

Testing Continuous-Time Models of the Spot Interest Rate

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Different continuous-time models for interest rates coexist in the literature. We test parametric models by comparing their implied parametric density to the same density estimated nonparametrically. We do not replace the continuous-time model by discrete approximations, even though the data are recorded at discrete intervals. The principal source of rejection of existing models is the strong nonlinearity of the drift. Around its mean, where the drift is essentially zero, the spot rate behaves like a random walk. The drift then mean-reverts strongly when far away from the mean. The volatility is higher when away from the mean.

The continuous-time financial theory has developed extensive tools to price derivative securities when the underlying traded asset(s) or nontraded factor(s) follow stochastic differential equations [see Merton (1990) for examples]. However, as a practical matter, how to specify an appropriate stochastic differential equation is for the most part an unanswered question. For example, many different continuous-time

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processes have been proposed to capture the dynamics of the instantaneous spot interest rate. These models are generally mutually exclusive and, when used to price derivative securities, generate significantly different prices. This article develops a simple methodology for testing their specification and evaluates various models for the short-term spot interest rate.

A continuous-time model in finance typically rests on one or more stationary diffusion processes $\{X_t, t \geq 0\}$, with dynamics represented by Itô stochastic differential equations:

$$dX_t = \mu(X_t)dt + \sigma(X_t)dW_t \quad (1)$$

where $\{W_t, t \geq 0\}$ is a standard Brownian motion. The functions $\mu(\cdot)$ and $\sigma^2(\cdot)$ are, respectively, the drift and the diffusion functions of the process. Most often they are parametrized:

$$\mu(x) = \mu(x, \theta) \text{ and } \sigma^2(x) = \sigma^2(x, \theta), \text{ where } \theta \in \Theta \subset R^K. \quad (2)$$

The choice of the parametric drift and diffusion families is often arbitrary. For example, most interest rate models specify a linear mean-reverting drift, $\mu(x, \theta) = \beta(\alpha - x)$, where the spot rate moves in the direction of its mean α at speed β . The specification of the diffusion function, however, tends to vary widely. The Vasicek (1977) model has $\sigma^2(x, \theta) = \sigma^2$, while the Cox, Ingersoll, and Ross (1985) model has $\sigma^2(x, \theta) = \sigma^2 x$ and in the Courtadon (1982) model the diffusion function is $\sigma^2(x, \theta) = \sigma^2 x^2$. Chan et al. (1992) utilized a discrete approximation to estimate the constant elasticity of variance model where $\sigma^2(x, \theta) = \sigma^2 x^\gamma$.¹ In the Constantinides (1992) model, the resulting specification is of the form $\mu(x, \theta) = \alpha_0 + \alpha_1 x + \alpha_2 \sqrt{x - \alpha_3}$ and $\sigma^2(x, \theta) = \sigma_0^2 (x - \alpha_3)^2$, while Duffie and Kan (1993) specify $\mu(x, \theta) = \beta(\alpha - x)$ and $\sigma(x, \theta) = \sqrt{\sigma_0 + \sigma_1 x}$. Ait-Sahalia (1992b) developed an estimator designed to take into account the discrete character of the data while maintaining the attractiveness of the continuous-time model, and estimate nonparametrically the diffusion function.

This far from exhaustive list (see also Table 2) shows that there is no shortage of proposed models for the continuous-time dynamics of the spot rate. We therefore focus on the following question: Is it possible to distinguish between the various specifications? Or equivalently: when is a given parametric model [Equation (2)] a "good" model for short-term interest rate movements? For a given parametric model, the null hypothesis will therefore state that there exist parameter values for which the parametric model considered is an acceptable represen-

¹ Other articles considering a similar class of models are Koejdik, Schotman, and Wolff (1995), Pagan, Hall, and Martin (1995), and Pfann, Schotman, and Tschernig (1995).

tation of the data. The alternative hypothesis, on the contrary, affirms that no parameter values are capable of reproducing the true μ and σ^2 functions.

One approach might be to attempt to choose among possible spot rate processes based on how well they price specific liquid derivatives; for example, bonds, swaps, or caps. Unfortunately this is often a difficult task in practice, and when at all feasible the answer tends to vary with the specific derivatives selected. This approach also implicitly assumes that the market prices these instruments correctly in the first place, so the resulting process can hardly be used to try to detect and exploit market biases in relatively illiquid markets. Furthermore any such test is a joint test of the specification of the factor process here the spot rate, and the pricing model—in particular the specification of the market price of spot rate risk. Any rejection is consequently hard to interpret.

