

Opportunistic Communications in an Orthogonal Multiaccess Relay Channel

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Abstract—The problem of resource allocation is studied for a two-user fading *orthogonal* multiaccess relay channel (MARC) where both users (sources) communicate with a destination in the presence of a relay. A half-duplex relay is considered that transmits on a channel orthogonal to that used by the sources. The instantaneous fading state between every transmit-receive pair in this network is assumed to be known at both the transmitter and receiver. Under an average power constraint at each source and the relay, the sum-rate for the achievable strategy of decode-and-forward (DF) is maximized over all power allocations (policies) at the sources and relay. It is shown that the sum-rate maximizing policy exploits the multiuser fading diversity to reveal the optimality of *opportunistic* channel use by each user. A geometric interpretation of the optimal power policy is also presented.

I. INTRODUCTION

The multiaccess relay channel (MARC) is a network in which several users (source nodes) communicate with a single destination in the presence of a relay [1]. The MARC is a model for relay-based cooperation in a multiuser network where the users have limited power and processing capabilities or need tangible incentives to cooperate. We model a MARC with a half-duplex relay as an *orthogonal* MARC where the relay transmits on a channel orthogonal to that used by the sources (see [2], [3]). The coding strategies developed for the relay channel [4] extend readily to the MARC [3]. For example, the strategy of [4, Theorem 1], now often called *decode-and-forward* (DF), has a relay that decodes user messages before forwarding them to the destination [5], [6]. Similarly, the strategy in [4, Theorem 6], now often called *compress-and-forward* (CF), has the relay quantize its output symbols and transmit the resulting quantized bits to the destination [3].

We study the problem of resource allocation in a two-user ergodic fading orthogonal MARC employing DF under the assumption that the instantaneous fading state between each transmit-receive pair in this network is known at both the transmitter and receiver. Resource allocation for a single-user ergodic fading orthogonal relay channel employing DF and subject to an average power constraint at the source and

relay is studied in [2] (see also [7]). The authors formulate the problem as a *max-min* optimization. They draw parallels with the classic minimax optimization in hypothesis testing to show that the optimal resource allocation achieves one of three solutions depending on the joint fading statistics. The orthogonal MARC studied here is a multiaccess generalization of the orthogonal relay channel in [2]; however, the optimal policies developed in [2] do not extend readily to maximize the sum-rate of the MARC. For a two-user MARC, we show that the DF sum-rate belongs to one of five disjoint cases or lies on the boundary of any two of them. Our results reveal two interesting observations: 1) analogously to a classic fading multiaccess channel [8], [9], the sum-rate optimal policy for each case exploits the multiuser fading diversity to opportunistically schedule users; 2) however, these optimal policies are not necessarily water-filling solutions. Finally, we present a geometric interpretation for each case to highlight the effects of node topology in the analysis of multi-terminal networks.

The paper is organized as follows. In Section II, we model the orthogonal MARC with Gaussian noise and fading. In Section III we present the rate region and determine the power policies that maximize the DF sum-rate. Finally, we conclude in Section IV.

II. CHANNEL MODEL AND PRELIMINARIES

A two-user MARC consists of two source nodes numbered 1 and 2, a relay node r , and a destination node d . We write $\mathcal{K} = \{1, 2\}$ to denote the set of sources, $\mathcal{T} = \mathcal{K} \cup \{r\}$ to denote the set of transmitters, and $\mathcal{D} = \{r, d\}$ to denote the set of receivers. In an orthogonal MARC, the sources transmit to the relay and destination on one channel, say channel 1, while the half-duplex relay transmits to the destination on an orthogonal channel 2 as shown in Fig. 1. A fraction θ of the total bandwidth resource is allocated to channel 1 while the remaining fraction $\bar{\theta} = 1 - \theta$ is allocated to channel 2. In the fraction θ , the source k transmits the signal X_k while the relay and the destination receive Y_r and $Y_{d,1}$ respectively. In the fraction $\bar{\theta}$, the relay transmits X_r and the destination receives

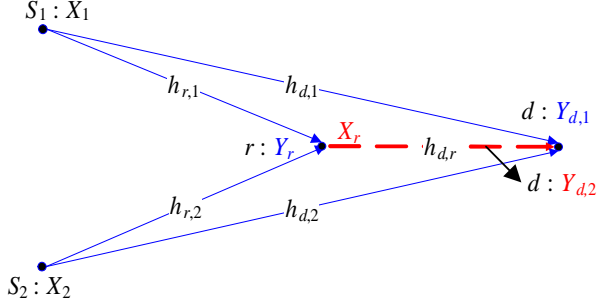


Fig. 1. A two-user orthogonal MARC.

