

### Exercises For Wednesday Evening

#### 1. Presented by: Vera Zabrodina (Basel)

Suppose that  $y_{1t}$  and  $y_{2t}$  are scalar random variables with

$$y_{1t} = x_t + \varepsilon_{1t}$$

$$y_{2t} = x_t + \varepsilon_{2t}$$

where  $x_t$ ,  $\varepsilon_{1t}$ , and  $\varepsilon_{2t}$  are mutually independent i.i.d. sequences of  $N(0,1)$  random variables. A researcher has data on  $y_{1t}$  and  $y_{2t}$  and would like to use these data to estimate the value of  $x_t$ .

She proposes the estimator  $\hat{x}_t = \frac{1}{2}(y_{1t} + y_{2t})$ .

- Compute the mean squared error (MSE) of  $\hat{x}_t$ .
- A more general estimator is  $\tilde{x}_t = \lambda_1 y_{1t} + \lambda_2 y_{2t}$ , where  $\lambda_1$  and  $\lambda_2$  are two constants. What values of  $\lambda_1$  and  $\lambda_2$  yield the estimator with the smallest MSE?
- An even more general estimator is  $\tilde{x}_t = g(y_{1t}, y_{2t})$ . What function  $g$  yields the estimator with the smallest MSE?

#### 2. Presented by: Pascal Mehty (Lausanne)

Consider the state-space model

$$y_t = \beta x_t + v_t$$

$$x_t = \phi x_{t-1} + \varepsilon_t$$

where  $x$  and  $y$  are scalars,

$$\begin{pmatrix} v_t \\ \varepsilon_t \end{pmatrix} \sim i.i.d. N \left( \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \sigma_v^2 & \sigma_{v\varepsilon} \\ \sigma_{v\varepsilon} & \sigma_\varepsilon^2 \end{bmatrix} \right)$$

with  $\sigma_{v\varepsilon} \neq 0$ , and  $\{x\}$  is not observed. Using the usual Kalman filter notation, let

$x_{t|k} = E(x_t | \{y_i\}_{i=1}^k)$  and  $P_{t|k} = Var(x_t | \{y_i\}_{i=1}^k)$ . Derive an algorithm that computes  $x_{t|t}$  and  $P_{t|t}$  as a function of  $x_{t-1|t-1}$ ,  $P_{t-1|t-1}$  and  $y_t$ .

### 3. Presented by: Tobias Lehmann (Lausanne)

Consider the model  $y_t = s_t + \varepsilon_t$  where  $\varepsilon_t \sim \text{i.i.d. } N(0,1)$  and  $s_t$  is a 0-1 binary random variable with  $P(s_t = 1 | s_{t-1} = 0) = 0.3$  and  $P(s_t = 1 | s_{t-1} = 1) = 0.8$ .

- (a) Suppose that the history of information on  $y$  tells you that  $P(s_{t-1} = 1 | y_{1:t-1}) = 0.6$ . You observe  $y_t = 1.5$ . Compute  $P(s_t = 1 | y_{1:t})$ .
- (b) Generalize your calculations and derive a recursive algorithm for computing  $P(s_t = 1 | y_{1:t})$  as a function of  $y_t$  and  $P(s_{t-1} = 1 | y_{1:t-1})$ . Explain how this result can be used to compute the likelihood function/joint density of  $y_{1:T}$ .

### 4. Presented by: Seoni Han (Graduate)

Suppose that  $y_t = x_t + \varepsilon_t$ , where  $x_t = 0.8x_{t-1} + e_t$ , and where  $\begin{bmatrix} \varepsilon_t \\ e_t \end{bmatrix} \sim \text{i.i.d. } N\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}\right)$ .

Suppose you know that  $x_0 = 2$  and  $y_1 = 4.6$ .

- (a) Derive the minimum mean square error estimate of  $x_1$ .
- (b) What is the mean squared error of the estimate in (a)?

Now suppose now that  $\{\varepsilon_t\}$  and  $\{e_t\}$  are mutually independent iid processes with (i)  $\varepsilon_t = -2$  with probability 0.5 and  $\varepsilon_t = 2$  with probability 0.5, and (ii)  $e_t = -1$  with probability 0.5 and  $e_t = 1$  with probability 0.5. Suppose you know that  $x_0 = 2$  and  $y_1 = 4.6$

- (c) Derive the linear minimum mean square error estimate of  $x_1$ .
- (e) What is the mean squared error of this estimate?
- (f) Is the estimate in (e) the minimum mean squared estimate? Explain.

### 5. Presented by: Severin Lenhard (Bern)

Suppose that  $y_t = x_t\beta + u_t$ , where  $u_t = \phi u_{t-1} + \varepsilon_t$ , where  $\varepsilon_t$  and  $x_t$  are both i.i.d. with mean zero and variance  $\sigma_\varepsilon^2$  and  $\sigma_x^2$ , and  $\varepsilon_t$  and  $x_\tau$  are independent for all  $t$  and  $\tau$ . Let  $\hat{\beta}$  denote the OLS estimator of  $\beta$  based on a sample of size  $T$ , and let  $\hat{u}_t$  denote the OLS residual.

- (a) Show that  $\sqrt{T}(\hat{\beta} - \beta) \xrightarrow{d} N(0, V)$  and  $\sqrt{T}(\hat{\beta} - \beta) \xrightarrow{d} N(0, V)$  and derive an expression for  $V$ .

(b) Suppose that  $T = 100$ ,  $\hat{\beta} = 2.1$ ,  $\frac{1}{100} \sum_{t=1}^{100} x_t^2 = 5$ ,  $\frac{1}{99} \sum_{t=2}^{100} x_t x_{t-1} = 0.5$ ,  $\frac{1}{98} \sum_{t=3}^{100} x_t x_{t-2} = 0.03$ ,  
 $\frac{1}{100} \sum_{t=1}^{100} \hat{u}_t^2 = 4$ ,  $\frac{1}{99} \sum_{t=2}^{100} \hat{u}_t \hat{u}_{t-1} = 3.6$ ,  $\frac{1}{98} \sum_{t=3}^{100} \hat{u}_t \hat{u}_{t-2} = 3.1$ ,  $\frac{1}{99} \sum_{t=2}^{100} x_t \hat{u}_{t-1} = 0.2$ ,  
 $\frac{1}{99} \sum_{t=2}^{100} \hat{u}_t x_{t-1} = -0.05$ . Construct a 95% confidence interval for  $\beta$ .