It is therefore desirable to be able to test the specification of the actual spot rate process without making use of observations on a collection of derivatives. The test statistic in this article is based on the following idea. An essential property of a diffusion process is that it is entirely characterized by its first two continuous-time moments, the μ and σ^2 functions.² So each parametric model for the μ and σ^2 functions, such as the Cox, Ingersoll, and Ross (1985) model, will imply a certain family of density functions for the interest rate observations. The test statistic is based on a comparison of the density implied by the parametric model and a nonparametric estimator valid even if the parametric model is misspecified.

We empirically test several one-factor diffusion models for the 7-day Eurodollar deposit rate. We then identify the sources of the rejection of existing models. The linearity of the drift imposed in the literature appears to be the main source of misspecification. We find instead that the drift of the spot rate process is essentially zero as long as the rate is between 4 and 17 percent, but pulls it strongly toward this middle region whenever it escapes. This nonlinear mean reversion effectively makes the process stationary, even though it is locally nonstationary on most of its support. We also find that the associated diffusion function is lower in the middle region and higher at both extremes—as opposed to the uniformly increasing pattern specified by the popular constant elasticity of variance (CEV) model.

This article is organized as follows. Section 1 presents the test statistic based on the unconditional information and gives its properties.

² The continuous-time process therefore has the same characterization as a discrete-time Gaussian random variable, even though its distribution is not necessarily Gaussian.

Section 2 incorporates the conditional information contained in the interest rate transitions. Section 3 describes how the basic framework can be extended to regime switching models, multivariate diffusions, and diffusions with jumps. Section 4 tests spot rate models proposed in the literature and determines a simple specification that cannot be rejected by the data. Section 5 summarizes the results and concludes. Technical assumptions and proofs are in the Appendix.

1. Testing the Parametric Specification of Diffusion Processes

1.1 Null hypothesis and test statistics

The main focus of the test is on models for the spot interest rate that belong to the class of (1) Markov processes of (2) the univariate diffusion type, which are (3) strictly stationary. The Markov property (property 1) is fundamental for what follows. When a model does not yield Markov dynamics, it is sometimes possible to redefine the state space so that the Markov property holds [see e.g., Cox and Miller (1965, pp. 18–19)]. Property 3 in particular precludes the μ and σ^2 functions from depending directly on time, in addition to being functions of the state X .³ Strict stationarity means that the joint distributions of the process satisfy for every m , every $0 < t_1 < \dots < t_m < \infty$ and every x_1, \dots, x_m in the state space: $P(X_{t_1} \leq x_1, \dots, X_{t_m} \leq x_m) = P(X_{t_1+\Delta} \leq x_1, \dots, X_{t_m+\Delta} \leq x_m)$. In particular, applying this to $m = 1$ and 2, the transition density of the process (the conditional density of $X_{t+\Delta}$ given X_t) can depend on Δ but not on t . And the process admits a stationary marginal density.⁴ Section 4 shows how to relax property 2 to cover multivariate diffusions and diffusions with jumps, and property 3 to cover regime switching models.

We further restrict attention (property 4) to models for the spot interest rate such that zero and infinity are unattainable in finite expected time, starting from any point in the interior of the state space $(0, \infty)$. We finally require (property 5) that classical asymptotic theory be applicable to the discrete data generated by this continuous-time process, that is, that the discrete data be mixing at a sufficiently fast rate. We give sufficient conditions on the drift and diffusion in the

³ "Arbitrage-free" models of the term structure [e.g., Ho and Lee (1986), Hull and White (1990)] make some or all the parameters functions of time. They are not meant to describe the time-series properties of the short-term interest rate—which is the focus here—but rather force the derivative pricing model to fit at a given instant the underlying term structures of bond prices, volatilities, caps, etc. The functions of time change and must be refitted continually to maintain the term structures' fit.

⁴ A process can have time-homogenous transition densities and nevertheless not be stationary (for example, a Brownian motion).

Appendix to ensure that the model considered is the unique strong solution of Equation (1) and satisfies properties 1 through 5.