$Y_{d,2}$. In each time symbol (channel use), we then have

$$Y_r = h_{r,1}X_1 + h_{r,2}X_2 + Z_r \quad (1)$$

$$Y_{d,1} = h_{d,1}X_1 + h_{d,2}X_2 + Z_{d,1} \quad (2)$$

$$Y_{d,2} = h_{d,r}X_r + Z_{d,2} \quad (3)$$

where $Z_r, Z_{d,1}, Z_{d,2}$ are independent circularly symmetric complex Gaussian noise random variables with zero means and unit variances. We write \underline{h} to denote the vector of fading gains, $h_{k,m}$, for all $k \in \mathcal{D}$ and $m \in \mathcal{T}, k \neq m$, such that \underline{h} is a realization for a given channel use of a jointly stationary and ergodic vector fading process \underline{H} . We assume that the fraction θ is fixed *a priori* and is known at all nodes.

Over n uses of the channel, the source and relay transmissions are constrained in power according to

$$\sum_{i=1}^n \mathbb{E}(|X_{ki}|^2) \leq n\bar{P}_k \quad \text{for all } k \in \mathcal{T}. \quad (4)$$

Since the sources and relay know the fading states of the links on which they transmit, they can allocate their transmitted signal power according to the channel state information. We write $P_k(\underline{h})$ to denote the power allocated as a function of the channel states \underline{h} at the k^{th} transmitter, for all $k \in \mathcal{T}$. For an ergodic fading channel, (4) then simplifies to

$$\mathbb{E}(P_k(\underline{h})) \leq \bar{P}_k \quad \text{for all } k \in \mathcal{T} \quad (5)$$

where the expectation in (5) is over the joint distribution \underline{H} . We write $\underline{P}(\underline{h})$ to denote a vector of power allocations with entries $P_k(\underline{h})$ for all $k \in \mathcal{T}$, and define \mathcal{P} to be the set of all $\underline{P}(\underline{h})$ whose entries satisfy (5). For ease of notation, we henceforth omit the functional dependence of \underline{P} on \underline{h} . We use the notation $C(x) = \log(1+x)$ where the logarithm is to the base 2, $(x)^+ = \max(x, 0)$, and write $R_S = \sum_{k \in S} R_k$ for any $S \subseteq \mathcal{K}$.

III. SUM-RATE OPTIMAL POWER POLICY

The DF rate region for a MARC with fixed channel gains and a full-duplex relay is developed in [5, Appendix A] (see also [6]). For a half-duplex MARC with a fixed \underline{h} and a fixed fraction θ , the DF rate region includes an additional

conditioning on the half-duplex modes of the relay [3] and is the set of all rate pairs (R_1, R_2) that satisfy

$$R_k \leq \min \left\{ \theta C \left(\frac{|h_{d,k}|^2 P_k}{\theta} \right) + \bar{\theta} C \left(\frac{|h_{d,r}|^2 P_r}{\theta} \right), \theta C \left(\frac{|h_{r,k}|^2 P_k}{\theta} \right) \right\}, k = 1, 2 \quad (6)$$

and

$$R_1 + R_2 \leq \min \left\{ \theta C \left(\sum_{k=1}^2 \frac{|h_{d,k}|^2 P_k}{\theta} \right) + \bar{\theta} C \left(\frac{|h_{d,r}|^2 P_r}{\theta} \right), \theta C \left(\sum_{k=1}^2 \frac{|h_{r,k}|^2 P_k}{\theta} \right) \right\}. \quad (7)$$

For a stationary and ergodic vector process \underline{H} , the channel in (1)-(3) can be modeled as a set of parallel Gaussian orthogonal MARCs, one for each fading instantiation \underline{h} . For a fixed \underline{P} , the DF rate bounds for this ergodic fading channel are obtained by averaging the bounds in (6) and (7) over all channel realizations. The DF rate region, \mathcal{R}_{DF} , achieved over all $\underline{P} \in \mathcal{P}$, is given by the following theorem.

