Gaussian Secure Source Coding and Wyner's Common Information

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This Mork

- o Optimize a rate region
- Show that a Gaussian auxiliary variable is optimal for Gaussian setting

This Work

- ø X, Y, U jointly Gaussian (given)
- ø V is auxiliary: X-(U,V)-Y

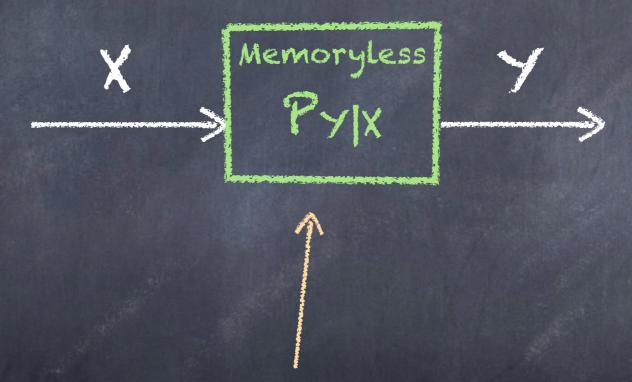
CONCEXE

o Synthetic Noise



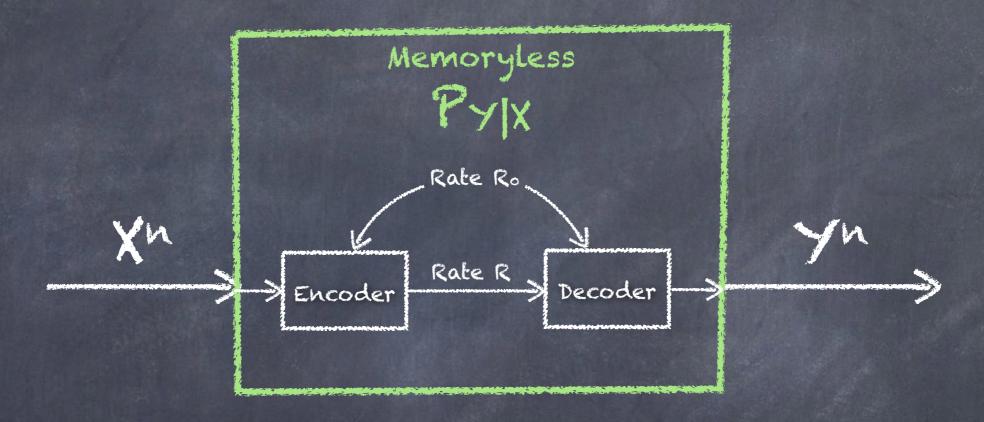
CONCEXE

o Synthetic Noise



What resources are required to produce this?

Synchette Moise

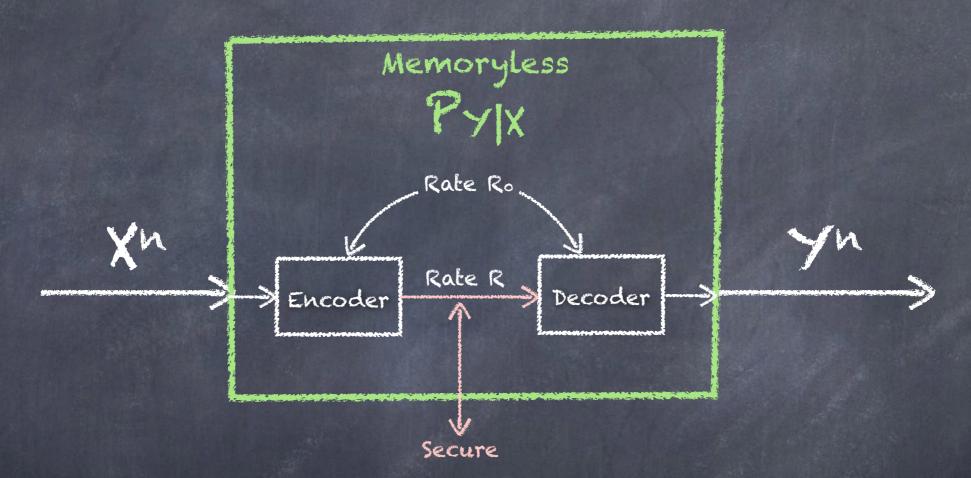


Resource Requirements: Choose V s.t. X-V-Y

 $R \ge I(X,V)$ $R + R_0 \ge I(X,Y,V)$

[Cuff, "Distributed Channel Synthesis," '13] [Bennett, et. al., "Reverse Shannon Theorem," '14]