Suppose for now under properties 1 through 5 that the true process of the spot interest rate is the unique strong solution of Equation (1) for given “true” drift and diffusion functions $(\mu_0(\cdot), \sigma_0^2(\cdot))$. Consider then a specific parametrization, that is, a joint parametric family:

$$P \equiv \{(\mu(\cdot, \theta), \sigma^2(\cdot, \theta)) / \theta \in \Theta\} \quad (3)$$

where Θ is a compact subset of R^K . An example is the Cox, Ingersoll, and Ross (1985) model where $P \equiv \{(\mu(x, \theta), \sigma^2(x, \theta)) = (\beta(\alpha - x), \sigma^2 x) / \theta \equiv (\alpha, \beta, \sigma^2) \in \Theta\}$. The question to be addressed is: Are there values of the parameters in Θ for which this parametric model is an acceptable representation of the true process, that is, do the functions $(\mu_0(\cdot), \sigma_0^2(\cdot))$ belong to the parametric space P ? Formally, our null and alternative hypotheses are

$$\begin{cases} H_0: \exists \theta_0 \in \Theta / \mu(\cdot, \theta_0) = \mu_0(\cdot) \text{ and } \sigma^2(\cdot, \theta_0) = \sigma_0^2(\cdot) \\ H_1: (\mu_0(\cdot), \sigma_0^2(\cdot)) \notin P \end{cases} \quad (4)$$

Except in special cases, it is quite difficult to estimate directly the drift and diffusion functions. While the most common approach in the literature,⁵ discretization-based methods encounter many problems: the discrete scheme is only an approximation to the continuous-time model,⁶ and in general the first and second conditional moments of the data generated by the model [Equations (1) and (2)] over discrete time intervals are not given by μ and σ^2 , respectively.⁷ The approximation is valid only as the time interval shrinks to zero. It may be difficult to justify for monthly, weekly, or even daily observations of financial time series: their intraday volatility is often substantial. So while the functions μ and σ^2 may be correctly specified by Equation (2) the discrete estimates obtained under the approximation that daily observations represent a continuous record of observations would fail to reflect this volatility. In light of this problem, one possible option would be to collect data sampled very frequently. However, moving to transaction data, or other forms of high-frequency observations, introduces microstructure issues that then have to be addressed: dis-

⁵ See Melino (1994) for a review of the empirical literature.

⁶ The convergence of discrete approximations to the continuous-time model has been studied in the finance literature by He (1990), Nelson (1990), and Nelson and Ramaswamy (1990). The approximation can only be made exact in a few cases [typically when the likelihood function is known in closed form, see Wong (1964) for a list].

⁷ For example, unless Equation (3) specifies a linear drift function, the conditional mean of the process at date s given where it was at date t depends on *both* the μ and σ functions.

creteness of price and therefore interest rate changes, price jumping from the bid to the ask, asynchronous trading, etc. The diffusion model may not any longer be an adequate model for these data or, at least, these effects would need to be modeled explicitly.

For these reasons it is difficult to envision a direct way of testing Equation (4). We will be looking for a characterization of the process [Equation (1)] equivalent to Equation (3), but which relies on quantities that can actually be estimated under the constraints imposed by the discrete data. Under the assumptions made, the μ and σ^2 functions of the process will characterize uniquely its marginal (or unconditional) and transitional (or conditional) densities over discrete time intervals. The joint parametrizations for μ and σ^2 adopted in the literature imply specific forms for the densities of the process. For example, the Ornstein-Uhlenbeck process $dX_t = \beta(\alpha - X_t)dt + \gamma dW_t$ specified by Vasicek (1977) generates Gaussian marginal and transitional densities. The square-root process $dX_t = \beta(\alpha - X_t)dt + \gamma X_t^{1/2} dW_t$ used by Cox, Ingersoll, and Ross (1985) yields a gamma marginal and noncentral χ^2 transitional densities [Feller (1951)].

More generally, any parametrization P of μ and σ^2 corresponds to a parametrization of the marginal and transitional densities:

$$\Pi \equiv \{(\pi(\cdot, \theta), p(\cdot, \cdot | \cdot, \cdot, \theta)) / (\mu(\cdot, \theta), \sigma^2(\cdot, \theta)) \in P, \theta \in \Theta\} \quad (5)$$

where $\pi(x, \theta)$ is the marginal density at x and $p(s, y | t, x, \theta)$ is the transition probability density from x at time t to y at time s . This is the conditional density that $X_s = y$ given $X_t = x$. While the direct estimation of μ and σ^2 with discrete data is problematic, the estimation of the densities explicitly take into account the discreteness of the data. The basic idea of this article is to use the mapping between the drift and diffusion on the one hand, and the marginal and transitional densities on the other, to test the model's specification.