Theorem 1: The DF rate region, \mathcal{R}_{DF} , achieved over an ergodic fading orthogonal Gaussian MARC is

$$\mathcal{R}_{DF} = \bigcup_{\underline{P} \in \mathcal{P}} \{ \mathcal{R}_r(\underline{P}) \cap \mathcal{R}_d(\underline{P}) \} \quad (8)$$

where, for all $S \subseteq \mathcal{K}$, we have

$$\mathcal{R}_r(\underline{P}) = \left\{ (R_1, R_2) : R_S \leq \theta \mathbb{E} C \left(\frac{\sum_{k \in S} |h_{r,k}|^2 P_k}{\theta} \right) \right\} \quad (9)$$

and

$$\mathcal{R}_d(\underline{P}) = \left\{ (R_1, R_2) : R_S \leq \theta \mathbb{E} C \left(\frac{\sum_{k \in S} |h_{d,k}|^2 P_k}{\theta} \right) + \bar{\theta} \mathbb{E} C \left(\frac{|h_{d,r}|^2 P_r}{\theta} \right) \right\} \quad (10)$$

Remark 2: The rate region \mathcal{R}_{DF} is convex. This follows from the convexity of the set \mathcal{P} and the concavity of the log function.

The region \mathcal{R}_{DF} in (8) is a union of the intersections of the regions $\mathcal{R}_r(\underline{P})$ and $\mathcal{R}_d(\underline{P})$ achieved at the relay and destination respectively, where the union is over all $\underline{P} \in \mathcal{P}$. Since \mathcal{R}_{DF} is convex, each point on the boundary of \mathcal{R}_{DF} is obtained by maximizing the weighted sum $\mu_1 R_1 + \mu_2 R_2$ over all $\underline{P} \in \mathcal{P}$, and for all $\mu_1 > 0, \mu_2 > 0$. Specifically, we determine the optimal policy \underline{P}^* that maximizes the sum-rate $R_1 + R_2$ when $\mu_1 = \mu_2 = 1$. Observe from (8) that every point on the boundary of \mathcal{R}_{DF} results from the intersection of $\mathcal{R}_r(\underline{P})$ and $\mathcal{R}_d(\underline{P})$ for some \underline{P} . In Figs. 2 and 3 we illustrate the five possible choices for the sum-rate resulting from such an intersection. Case 1 and case 2 result when no rate pair on the sum-rate plane achieved at one receiver lies within or on the boundary of the rate region achieved at the other receiver (see Fig. 2). On the other hand, cases 3a, 3b, and 3c result

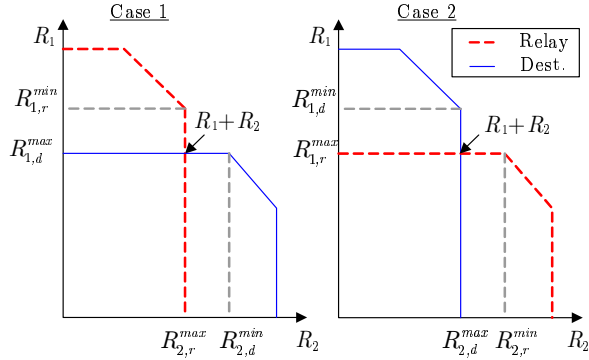


Fig. 2. Rate region and sum-rate for case 1 and case 2.

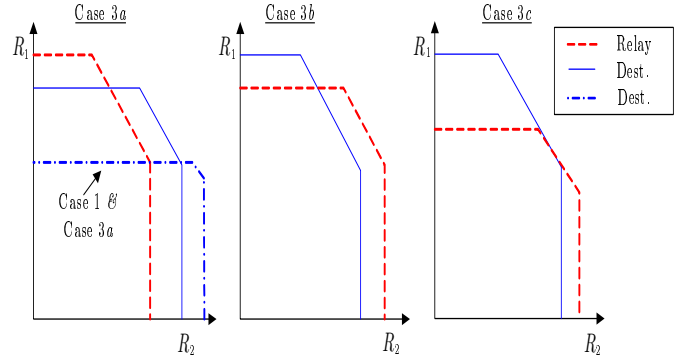


Fig. 3. Rate region and sum-rate for cases 3a, 3b, and 3c.