Synthetic Noise

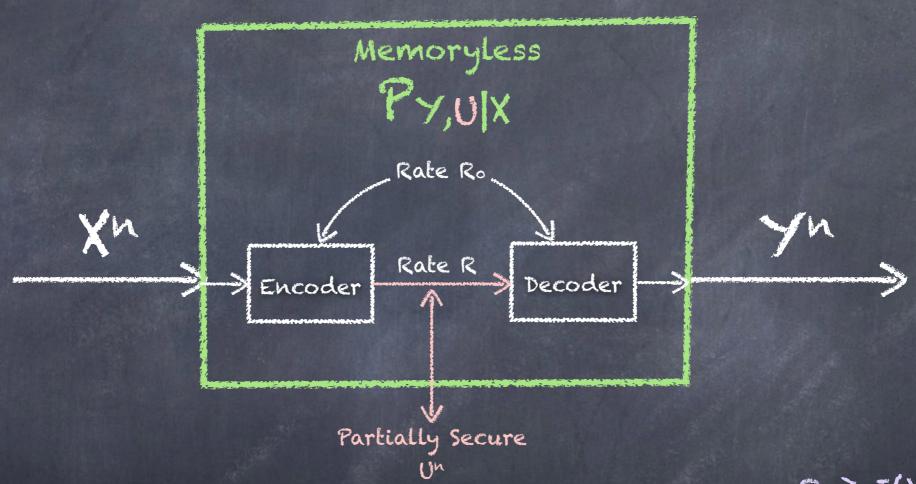


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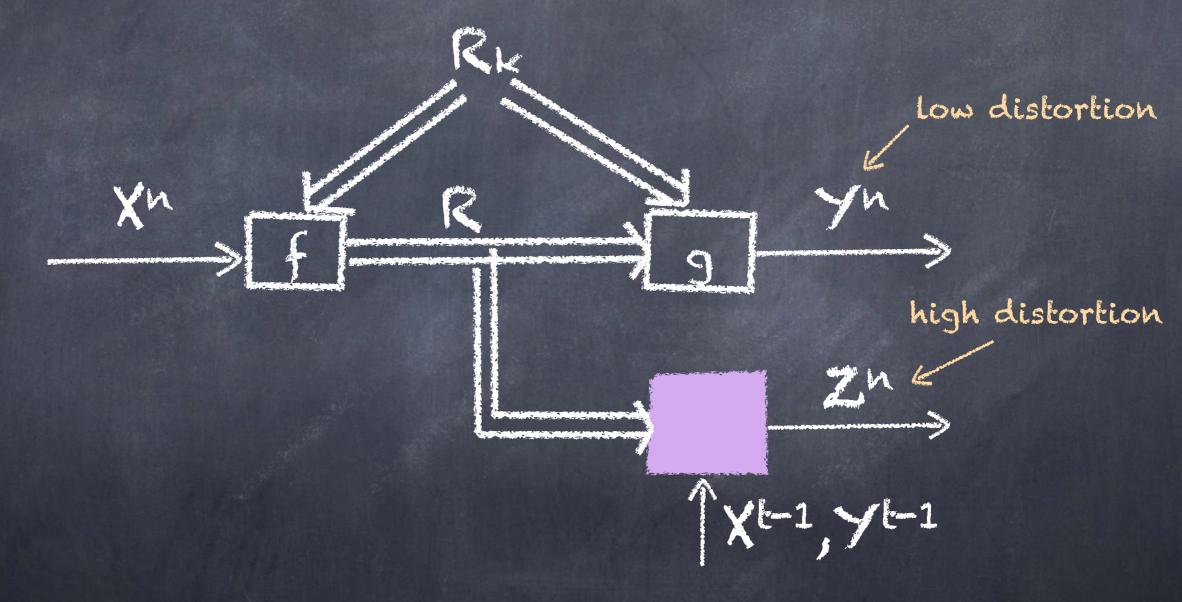
Synthetic Noise



Resource Requirements: Choose V s.t. X-(U,V)-Y $R \ge I(X;U,V)$

[Schieler-Cuff, "Rate-Distortion Theory for Secrecy Systems," '14]

