

# Correspondence

## A Simple Proof of the Entropy-Power Inequality

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**Abstract**—This correspondence gives a simple proof of Shannon’s entropy-power inequality (EPI) using the relationship between mutual information and minimum mean-square error (MMSE) in Gaussian channels.

**Index Terms**—Differential entropy, entropy-power inequality (EPI), minimum mean-square error (MMSE).

### I. INTRODUCTION

In *A Mathematical Theory of Communication* [1], Claude Shannon put forth the inequality

$$\exp(2h(X + Y)) \geq \exp(2h(X)) + \exp(2h(Y)) \quad (1)$$

where  $X$  and  $Y$  are independent real-valued random variables and  $h(X)$  is the differential entropy of the probability density function  $f_X$ <sup>1</sup>

$$h(X) = - \int_{-\infty}^{\infty} f_X(u) \log f_X(u) du.$$

The entropy-power (variance of a Gaussian random variable with the same differential entropy) is maximum and equal to the variance when the random variable is Gaussian, and thus, the essence of (1) is that the sum of independent random variables tends to be “more Gaussian” than one or both of the individual components. Note that (1) is equivalent to

$$\exp(2h(X_1 + \dots + X_n)) \geq \sum_{i=1}^n \exp(2h(X_i)) \quad (2)$$

for  $n$  independent random variables.

The first proof of (1) was given by Stam [2], based on an identity communicated to him by N. G. De Bruijn, which couples Fisher’s information with Shannon’s differential entropy.

Capitalizing on the relationship between mutual information and minimum mean-square error (MMSE) for additive Gaussian channels [3], this note gives a simpler proof of the entropy-power inequality (EPI) based on an elementary estimation-theoretic reasoning which sidesteps invoking Fisher’s information. In a follow-up to this work [4], we use the MMSE to give simple proofs of two variations of the EPI, namely, Costa’s strengthened EPI in which one of the variables is

Gaussian [5], and a generalized EPI for linear transforms of a random vector due to Zamir and Feder [6].

Following a simple “noise-incremental” argument, [3] shows that regardless of the distribution of  $X$  we can write

$$\frac{d}{d\gamma} I(X; \sqrt{\gamma}X + N) = \frac{1}{2} \text{mmse}(X, \gamma) \quad (3)$$

where  $N \sim \mathcal{N}(0, 1)$  is standard Gaussian independent of  $X$ , and the MMSE of estimating  $X$  in unit-variance additive Gaussian noise is

$$\text{mmse}(X, \gamma) = E \left\{ (X - E\{X | \sqrt{\gamma}X + N\})^2 \right\}.$$

Here  $\gamma$  is understood as the (gain of the) signal-to-noise ratio of the Gaussian channel whose input is  $X$ .

A direct consequence of (3) is the representation of the differential entropy of a random variable with variance  $\sigma_X^2$  as [3, eq. (182)]

$$h(X) = \frac{1}{2} \log(2\pi e \sigma_X^2) - \frac{1}{2} \int_0^\infty \frac{\sigma_X^2}{1 + \gamma \sigma_X^2} - \text{mmse}(X, \gamma) d\gamma. \quad (4)$$

Thus, the nongaussianness of  $X$  (divergence of  $f_X$  with respect to the Gaussian density with identical first and second moments) is given by one half of the integral of the difference of the MMSEs achievable by a Gaussian input with variance  $\sigma_X^2$  and by  $X$ , respectively.

For a unit-variance  $X$ , (4) reduces to

$$h(X) = \frac{1}{2} \log(2\pi e) - \frac{1}{2} \int_0^\infty \frac{1}{1 + \gamma} - \text{mmse}(X, \gamma) d\gamma. \quad (5)$$

It is amusing (and useful) to note that (5) holds even if  $X$  does not have unit variance: simply observe that

$$\log \sigma_X^2 = \int_0^\infty \frac{\sigma_X^2}{1 + \gamma \sigma_X^2} - \frac{1}{1 + \gamma} d\gamma. \quad (6)$$

Note that whenever  $\text{mmse}(X, \gamma) = o(1/\gamma)$  (as in the case of a discrete random variable, where it vanishes exponentially), (4) indicates that  $h(X) = -\infty$ .

Since (5) expresses the differential entropy of an arbitrary random variable in terms of the MMSE of its estimation when observed in Gaussian noise, (1) can be seen as a relationship between the MMSEs (integrated over signal-to-noise ratios) of the sum and of the individual random variables.

### II. PROOF OF (1)

Instead of showing (1) directly, it is more convenient to prove the equivalent inequality:

*Lemma 1:* (Lieb [7])<sup>2</sup> The inequality

$$h(X_1 \cos \alpha + X_2 \sin \alpha) \geq \cos^2 \alpha h(X_1) + \sin^2 \alpha h(X_2) \quad (7)$$

for all independent  $X_1$  and  $X_2$  and  $\alpha \in [0, 2\pi]$  is equivalent to the EPI (1) for all independent  $X$  and  $Y$ .

<sup>2</sup>See the Appendix for the proof.

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<sup>1</sup>For convenience, throughout this correspondence we assume that all logarithms are natural.