We start by concentrating on the marginal density. The marginal density corresponding to the pair (μ, σ^2) is⁸

$$\pi(x, \theta) = \frac{\xi(\theta)}{\sigma^2(x, \theta)} \exp \left\{ \int_{x_0}^x \frac{2\mu(u, \theta)}{\sigma^2(u, \theta)} du \right\} \quad (6)$$

where the process is distributed on $D = (\underline{x}, \bar{x})$ with $-\infty \leq \underline{x} < \bar{x} \leq +\infty$ [for example, our interest rate process has $D = (0, +\infty)$]. The choice of the lower bound of integration in the interior of D is irrelevant. It is absorbed in the normalization constant $\xi(\theta)$ determined to ensure that the density integrates to one.

⁸ This equation for the density follows easily from the forward Kolmogorov equation [e.g., Karlin and Taylor (1981, 15.6.22)].

Define Π_M to be the space of density functions of the form of Equation (6) corresponding to pairs (μ, σ^2) in P , $\Pi_M \equiv \{\pi(\cdot, \theta) / (\mu(\cdot, \theta), \sigma(\cdot, \theta)) \in P, \theta \in \Theta\}$, and let the true marginal density of the process be $\pi_0(x) \equiv (\xi_0/\sigma_0^2(x)) \exp \left\{ \int_{x_0}^x (2\mu_0(u)/\sigma_0^2(u)) du \right\}$. Formally, we test in this section the null versus alternative hypothesis that

$$\begin{cases} H_{M0}: \exists \theta_0 \in \Theta / \pi(\cdot, \theta_0) = \pi_0(\cdot) \\ H_{M1}: \pi_0(\cdot) \notin \Pi_M. \end{cases} \quad (7)$$

It is necessary that H_{M0} be true for H_0 to be true. If the true density $\pi_0(\cdot)$ were known, we could simply check to see if it belonged to the proposed parametric class. Since it is unknown, we must estimate it, and do so with an estimator that does not already assume that the null hypothesis is correct (otherwise there is obviously no way of testing it). We use for that purpose a nonparametric estimator—that is, free of all parametric assumptions regarding μ and σ^2 —which will converge to the true density whether or not the parametric model [Equation (3)] is correctly specified. Now consider a parametric estimator of the implied density $\pi(\cdot, \theta_0)$. It will converge to the true density only if the model is correctly specified. Therefore the parametric and nonparametric density estimators should be close together if the parametric model is correct, and far from each other otherwise. A measure of distance M between the two density estimates provides a natural statistic to test the null hypothesis of correct parametric specification.⁹ We suggest to test H_0 versus H_1 using the distance measure between the densities:

$$\begin{aligned} M &\equiv \min_{\theta \in \Theta} \int_{\underline{x}}^{\bar{x}} (\pi(u, \theta) - \pi_0(u))^2 \pi_0(u) du \\ &= \min_{\theta \in \Theta} E [(\pi(X, \theta) - \pi_0(X))^2]. \end{aligned} \quad (8)$$

The distance M weighs the difference between the parametric and nonparametric estimators according to their relevance, putting more weight on values of the process more likely to appear [$\pi_0(u)$ high]. Similarly when the density is very low, that is, for interest rate regions not likely to be visited, differences in the true density and the implied parametric density are not penalized heavily (other distance measures could be used as well). From the discussion above, under the null

⁹ Comparing different types of estimators of a same quantity goes back to Hausman (1978) in the context of parameters of simultaneous equations. Here we must use a nonparametric estimator because no consistent parametric estimator is available if the model is misspecified. See also Bickel and Rosenblatt (1973).

Table 1

	Under the null (parametric model correctly specified)	Under the alternative (parametric model misspecified)
Parametric density estimator	Consistent	Inconsistent
Nonparametric density estimator	Consistent	Consistent
Distance (parametric, nonparametric)	Approximately zero	Large

hypothesis M is small, while it is large under the alternative (Table 1).

The proposed test statistic is the (properly normalized) sample analog¹⁰ of Equation (8):

$$\widehat{M} \equiv n b_n \min_{\theta \in \Theta} \frac{1}{n} \sum_{i=1}^n (\pi(r_i, \theta) - \widehat{\pi}_0(r_i))^2 \quad (9)$$

where $\widehat{\pi}_0(\cdot)$ is a nonparametric estimator of the density function with bandwidth b_n and $n b_n$ is a normalizing constant. The null hypothesis is therefore rejected when the test statistic \widehat{M} is large enough. The test statistic has a minimum-distance flavor. It considers the scenario that is the most favorable to the parametric model, to maximize power, evaluating the distance between the densities at the “best possible” parametric estimator:

$$\widehat{\theta}_M \equiv \arg \min_{\theta \in \Theta} \frac{1}{n} \sum_{i=1}^n (\pi(r_i, \theta) - \widehat{\pi}_0(r_i))^2. \quad (10)$$

The identification of the parameter vector is discussed in the Appendix (see assumption A0). Before investigating the distribution of the test statistic and its other properties, we next describe the nonparametric estimator $\widehat{\pi}_0(\cdot)$ of the density function.