when there is more than one such rate pair as shown in Fig. 3. Observe that case 3c corresponds to a boundary case where the sum-rate planes overlap. We also consider six boundary cases where there is exactly one such rate pair that serves as a transition between case 1 or 2 and one of cases 3a, 3b, or 3c. An example of a boundary case for case 1 and case 3a is shown in Fig. 3. We write $\mathcal{B}_m \subseteq \mathcal{P}$ to denote the set of \underline{P} that achieve case i , $i = 1, 2, 3a, 3b, 3c$ and $\mathcal{B}_{l,n}$, $l = 1, 2$, $n = 3a, 3b, 3c$ to denote the set of \underline{P} satisfying each boundary case. We show in the sequel that the optimization is simplified considerably when the conditions for each case are defined such that the sets \mathcal{B}_i and $\mathcal{B}_{l,n}$ are disjoint for all i, l, n , and thus, are either open or half-open sets such that no two sets share a boundary. Finally, we observe that cases 1 and 2 do not share a boundary since such a transition (see Fig. 2) requires passing through case 3a or 3b or 3c.

To determine the optimal \underline{P}^* , we first define the conditions for each case and determine the policy $\underline{P}^{(i)}$ or $\underline{P}^{(l,n)}$ maximizing the sum-rate for case i or the boundary case (l, n) . We collect the six boundary cases as the last case. The optimal policy for each case is determined using Lagrange multipliers and the *Karush-Kuhn-Tucker* (KKT) conditions [10, 5.5.3].

Case 1: This case occurs when the power policy $\underline{P} \in \mathcal{B}_1$ achieves the relay and destination regions shown in Fig 2. The maximum sum-rate achieved in this case is

$$\max_{\underline{P} \in \mathcal{B}_1} (R_{1,d}^{\max}(\underline{P}) + R_{2,r}^{\max}(\underline{P})) \quad (11)$$

where $R_{k,m}^{\max}$ is the maximum rate achieved by user k at receiver $m \in \mathcal{D}$ in (9) and (10). The open set \mathcal{B}_1 contains all \underline{P} that satisfy

$$R_{1,d}^{\max}(\underline{P}) < R_{1,r}^{\min}(\underline{P}) \text{ and } R_{2,r}^{\max}(\underline{P}) < R_{2,d}^{\min}(\underline{P}) \quad (12)$$

where $R_{k,m}^{\min}$ is the rate achieved by user k when it is the first user to be successively decoded at a sum-rate corner point achieved at receiver m . Since \mathcal{B}_1 is not known a priori, we determine the optimal $\underline{P}^{(1)}$ maximizing $R_1 + R_2$ in (11) over \mathcal{P} . Expanding (11) using (9) and (10) and applying the Lagrange multiplier rule and the KKT conditions, we obtain

$P_k^{(1)}$ and $P_r^{(1)}$ as

$$P_k^{(1)} = \left(\frac{\theta}{\nu_k \ln 2} - \frac{\theta}{|h_{m,k}|^2} \right)^+ \quad (k, m) = (1, d), (2, r) \quad (13)$$

and

$$P_r^{(1)} = \left(\frac{\bar{\theta}}{\nu_r \ln 2} - \frac{\bar{\theta}}{|h_{d,r}|^2} \right)^+ \quad (14)$$

where the water-filling level ν_k , $k = 1, 2, r$, is determined from (5). To ensure that case 1 occurs, we require that $\underline{P}^{(1)} \in \mathcal{B}_1$, i.e., (13) and (14) satisfy (12). Then, the concavity of the rate functions in (9) and (10) suffices to show that $\underline{P}^{(1)}$ in (13) and (14) maximizes (11). On the other hand, when $\underline{P}^{(1)} \notin \mathcal{B}_1$, we show that $R_1 + R_2$ achieves its maximum outside \mathcal{B}_1 . Note that the expression for $R_1 + R_2$ for the other cases is not the same as that in (11). The proof follows from the fact that $R_1 + R_2$ in (11) is a concave function of \underline{P} for all $\underline{P} \in \mathcal{P}$. Thus, when $\underline{P}^{(1)} \notin \mathcal{B}_1$, for every $\underline{P} \in \mathcal{B}_1$ there exists a $\underline{P}' \in \mathcal{B}_1$ with a larger sum-rate. Combining this with the fact that the sum-rate expressions are continuous while transitioning from one case to another at the boundary of the open set \mathcal{B}_1 , ensures that the maximum sum-rate is achieved by some $\underline{P} \notin \mathcal{B}_1$. We remark that similar arguments also apply to the remaining cases, and will be omitted for brevity. Finally, we remark that (12) models a network geometry in which the destination and source 1 are physically proximal, i.e., they form a cluster, and the relay and source 2 form another cluster.

