Lecture 6 ELE 301: Signals and Systems

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Outline

• LTI System Response

Filtering

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Transfer Function

• Response to LTI system h.

Continuous time:
$$e^{st} \longrightarrow^{h} H_{c}(s)e^{st}$$
,
Discrete time: $z^{n} \longrightarrow^{h} H_{d}(z)z^{n}$.

• We are interested in the cases $s = i2\pi f$ and $z = e^{i2\pi f}$.

Continuous time:
$$y(t) = \sum_{k=-\infty}^{\infty} a_k H_c (i2\pi f_0 k) e^{i2\pi f_0 kt}$$
,
Discrete time: $y[n] = \sum_{k=-\infty}^{\infty} a_k H_d (e^{i2\pi f_0 k}) e^{i2\pi f_0 kn}$.

where a_k are the Fourier Series coefficients of the input with period $\mathcal{T}=1/f_0.$

Intuitive Visualization



Note: Plots aren't technically accurate because complex numbers are not one-dimensional.

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Intuitive Visualization



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Filtering Example

$$h(t) = e^{-t}u(t),$$

 $H(i2\pi f) = ?.$

First-order low-pass filter



Filtering example - running average

$$h[n] = \frac{1}{3}(\delta[n] + \delta[n-1] + \delta[n-2]),$$

$$H(e^{i2\pi f}) = ?.$$

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Running average

$$H(i2\pi f) = \frac{1}{3} \left(1 + e^{-i2\pi f} + e^{-i4\pi f} \right).$$



Filtering example - Differentiator

What is the impulse response of a differentiator?

$$h(t) = ?$$

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Unit Doublet

• Another invented pseudo-function

· Conceptually the derivative of the Dirac delta function

Properties

$$\blacktriangleright \ \delta' * f = f'$$

•
$$f(t)\delta'(t-t_0) = -f'(t_0)\delta(t-t_0)$$

•
$$\delta'(-t) = -\delta'(t)$$

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Differentiator

$$h(t) = \delta'(t),$$

$$H(i2\pi f) = ?.$$

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High-pass filter (Differentiator)

 $H(i2\pi f) = i2\pi f.$



Filtering example - discrete difference

$$h[n] = \frac{1}{2}(\delta[n] - \delta[n-1]),$$

$$H(e^{i2\pi f}) = ?.$$

Discrete Difference

$$H(i2\pi f) = i e^{-i\pi f} \sin(\pi f).$$



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