1.2 Nonparametric estimation of the density

The data used to form these density estimators consists of discrete observations of the short interest rate $\{r_1, \dots, r_n\}$ sampled at interval Δ (for example $\Delta = 1$ day). These discrete data are used to estimate the continuous density of the process without replacing the continuous-time model with a discrete approximation. The asymptotic properties of the estimators are derived for an expanding sampling period, that is, the interest rate is observed over an increasingly long period of time. Our method does not require that the sampling interval

¹⁰ Any other measure of the integral in Equation (2.6) could be used: for example a Riemann sum $\frac{1}{j} \sum_{j=1}^j (\pi(x_j, \theta) - \widehat{\pi}_0(x_j))^2 \widehat{\pi}_0(x_j) \{x_{j+1} - x_j\}$ where the x_j 's form a grid on (x, \bar{x}) .

Δ be small: for example weekly or monthly data could be used as well.

The nonparametric kernel estimator of the marginal density is given by

$$\hat{\pi}_0(u) \equiv \frac{1}{n} \sum_{i=1}^n \frac{1}{b_n} K\left(\frac{u - r_i}{b_n}\right) \quad (11)$$

where $K(\cdot)$ is the kernel function and b_n the bandwidth. Silverman (1986) provides an introduction to kernel estimation, while Scott (1992) contains more details. One can think of Equation (11) as being a “smooth histogram.” Regularity conditions and restrictions on the choice of the kernel and bandwidth are given in the Appendix.

1.3 Distribution of the test statistics

It is shown in the Appendix that under H_0 , the estimated parameter $\hat{\theta}_M$ has the distribution

$$n^{1/2} \left\{ \hat{\theta}_M - \theta_0 \right\} \xrightarrow{d} N(0, \Omega_M) \quad (12)$$

with Ω_M and a consistent estimator given in the Appendix.

The test statistic \hat{M} is distributed as

$$b_n^{-1/2} \left\{ \hat{M} - E_M \right\} \xrightarrow{d} N(0, V_M) \quad (13)$$

with E_M, V_M given in the Appendix.

To test the null hypothesis at the level α , we would therefore use the critical region:

$$\text{reject } H_0 \text{ when } \hat{M} \geq \hat{c}(\alpha) \equiv \hat{E}_M + b_n^{1/2} z_{1-\alpha} / \left\{ \hat{V}_M \right\}^{1/2} \quad (14)$$

where estimators of E_M and V_M , which can be plugged into (13), are given by

$$\begin{cases} \hat{E}_M \equiv \left(\int_{-\infty}^{+\infty} K^2(x) dx \right) \left(\frac{1}{n} \sum_{i=1}^n \hat{\pi}_0(r_i) \right) \\ \hat{V}_M \equiv 2 \left(\int_{-\infty}^{+\infty} \left\{ \int_{-\infty}^{+\infty} K(u)K(u+x) du \right\}^2 dx \right) \left(\frac{1}{n} \sum_{i=1}^n \hat{\pi}_0^3(r_i) \right) \end{cases} \quad (15)$$

This test is locally strictly unbiased. Any other consistent estimates of E_M and V_M could be used. Set $z_{1-\alpha} = 1.64$ to obtain a test at the 95 percent level. For the Gaussian kernel $K(u) = \exp(-u^2/2)/\sqrt{2\pi}$, the two kernel constants are $(\int_{-\infty}^{+\infty} K^2(x) dx) = 1/(2\sqrt{\pi})$ and $(\int_{-\infty}^{+\infty} \{\int_{-\infty}^{+\infty} K(u)K(u+x) du\}^2 dx) = 1/(2\sqrt{2\pi})$. The choice of the bandwidth h_n is discussed in the Appendix (see Assumption A5). This completes the description of the marginal-based test.