Case 2: The maximum sum-rate achieved for this case is

$$\max_{\underline{P} \in \mathcal{B}_2} (R_{1,r}^{\max}(\underline{P}) + R_{2,d}^{\max}(\underline{P})) \quad (15)$$

where \mathcal{B}_2 contains all \underline{P} that satisfy

$$R_{1,r}^{\max}(\underline{P}) < R_{1,d}^{\min}(\underline{P}) \text{ and } R_{2,d}^{\max}(\underline{P}) < R_{2,r}^{\min}(\underline{P}). \quad (16)$$

As in case 1, we can show that (15) is maximized by setting the optimal $P_k^{(2)}$ and $P_r^{(2)}$ to the expressions in (13) and (14) respectively with $(k, m) = (1, r), (2, d)$ provided the resulting $\underline{P}^{(2)}$ satisfies (16). Finally, we remark that the conditions in (16) model a network geometry in which the destination and source 2 form one cluster while the relay and source 1 form another cluster.

Case 3: Consider the cases 3a, 3b, and 3c shown in Fig. 3. The sum-rate optimization for all three cases simplifies to

$$\max_{\underline{P} \in \mathcal{B}_3} \min((R_{\mathcal{K}})_r, (R_{\mathcal{K}})_d) \quad (17)$$

where $(R_{\mathcal{K}})_r$ and $(R_{\mathcal{K}})_d$ are the mutual information expressions in (9) and (10) respectively for $\mathcal{S} = \mathcal{K}$, and \mathcal{B}_3 consists of \underline{P} that do not satisfy (12) and (16) either as strict inequalities or with equality. We write $\mathcal{B}_3 = \mathcal{B}_{3a} \cup \mathcal{B}_{3b} \cup \mathcal{B}_{3c}$, where \mathcal{B}_i , $i = 3a, 3b, 3c$ is defined for case i below. The optimization in (17) is a multiuser generalization of the single-user *max-min* problem studied in [2]. Extending the known general solution to (17), the optimal policy $\underline{P}^{(3)}$ for this case satisfies one of following three conditions

$$\text{Case 3a: } (R_{\mathcal{K}})_r|_{\underline{P}^{(3)}} < (R_{\mathcal{K}})_d|_{\underline{P}^{(3)}} \quad (18)$$

$$\text{Case 3b: } (R_{\mathcal{K}})_r|_{\underline{P}^{(3)}} > (R_{\mathcal{K}})_d|_{\underline{P}^{(3)}} \quad (19)$$

$$\text{Case 3c: } (R_{\mathcal{K}})_r|_{\underline{P}^{(3)}} = (R_{\mathcal{K}})_d|_{\underline{P}^{(3)}}. \quad (20)$$

We proceed to study cases 3a, 3b, and 3c in detail.

Case 3a: Maximizing $(R_{\mathcal{K}})_r$ subject to (5) results in the KKT conditions

$$f_k \leq \nu_k \ln 2, \quad k = 1, 2 \quad (21)$$

where

$$f_k = |h_{r,k}|^2 \left/ \left(1 + \sum_{k=1}^2 \frac{|h_{r,k}|^2 P_k}{\theta} \right) \right. \quad (22)$$

For those channel states in which the two users do not see the same scaled fading gains at the relay, i.e., $|h_{r,1}|/\nu_1 \neq |h_{r,2}|/\nu_2$, (21) reduces, for all $k, j \in \mathcal{K}$, $k \neq j$, and $i = 3a$, to

$$P_k^{(i)} = \begin{cases} \left(\frac{\theta}{\nu_k \ln 2} - \frac{\theta}{|h_{r,k}|^2} \right)^+ & f_k > f_j \frac{\nu_k}{\nu_j}, j \neq k \\ 0 & \text{o.w.} \end{cases} \quad (23)$$