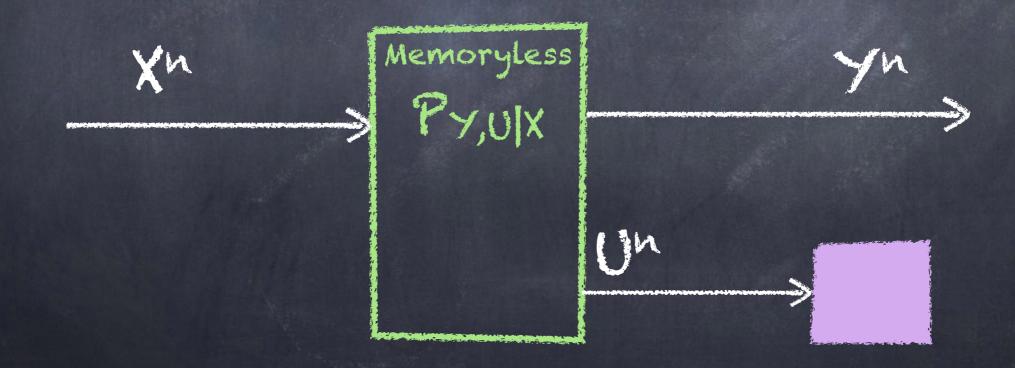
Secure Source Coding



[Schieler-Cuff, "Rate-Distortion Theory for Secrecy Systems," '14]