2. Exploiting the Information Contained in the Transitions of the Process

The stationary marginal density of the process does not summarize all the information available in the data. For our specification test, it is clear that a rejection based on the marginal density (\hat{M} large) already invalidates the candidate parametrization of the drift and the diffusion, and we need not go any further. While the empirical results of this article suggest that it is unlikely in practice, we could possibly be unable to reject an inadequate parametrization based on the marginal density alone. For that reason, it is worthwhile to examine the transitions of the process over finite intervals of time, corresponding to the sampled data (say, daily). Hansen and Scheinkman (1995) proposed to estimate diffusion processes based on moment conditions that must be satisfied over time intervals by arbitrary functions. Their method, along with an extension of the method of Ait-Sahalia (1992b), is implemented empirically by Conley et al. (1995). We treat the Markovian character of the process as a maintained hypothesis, so there is no need to look at transitions over time intervals longer than the sampled frequency of the data (say, 2 days when daily data are available).¹¹

We propose to exploit stationarity by combining the forward and backward equations characterizing the transitional density $p_0(s, y | t, x)$ in a way that eliminates the time derivatives of p_0 —which are unobservable with discrete data. Consider the forward Kolmogorov

¹¹ As an aside, note that a simple test of the Markovian property of the data consists of examining whether the 2-day transitions can be derived from the 1-day transitions (say $\Delta = 1$ day) according to the Chapman-Kolmogorov equation. This equation can be found in Gardiner (1990, sec. 3.2.1). In particular, note that knowledge of the 1-day transition density is enough to characterize the marginal density since we have for all n : $p(n\Delta, y | x) = \int_x^x p(\Delta, y | z)p((n-1)\Delta, z | x) dz$, which can be iterated recursively from $p(\Delta, y | z)$. Then by ergodicity $\lim_{n \rightarrow \infty} p(n\Delta, y | z) = \pi(y)$.

equation, with the natural initial condition (x and t are fixed):¹²

$$\begin{aligned} \frac{\partial p_0(s, y | t, x)}{\partial s} &= -\frac{\partial}{\partial y}(\mu(y, \theta)p_0(s, y | t, x)) \\ &\quad + \frac{1}{2} \frac{\partial^2}{\partial y^2}(\sigma^2(y, \theta)p_0(s, y | t, x)) \end{aligned} \quad (16)$$

for all y in the interior of the domain of the diffusion $D = (\underline{x}, \bar{x})$, and s such that $s > t$. The backward equation (y and s are fixed) is¹³

$$\begin{aligned} -\frac{\partial p_0(s, y | t, x)}{\partial t} &= \mu(x, \theta) \frac{\partial}{\partial x}(p_0(s, y | t, x)) \\ &\quad + \frac{1}{2} \sigma^2(x, \theta) \frac{\partial^2}{\partial x^2}(p_0(s, y | t, x)) \end{aligned} \quad (17)$$

for all x in D and t such that $0 \leq t < s$.

Unfortunately, these two equations cannot be used as such to estimate the parameters because their left-hand side contains the derivative of the transition density with respect to time. There is clearly no way to estimate this derivative without observations on interest rate changes over small intervals of time. The idea here is to work around this problem by getting rid of the time derivatives with the following trick. By stationarity $p_0(s, y | t, x) = p_0(s - t, y | 0, x) \equiv p_0(s - t, y | x)$, and therefore, $\partial p_0 / \partial s = -\partial p_0 / \partial t$. Combining the two equations then yields (with $\Delta \equiv s - t$) what we might call the “transition discrepancy”:

$$\begin{aligned} m(\Delta, y, x, \theta) &\equiv \left\{ \frac{1}{2} \frac{\partial^2}{\partial y^2}(\sigma^2(y, \theta)p_0(\Delta, y | x)) \right. \\ &\quad \left. - \frac{\partial}{\partial y}(\mu(y, \theta)p_0(\Delta, y | x)) \right\} \\ &\quad - \left\{ \mu(x, \theta) \frac{\partial}{\partial x}(p_0(\Delta, y | x)) \right\} \end{aligned}$$

¹² See e.g., Gardiner (1990, chap. 5). The forward and backward equations cannot be solved explicitly for the transition density, except in a small number of special cases [see Wong (1964) for a list]. The initial condition for the forward equation at $s = t$ is $p(s, y | s, x) = \delta(y - x)$. The boundary condition for an absorbing barrier is $p(s, y | t, x) = 0$ when y is at the barrier \underline{x} or \bar{x} . For a reflecting barrier $\mu(y, \theta)p(s, y | t, x) - (1/2)(\partial/\partial y)(\sigma^2(y, \theta)p(s, y | t, x)) = 0$ when y is at the barrier. The marginal density π is the only solution of Equation (3.1) which does not depend on time (and integrates to one), hence Equation (6).