Observe that the optimal $P_k^{(3a)}$ in (23) is an opportunistic water-filling solution that exploits the fading diversity in a multiaccess channel with the relay as the receiver. The optimal policy at the relay $P_r^{(3a)}$ is given by (14). For $\underline{P}^{(3a)} \in \mathcal{B}_3$, the requirement of satisfying (18), i.e., $\underline{P}^{(3a)} \in \mathcal{B}_{3a}$, simplifies to a threshold condition $\bar{P}_r > P_u(\bar{P}_1, \bar{P}_2)$ where \bar{P}_k , $k \in \mathcal{T}$, is defined in (5) and the threshold $P_u(\bar{P}_1, \bar{P}_2)$ is obtained by setting (18) to an equality. When $\underline{P}^{(3a)} \in \mathcal{B}_3$ but $\underline{P}^{(3a)} \notin \mathcal{B}_{3a}$, $R_1 + R_2$ is maximized by either *case 3b* or *case 3c*. For $\underline{P}^{(3a)} \notin \mathcal{B}_3$, as argued in case 1, the sum-rate is not maximized by any $\underline{P} \in \mathcal{B}_3$. Finally, the condition in (18) suggests a geometry where the sources and destination are clustered.

Case 3b: The KKT conditions and optimal $P_k^{(3b)}$ for this case maximize $(R_{\mathcal{K}})_d$ and are given by (21) and (23) respectively with the subscript ‘ r ’ in (22) changed to ‘ d ’ for all k and $i = 3b$. Further, (21) and (22) also hold for the relay node, $k = r$, and simplifies to the water-filling solution in (14). Thus, as in case 3a, it is optimal to time-division duplex the users except that this is now based on their scaled fading gains to the destination. For $\underline{P}^{(3b)} \in \mathcal{B}_3$, satisfying (19), i.e., $\underline{P}^{(3b)} \in \mathcal{B}_{3b}$, reduces to satisfying the threshold condition $\bar{P}_r < P_l(\bar{P}_1, \bar{P}_2)$ where $P_l(\bar{P}_1, \bar{P}_2)$ is determined by setting (19)

to an equality. Finally, (19) implies a geometry in which the sources are clustered closer to the relay than to the destination.

Case 3c (equalizer policy): Maximizing $(R_{\mathcal{K}})_r$ over all \underline{P} , subject to (20) gives $\underline{P}^{(3c)}$. This case occurs when $\underline{P}^{(3c)} \in \mathcal{B}_{3c}$, i.e. $P_l(\bar{P}_1, \bar{P}_2) \leq \bar{P}_r \leq P_u(\bar{P}_1, \bar{P}_2)$. The resulting KKT conditions take the form in (21) such that for $k = 1, 2$,

$$f_k = \frac{(1-\alpha)|h_{r,k}|^2}{1 + \sum_{j=1}^2 |h_{r,j}|^2 P_j / \theta} + \frac{\alpha|h_{d,k}|^2}{1 + \sum_{j=1}^2 |h_{d,j}|^2 P_j / \theta}. \quad (24)$$

For $k = r$, f_r is obtained by replacing $h_{r,k}$ in (22) by $h_{d,r}$ and scaling by α . The Lagrange multiplier α accounts for the boundary condition in (20) and is computed by evaluating (20) at $\underline{P}^{(3c)}$. The relay’s optimal policy simplifies to the water-filling solution in (14) with the first term scaled by α . For $|h_{m,1}|/\nu_1 \neq |h_{m,2}|/\nu_2$, $m = r$ or d , (21) simplifies, for f_k in (24) and for all $k, j \in \mathcal{K}$, $k \neq j$, and $i = 3c$ as

$$P_k^{(i)} = \begin{cases} (\text{root of } f_k|_{P_j=0})^+ & f_k > f_j \\ 0 & \text{o.w.} \end{cases} \quad (25)$$

From (25), we see that user k , $k = 1, 2$, transmits opportunistically over those channel states where a function f_k of its fading gains and power is larger than that of the other user. Note that the optimal policy $P_k^{(3c)}$ in (25) is no longer a water-filling solution at the two sources. Finally, we remark that this boundary case occurs for a range of geometries that transition from the clustered geometry of case 3a to that of case 3b.