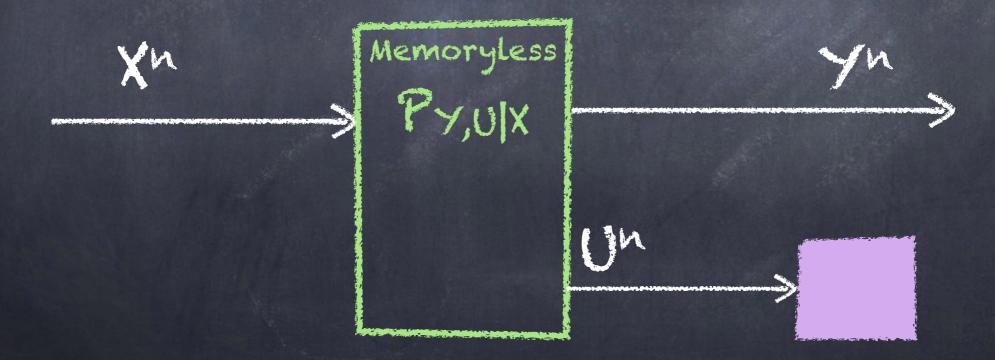
Synthetic Broadcast Channel

Optimal Communication for secure source coding

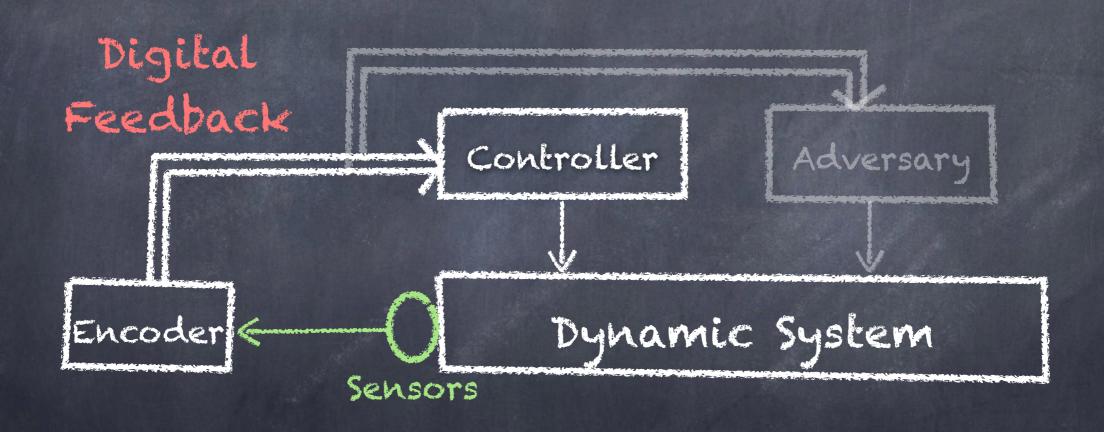


Properties

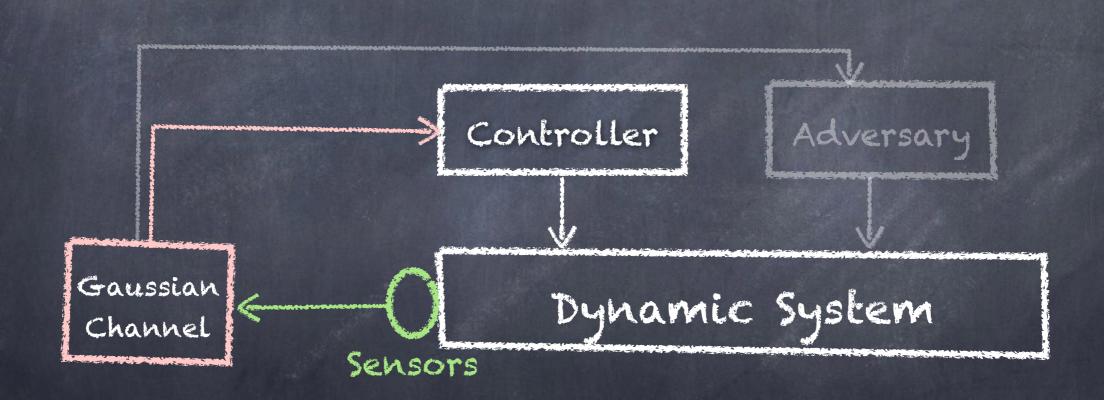
- o Un is statistically typical
- « Xn, Yn|Un is indistinguishable from memoryless channel



Gaussian Case -Control Application



Gaussian Case -Control Application



Rate-distortion theory (Gaussian channel): same fundamental limit

[Tatikonda-Mitter-Sahai, "Data-Rate Theorem," '98]

Optimization Problem

- ø X,Y,U jointly Gaussian (given)
- V is auxiliary: X-(U,V)-Y
 Σi 1/2 log (1/(1-ρi²))

$$R \ge I(X;U,V) = I(X;U) + I(X;V|U)$$
 $R_0 \ge I(X,Y;V|U)$

X,YU - Gaussian with covariance Ex,yo

Simpler Optimization

- @ X, Y jointly Gaussian (Σx, y|υ)
- o V is auxiliary: X-V-Y

$$Ro \ge I(X,Y,V)$$

Without loss of generality:

$$\Sigma x = I$$
 $\Sigma y = I$
 Σxy is diagonal

Process X and Y (invertibly): Whiten: $\Sigma x^{-1/2} X$ SVD of P = $\Sigma x^{-1/2} \Sigma x \Sigma y^{-1/2}$

Collection of Independent Pairs

- « Xk, Yk jointly Gaussian scalars
 - o mutually independent pairs
- o V is auxiliary: XK-V-YK

Use an independent Vk for each pair of scalars

Collection of Independent Pairs

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$$S = I(X_K, \lambda_K, \lambda_K) > \sum I(X_K, \lambda_K, \lambda_K)$$

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Use an independent Vk for each pair of scalars

Scalar Optimization

- o X,Y jointly Gaussian scalars
- o V is auxiliary: X-V-Y

Claim: Optimized by jointly Gaussian V

Myner's Common Information

- ø X,7 jointly Gaussian scalars
- o V is auxiliary: X-V-Y

 $Ro \ge I(X,Y;V)$

Claim: Optimized by jointly Gaussian V

Vector Gaussian Common Information

$$C(X;Y) = I(X;Y) + \sum log(1+pi)$$

where ρ_i are singular values of $\Sigma x^{-1/2} \Sigma xy \Sigma y^{-1/2}$

Scalar Optimization

- o X,Y jointly Gaussian scalars
- o V is auxiliary: X-V-Y

Claim: Optimized by jointly Gaussian V

Sais Proof

- o Consider the weighted combination:
 - $= \lambda I(X;V) + I(X,Y;V)$ $= (\lambda+1)I(X;V) + I(Y;V) I(X;Y)$
- o Consider optimal estimation error
 - $D_{x} = 1 E[E[X|V]^{2}]$
 - o $D_y = 1 E[E[Y|V]^2]$