¹³ The final condition for the backward equation at $t = s$ is $p(t, y | t, x) = \delta(y - x)$. The boundary condition for an absorbing barrier is $p(s, y | t, x) = 0$ when x is at the barrier \underline{x} or \bar{x} . For a reflecting barrier $\partial p(s, y | t, x) / \partial x = 0$ when x is at the barrier, unless $\sigma(\cdot)$ vanishes there.

$$+ \frac{1}{2} \sigma^2(x, \theta) \frac{\partial^2}{\partial x^2} (p_0(\Delta, y | x)) \} \quad (18)$$

which, for every (x, y) in D^2 and $\Delta > 0$, must be zero at $\theta = \theta_0$ under the null of correct parametric specification.¹⁴

The essential fact is that $m(\Delta, y, x, \theta_0) = 0$ must hold for every time interval Δ , not just small ones. Let Δ be the time interval between successive observations in the data (r_i, r_{i+1}) , $i = 1, \dots, n$ (for example $\Delta = 1$ day). A simple consistent method to estimate θ_0 based on the transition data for intervals of length Δ is to solve

$$T \equiv \min_{\theta \in \Theta} \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \{m(\Delta, y, x, \theta)\}^2 p_0(\Delta, y, x) dx dy \quad (19)$$

where $p_0(\Delta, y, x)$ is the joint density of observations separated by a time interval Δ (while $p_0(\Delta, y | x)$ is the conditional density).

The normalized sample analog is our transition-based test statistic:

$$\hat{T} \equiv nb_n^6 \min_{\theta \in \Theta} \frac{1}{n} \sum_{i=1}^n \{\hat{m}(\Delta, r_{i+1}, r_i, \theta)\}^2 \quad (20)$$

where $\hat{m}(\Delta, y, x, \theta)$ is analogous to Equation (18) except that the unknown joint and transition densities have been replaced by their

¹⁴ There is a link between Equation (3.3) and the second moment condition in Hansen and Scheinkman (1995). As they show, their condition is equivalent to the fact that the conditional expectation operator and the infinitesimal generator commute [for a proof of this fact, see e.g., Revuz and Yor (1988)]. Our condition is also equivalent to this commutativity property. Indeed we have just shown that $m(\Delta, y, x, \theta_0) = 0$ for all x and y in D , so if we take an arbitrary twice-continuously differentiable function $\varphi(y, x)$ in $L^2(D^2)$:

$$\begin{aligned} 0 &= \int \int m(\Delta, y, x, \theta_0) \varphi(y, x) dy dx \\ &= \int \int \left\{ \frac{1}{2} \frac{\partial^2}{\partial y^2} (\sigma^2(y, \theta_0) p_0(\Delta, y | x)) - \frac{\partial}{\partial y} (\mu(y, \theta_0) p_0(\Delta, y | x)) \right\} \varphi(y, x) dx dy \\ &\quad - \int \int \left\{ \mu(x, \theta_0) \frac{\partial}{\partial x} (p_0(\Delta, y | x)) + \frac{1}{2} \sigma^2(x, \theta_0) \frac{\partial^2}{\partial x^2} (p_0(\Delta, y | x)) \right\} \varphi(y, x) dx dy \\ &= \int \int \left\{ \frac{1}{2} \sigma^2(y, \theta_0) \frac{\partial^2 \varphi(y, x)}{\partial y^2} + \mu(y, \theta_0) \frac{\partial \varphi(y, x)}{\partial y} \right\} p_0(\Delta, y | x) dy dx \\ &\quad - \int \int \left\{ \frac{1}{2} \frac{\partial^2}{\partial x^2} (\sigma^2(x, \theta_0) \varphi(y, x)) - \frac{\partial}{\partial x} (\mu(x, \theta_0) \varphi(y, x)) \right\} p_0(\Delta, y | x) dx dy, \end{aligned}$$

so by integrating twice by parts we recover the commutativity property.

kernel estimators:

$$\left\{ \begin{array}{l} \hat{\rho}_0(\Delta, y, x) = \left\{ \frac{1}{n} \sum_{i=1}^n \frac{1}{b_n^2} K\left(\frac{x - r_i}{b_n}\right) K\left(\frac{y - r_{i+1}}{b_n}\right) \right\} \\ \hat{\rho}_0(\Delta, y | x) = \hat{\rho}_0(\Delta, y, x) / \hat{\pi}_0(x) \end{array} \right\}. \quad (21)$$

The asymptotic distribution of the test statistic based on the transition densities is

$$b_n^{-1} \{ \hat{T} - E_T \} \xrightarrow{d} N(0, V_T) \quad (22)$$

where E_T , V_T , and their consistent estimators are given in the Appendix.

