Differential Privacy as a Mutual Information Constraint Paul Cuff and Langing Yu



Database Privacy

- o Let X1, X2, ..., Xn be entries in a database
 - e E.g. Xi is personal information about person i
- o Let Y be the response to a query
- The job of the information provider is to answer queries and protect individual privacy

 Design P(y|x)

Differential Privacy

- Ø ε-DP:
 - e Let x and x' differ in only one entry (i.e. $x_i=x_i'$ for all but one i)
 - p(y|x) ≤ e[®] p(y|x')
- · Why x and x' differ in only one spot?
 - o Convince someone to put their data in your database
- · Why multiplicative constraint?
 - o Posterior update is small

A COMMON

o Add Laplacean noise

Weaker DP

- o (ε,δ) -DP:
 - e Let x and x' differ in only one entry
 - \circ $P(Y \in A | x) \leq e^{\epsilon} P(Y \in A | x') + \delta$
- Additive Gaussian noise often
 provides privacy

Multual Information Differential Privacy

E-MI-DP:

 $\max_{i,P_{X^n}} I(X_i;Y|X^{i-1},X_{i+1}^n) < \epsilon$

Claim

$$\varepsilon$$
-DP > MI-DP > (ε,δ) -DP

Furthermore, if input or output alphabet is finite,

$$MI-DP = (\epsilon, \delta)-DP$$

Privacy Ordering

 α -DP > β-DP if for all β>0 there exists α such that α -DP ⇒ β-DP.

Subaddilivity of DP

- o Multiple queries:
 - o If k queries Yq1, Yq2, ..., Yqk each have differential privacy s and are conditionally independent, the combined they have ks privacy.

Simple MI-DP Proof:

$$I(X; Y_1, Y_2) = I(X; Y_1) + I(X; Y_2 | Y_1)$$

 $\leq I(X; Y_1) + I(X; Y_2)$

For clarity, conditioned database variables are omitted.

Common complaint

- Differentially privacy doesn't not mean that you can't learn about Xi.
 - Consider a database with correlated entries.

Simple MI-DP Explanation:

$$I(X_i;Y) \leq I(X_i;Y|X^{i-1},X_{i+1}^n)$$

Precise Bounds

(e,8) CLOSENESS

$$P \stackrel{(\epsilon,\delta)}{pprox} Q$$

$$P(A) \le e^{\epsilon} Q(A) + \delta, \quad \forall A \in \mathcal{F},$$

 $Q(A) \le e^{\epsilon} P(A) + \delta, \quad \forall A \in \mathcal{F}.$

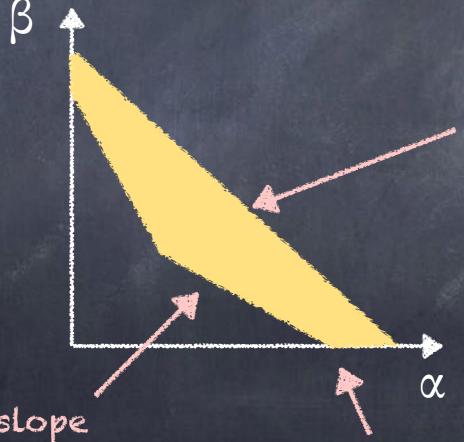
Special Cases

$$P \stackrel{(\epsilon,0)}{\approx} Q \iff \left| \ln \frac{dP}{dQ}(a) \right| \le \epsilon \quad \forall a \in \Omega.$$

$$P \stackrel{(0,\delta)}{\approx} Q \iff \|P - Q\|_{TV} \le \delta.$$

Relation to Detection Theory





Optimal tradeoff within this region

e determines slope

8 determines intercept

TLOMESE (E,8) CONVETSION

$$P \stackrel{(\epsilon,\delta)}{pprox} Q \implies P \stackrel{(\epsilon',\delta')}{pprox} Q.$$

for

$$\epsilon' \le \epsilon$$

$$\delta' = 1 - \frac{\left(e^{\epsilon'} + 1\right)(1 - \delta)}{e^{\epsilon} + 1}$$

Simple Claim

$$P \stackrel{(\epsilon,0)}{\approx} Q \implies \begin{array}{c} D(P||Q) \leq \epsilon \text{ nats,} \\ D(Q||P) \leq \epsilon \text{ nats.} \end{array}$$

Tightest Claim

$$P \overset{(\epsilon,0)}{\approx} Q \implies D(P||Q) \le \epsilon \frac{(e^{\epsilon} - 1)(1 - e^{-\epsilon})}{(e^{\epsilon} - 1) + (1 - e^{-\epsilon})} \text{ nats,}$$

$$D(Q||P) \le \epsilon \frac{(e^{\epsilon} - 1)(1 - e^{-\epsilon})}{(e^{\epsilon} - 1) + (1 - e^{-\epsilon})} \text{ nats.}$$

PINSKET

$$D(P||Q) \le \epsilon \text{ nats } \implies P \stackrel{\left(0,\sqrt{\epsilon/2}\right)}{pprox} Q.$$

Relative entropy to Mutual Information

If

$$D\left(P_{Y|X=x_1} \| P_{Y|X=x_2}\right) \le \epsilon \quad \forall x_1, x_2 \in \mathcal{X}$$

then

$$I(X;Y) \le \epsilon$$

Hint: Radius of information ball

Multual Information to Total Variation

$$\max_{P_X} I(X;Y) \le \epsilon \implies \frac{\|P_{Y|X=x_1} - P_{Y|X=x_2}\|_{TV}}{\forall x_1, x_2 \in \mathcal{X}} \le \delta'$$

$$\delta' = 1 - 2h^{-1}(\ln 2 - \epsilon)$$

$$\leq \sqrt{2\epsilon}$$

Tightest bound, achieved with binary channel

Finite Alphabet

$$\begin{aligned} \|P_{Y|X=x_1} - P_{Y|X=x_2}\|_{TV} &\leq \delta \\ \forall x_1, x_2 \in \mathcal{X} \end{aligned} \Longrightarrow I(X;Y) \leq \epsilon'$$

$$\epsilon' = 2h(\delta) + 2\delta \ln \left(\min \left\{ |\mathcal{Y}|, \max_{i} |\mathcal{X}_{i}| + 1 \right\} \right)$$

harder step

Continuity of entropy

Continuity of conditional entropy

inspired by Alicki and Fannes, 2004

Observation

$$\max_{P_{X^n}} I(X_i; Y | X^{i-1}, X_{i+1}^n) = \max_{\prod_{t=1}^n P_{X_t}} I(X_i; Y) \quad \forall i$$

Either could be used for definition of MI-DP