Case 4: Boundary Cases: We now consider the six boundary cases and summarize the optimal $\underline{P}^{(l,n)}$, $l = 1, 2$, $n = 3a, 3b, 3c$, for each case. As with case 3c, we observe that the geometries for these boundary cases also straddle the clustered geometries of the two cases involved.

Case 1 and Case 3a: The sum-rate optimization for this case simplifies to

$$\max_{\underline{P} \in \mathcal{B}_{1,3a}} (R_{\mathcal{K}})_r \quad \text{s.t. } (R_{\mathcal{K}})_r = R_{1,d}^{\max} + R_{2,r}^{\max} \quad (26)$$

where $\mathcal{B}_{1,3a}$ is the set of all \underline{P} that satisfy (18), (26), and one of the inequalities in (12) (see Fig. 3). Note that from (9), we can write $(R_{\mathcal{K}})_r = R_{1,r}^{\min} + R_{2,r}^{\max}$ thus simplifying the condition in (26) to $R_{1,r}^{\min} = R_{1,d}^{\max}$ as shown in Fig. 3. As before, we obtain the KKT conditions in (21) for $k = 1, 2$, $(k, m) = (1, d), (2, r)$, and

$$f_k = \frac{(1-\alpha)|h_{r,k}|^2}{1 + \sum_{j=1}^2 \frac{|h_{r,j}|^2 P_j}{\theta}} + \frac{\alpha|h_{m,k}|^2}{1 + \frac{|h_{m,k}|^2 P_k}{\theta}} \quad (27)$$

where α is the Lagrange multiplier satisfying the boundary condition in (26). When $|h_{m,1}|/\nu_1 \neq |h_{m,2}|/\nu_2$, $m = r$ or d , (21) simplifies $P_k^{(1,3a)}$ to the opportunistic non-water-filling solution in (25) with f_k in (27), and for all $k, j \in \mathcal{K}$, $k \neq j$, $(k, m) = (1, d), (2, r)$, $(l, n) = (1, 3a)$. The optimal $P_r^{(1,3a)}$ is given by (14) with the first term scaled by α .

Case 2 and Case 3a: The sum-rate optimization for this case is

$$\max_{\underline{P} \in \mathcal{B}_{2,3a}} (R_{\mathcal{K}})_r \quad \text{s.t. } R_{2,r}^{\min} = R_{2,d}^{\max} \quad (28)$$

where $\mathcal{B}_{2,3a}$ is the set of all \underline{P} that satisfy (18), (28), and the remaining inequality in (16). The resulting KKT conditions in (21) use f_k , $k = 1, 2$, defined in (27) but with $(k, m) = (1, r), (2, d)$. Note that α captures the equality condition in (28). For $|h_{m,1}|/\nu_1 \neq |h_{m,2}|/\nu_2$, $m = r$ or d , and $(k, m) = (1, r), (2, d)$, $P_k^{(2,3a)}$ at each source is given by the opportunistic policy in (25). The optimal relay policy $P_r^{(2,3a)}$ is the same as that obtained in *case 1* and *case 3a*.

Case 1 and *Case 3b*: The sum-rate optimization for this case is

$$\max_{P \in \mathcal{B}_{1,3b}} (R_{\mathcal{K}})_d \text{ s.t. } R_{2,d}^{\min} = R_{2,r}^{\max} \quad (29)$$

where $\mathcal{B}_{1,3b}$ is the set of all \underline{P} that satisfy (19), (29), and the remaining inequality in (12). The resulting KKT conditions satisfy (21) where f_k , $k = 1, 2$, is given by (27) with the subscript ‘ r ’ replaced by ‘ d ’. Note that α captures the boundary condition in (29). For $|h_{m,1}|/\nu_1 \neq |h_{m,2}|/\nu_2$, $m = r$ or d , and $(k, m) = (2, r), (1, d)$, $P_k^{(1,3b)}$ at each source is given by the opportunistic non-water-filling solution in (25). The optimal relay policy $P_r^{(1,3b)}$ simplifies to the water-filling solution in (14).