*Proof:* [Inequality (7)]. Select arbitrary independent  $X_1$  and  $X_2$ ,  $\alpha \in [0, 2\pi]$ . According to (5), the difference between the left- and right-hand sides of (7) is equal to

$$\frac{1}{2} \int_0^\infty \text{mmse}(X_1 \cos \alpha + X_2 \sin \alpha, \gamma) - \cos^2 \alpha \text{mmse}(X_1, \gamma) - \sin^2 \alpha \text{mmse}(X_2, \gamma) d\gamma.$$

Thus, it suffices to show that for all  $\gamma$

$$\text{mmse}(X, \gamma) \geq \cos^2 \alpha \text{mmse}(X_1, \gamma) + \sin^2 \alpha \text{mmse}(X_2, \gamma) \quad (8)$$

where we define

$$X = X_1 \cos \alpha + X_2 \sin \alpha.$$

Let  $N_1$  and  $N_2$  be independent standard Gaussian random variables, and let

$$\begin{aligned} Z_1 &= \sqrt{\gamma} X_1 + N_1 \\ Z_2 &= \sqrt{\gamma} X_2 + N_2 \\ Z &= Z_1 \cos \alpha + Z_2 \sin \alpha. \end{aligned}$$

Then, the left-hand side of (8) can be written as

$$\begin{aligned} & \mathbf{E} \left\{ (X - \mathbf{E} \{X | Z\})^2 \right\} \\ & \geq \mathbf{E} \left\{ (X - \mathbf{E} \{X | Z_1, Z_2\})^2 \right\} \end{aligned} \quad (9)$$

$$\begin{aligned} & = \cos^2 \alpha \mathbf{E} \left\{ (X_1 - \mathbf{E} \{X_1 | Z_1\})^2 \right\} \\ & \quad + \sin^2 \alpha \mathbf{E} \left\{ (X_2 - \mathbf{E} \{X_2 | Z_2\})^2 \right\} \end{aligned} \quad (10)$$

thereby showing (8). Note that in (10) we have used the mutual independence of  $N_1, N_2, X_1, X_2$ .  $\square$

Note that the only inequality used in the proof of (7) (and, hence, (1) via Lemma 1) is (9), namely, the fact that it is easier to estimate the sum of independent random variables on the basis of individual measurements than on the basis of their sum.

As an addendum to the foregoing proof, we call attention to the fact that the main inequality (7) also holds when the random variables therein are finitely or countably (real) valued and the differential entropies are replaced by entropies. To see this, note that in the discrete case, the representation

$$\begin{aligned} & H(X_1 \cos \alpha + X_2 \sin \alpha) - \cos^2 \alpha H(X_1) - \sin^2 \alpha H(X_2) \\ & = \int_0^\infty \text{mmse}(X_1 \cos \alpha + X_2 \sin \alpha, \gamma) \\ & \quad - \cos^2 \alpha \text{mmse}(X_1, \gamma) - \sin^2 \alpha \text{mmse}(X_2, \gamma) d\gamma \end{aligned}$$

follows immediately from [3, eq. (176)], and the argument we gave above for (8) holds also for discrete random variables.

Unlike previous proofs of the EPI (e.g., [2], [8]), the new proof does not hinge on Fisher's information.

### III. VECTOR ENTROPY-POWER INEQUALITY

To show the vector EPI for independent random  $n$ -vectors  $\mathbf{X}$  and  $\mathbf{Y}$ ,

$$\exp(2h(\mathbf{X} + \mathbf{Y})/n) \geq \exp(2h(\mathbf{X})/n) + \exp(2h(\mathbf{Y})/n)$$

we can follow the same steps as above using the following representation for the differential entropy of an  $n$  vector with covariance matrix  $\mathbf{\Sigma}$ , which follows easily from [3, eq. (22)]:

$$\begin{aligned} h(\mathbf{X}) &= \frac{1}{2} \log((2\pi e)^n \det \mathbf{\Sigma}) \\ & \quad - \frac{1}{2} \int_0^\infty \text{tr}[\mathbf{\Sigma}^{-1} + \gamma \mathbf{I}]^{-1} - \text{mmse}(\mathbf{X}, \gamma) d\gamma \\ & = \frac{n}{2} \log(2\pi e) - \frac{1}{2} \int_0^\infty \frac{n}{1+\gamma} - \text{mmse}(\mathbf{X}, \gamma) d\gamma. \end{aligned} \quad (11)$$

Here, the MMSE of estimating a vector in Gaussian noise is

$$\text{mmse}(\mathbf{X}, \gamma) = \mathbf{E} \left\{ \|\mathbf{X} - \mathbf{E} \{ \mathbf{X} | \sqrt{\gamma} \mathbf{X} + \mathbf{N} \}\|^2 \right\}$$

where  $\mathbf{N}$  consists of independent and identically distributed (i.i.d.) unit-variance Gaussian entries.

With (11), the same proof we used above can be employed to show that (7) holds when  $X_1$  and  $X_2$  therein are replaced by independent vectors of identical dimensions.

### APPENDIX

For completeness we include a simple proof of Lemma 1.

*Proof [Lemma 1]*

To verify that (1) follows from (7), choose arbitrary independent  $X$  and  $Y$  and let

$$\tan \alpha = \exp(h(Y) - h(X)) \quad (12)$$

$$X_1 = \frac{X}{\cos \alpha} \quad (13)$$

$$X_2 = \frac{Y}{\sin \alpha}. \quad (14)$$

Then, using (7) and  $h(aV) = h(V) + \log |a|$ , we can bound

$$\begin{aligned} & h(X + Y) \\ & \geq \cos^2 \alpha (h(X) - \log \cos \alpha) + \sin^2 \alpha (h(Y) - \log \sin \alpha) \\ & = \frac{1}{2} \log [\exp(2h(X)) + \exp(2h(Y))] \end{aligned}$$

which is (1).

The reverse direction is not needed in the proof of (1), but it is very simple: fixing arbitrary  $\alpha$  and independent  $X_1, X_2$ , choose  $X$  and  $Y$  to satisfy (13) and (14). Upon taking logarithms of both sides of (1), (7) follows from the concavity of the logarithm.  $\square$

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