Sais Proof

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Upper bound on distortion

- o Claim: $\rho^2 \leq (1-D_x)(1-D_y)$
- @ Proof (Cauchy-Schwarz):

```
\rho^{2} = E[XY]^{2} = E[E[XY|V]]^{2}
= E[E[X|V]E[Y|V]]^{2} \leftarrow Markovity
\leq E[E[X|V]^{2}] E[E[Y|V]^{2}]
= (1-D_{x})(1-D_{y})
```

Two Bounds

- Rate-distortion function for quadratic Gaussian
- o Cauchy-Schwartz
 - o Orthogonality Principle

Two Bounds

- Rate-distortion function for quadratic Gaussian (maximum entropy)
- o Cauchy-Schwartz
 - o Orthogonality Principle

Other Proof

o Jun Chen:

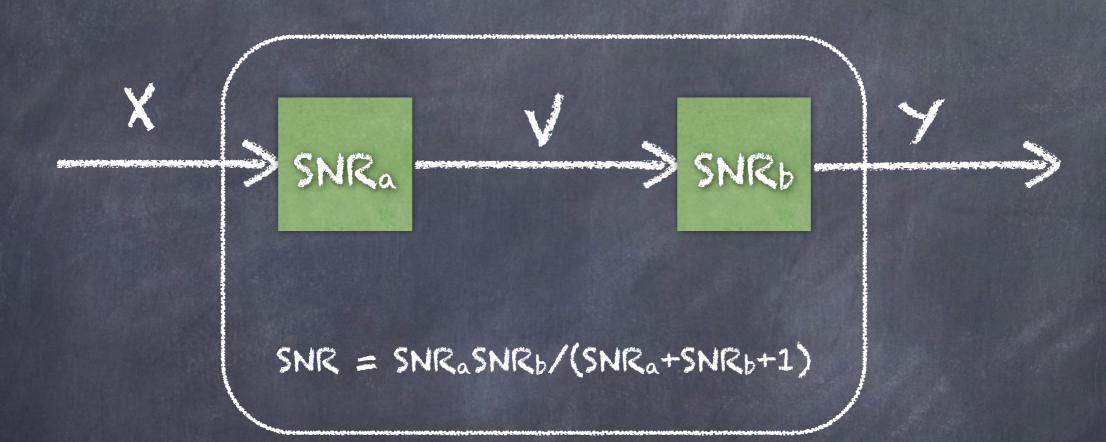
Consider the four variables: X, E[X|V], E[Y|V], Y

Construct Gaussian with same covariance: X, Va, Vb, Y

Properties Used:

- Maximum entropy
- Orthogonality Principle: X-(Va,Vb)-Y

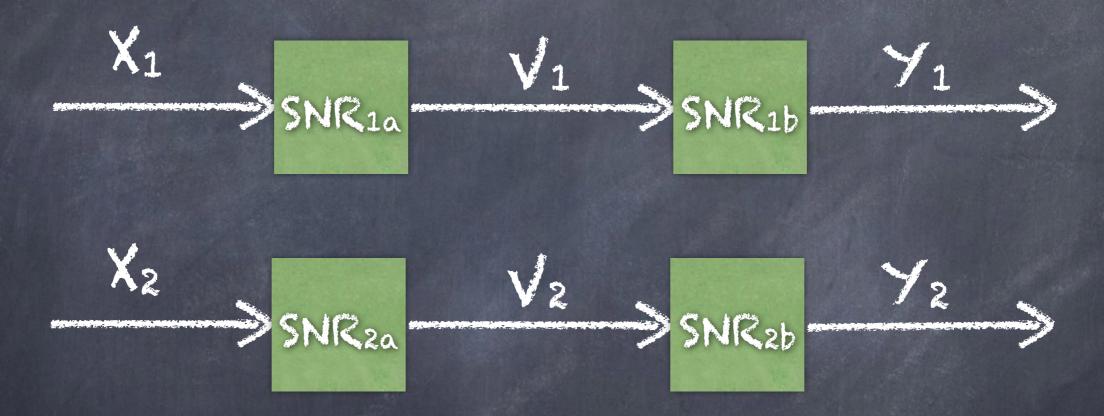
Tradeoff



$$I(X,V) = C(SNR_a)$$

$$I(X,Y,V) = C(SNR_a) + C(SNR/(SNR_a-SNR))$$

Vector Craussian



Optimized by SNRia/SNRib = constant