Case 2 and *Case 3b*: The sum-rate optimization for this case simplifies to

$$\max_{P \in \mathcal{B}_{2,3b}} (R_{\mathcal{K}})_d \text{ s.t. } R_{1,d}^{\min} = R_{1,r}^{\max} \quad (30)$$

where $\mathcal{B}_{2,3b}$ is the set of all \underline{P} that satisfy (19), (30), and the remaining inequality in (16). We remark that the KKT conditions are the same as (21) where f_k , $k = 1, 2$, is given by (27) with ‘ r ’ replaced by ‘ d ’ and $(k, m) = (1, r), (2, d)$. The resulting $P_k^{(2,3b)}$, $k = 1, 2$ are given by the opportunistic policies in (25). Finally, the optimal $P_r^{(2,3b)}$ is the same as that obtained in *case 1* and *case 3b*.

Case 1 and *Case 3c*: The sum-rate optimization for this case is

$$\max_{P \in \mathcal{B}_{1,3c}} (R_{\mathcal{K}})_r \text{ s.t. } R_{2,d}^{\min} = R_{2,r}^{\max} \text{ and } R_{1,d}^{\max} = R_{1,r}^{\min} \quad (31)$$

where $\mathcal{B}_{1,3c}$ is the set of all \underline{P} that satisfy (20), (31), and the remaining inequality in (12). The resulting KKT conditions satisfy (21) for $k = 1, 2$, and $(k, m) = (1, d), (2, r)$ where

$$f_k = \frac{\alpha_3 |h_{r,k}|^2}{1 + \sum_{j=1}^2 \frac{|h_{r,j}|^2 P_j}{\theta}} + \frac{\alpha_2 |h_{d,k}|^2}{1 + \sum_{j=1}^2 \frac{|h_{d,j}|^2 P_j}{\theta}} + \frac{\alpha_1 |h_{m,k}|^2}{1 + \frac{|h_{m,k}|^2 P_k}{\theta}} \quad (32)$$

and α_1 , α_2 , and $\alpha_3 = 1 - \alpha_1 - \alpha_2$ are Lagrange multipliers that capture the boundary conditions in (31). When $|h_{m,1}|/\nu_1 \neq |h_{m,2}|/\nu_2$, $m = r$ or d , for all $k, j \in \mathcal{K}$, $k \neq j$, and pairs $(k, m) = (1, d), (2, r)$, the optimal $P_k^{(1,3c)}$, $k = 1, 2$, is given by the opportunistic policy in (25) while $P_r^{(1,3c)}$ is given by the water-filling solution in (14) with the first term scaled by $(\alpha_1 + \alpha_2)$.

Case 2 and *Case 3c*: The sum-rate optimization for this case is

$$\max_{P \in \mathcal{B}_{2,3c}} (R_{\mathcal{K}})_r \text{ s.t. } R_{2,d}^{\max} = R_{2,r}^{\min} \text{ and } R_{1,d}^{\min} = R_{1,r}^{\max} \quad (33)$$

where $\mathcal{B}_{2,3c}$ is the set of all \underline{P} that satisfy (20), (33), and the remaining inequality in (16). The resulting KKT conditions and optimal policy $\underline{P}^{(2,3c)}$ are the same as in *case 1* and *case 3c* but with $(k, m) = (1, r), (2, d)$.

Finally, the optimal \underline{P}^* is given by the following theorem.

Theorem 3: The \underline{P}^* that maximizes the sum-rate is obtained by computing $\underline{P}^{(m)}$ or $\underline{P}^{(j,k)}$ starting from *case 1* and proceeding one case at a time, until for some case the corresponding $\underline{P}^{(m)}$ or $\underline{P}^{(j,k)}$ satisfies the case conditions.

IV. SUMMARY AND FUTURE WORK

We have developed the power policy that maximizes the sum-rate of a two-user orthogonal MARC. We have shown that the optimal policy is a function of the channel statistics and network geometry and can be classified into two broad categories. The first category involves cases where each user is clustered with a different receiver as a result of which the sum-rate decouples into independent terms for each user and the relay. The second category includes the cases where the two users are clustered with one of the receivers as well as the boundary cases. The first category admits the classic water-filling solution at each user and the relay. The optimal policies for the second category do not always result in a water-filling solution at the sources; however, they reveal the optimality of exploiting the multiuser fading diversity to opportunistically schedule users. Our results can be generalized to a K -user orthogonal MARC with $K > 2$. Finally, one could also consider the resource allocation problem for CF where the challenge lies in solving a non-convex optimization problem.

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