transform.* What is the Fourier transform of  $\text{rect}(t) * \text{sinc}(t)$ ? The convolution integral will *not* be the easiest way to do this.

8. *System response.* A continuous-time LTI system has impulse response  $h(t)$  with Fourier transform  $H(f)$ . What is the output of the system when the input is  $\sin(t)$ ?