The transition-based test can be derived as in Equation (14). Additionally, it can be noted that $\hat{\theta}_T \equiv \arg \min_{\theta \in \Theta} \hat{T}$ provides a consistent (under the null of correct specification) and asymptotically normal estimator of the drift and diffusion parameters.

3. Extensions

Recent articles in the term structure literature have modeled discrete regime shifts in the spot interest rate process [e.g., Das (1994), Gray (1994), Hamilton (1988), and Naik and Lee (1993)]. These models typically posit a spot interest rate process that can shift randomly between two or more regimes: for example, a “normal” low-mean regime and an exceptional high-mean regime (e.g., 1980 to 1982 in the United States). They typically keep the same μ and σ^2 functions, but with different parameter values for each regime. This makes the process time-inhomogenous, and therefore violates property 3. The rigorous estimation of such processes is difficult.

A simpler modeling alternative can be implemented to capture some of the same economic effects, without introducing different drift and diffusion functions. A process switching randomly between, for example, two possible regimes will have a bimodal marginal density, with (1) the relative height of each mode reflecting the amount of time spent by the process in each regime, and (2) the relative peakness of each mode reflecting the volatility of the corresponding regime.

Consider the typical configuration in Figure 1 (a, b, and c) for a basic diffusion of the type in Equation (1). The density in Figure 1a is bimodal. Instead of two separate pairs (drift, diffusion) with linear drift for each regime, the regime-switching effect can be modeled by a diffusion process with a “two-regime potential” drift function (Figure 1b). The type of density in Figure 1a would be the product of a kernel estimator with a bandwidth set lower than is optimal to artificially

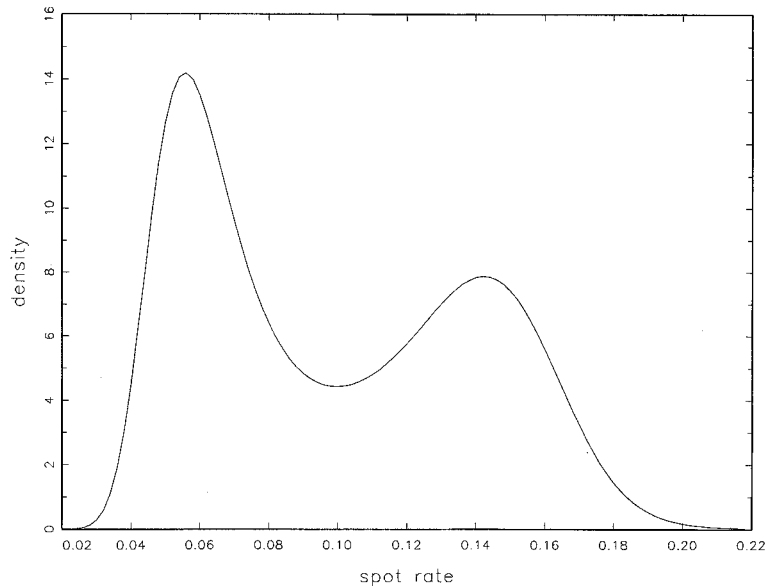


Figure 1a
Bimodal density of a two-regime spot rate model
 This figure plots a typical marginal density $r \mapsto \pi_0(r)$ generated by a two-regime spot rate model.

emphasize the multimodality (i.e., the multiplicity of regimes). The specification of the diffusion function in Figure 1c is a simple CEV function, for illustrative purposes. This specification of this model is as readily testable as any other diffusion of the type in Equation (1).

In other words, instead of two separate linear drift functions that result in a discontinuous global drift, we could specify a single continuous but nonlinear drift function that preserves time-homogeneity. The mean time spent in each regime is easily computed, as well as the probability of switching from one regime to the other [see Gardiner (1990:9.1)]. These can then be used to calibrate the model to the empirical observations on regime switches.

We finally note that the test can be extended to cover multivariate diffusions and jump-diffusion models [e.g., Heston (1993), Das (1994)]. Indeed, both classes of models are characterized by forward and backward equations that are straightforward extensions of Equations (16) and (17). The extension to jump diffusion presents no fundamental difficulty. However, the extension to multivariate diffusions is likely to be more difficult to implement in practice due to the “curse of dimensionality.” This refers to the fact that nonparametric kernel estimators converge at a speed that decreases as the dimensionality of the problem increases, in contrast to parametric estimators which

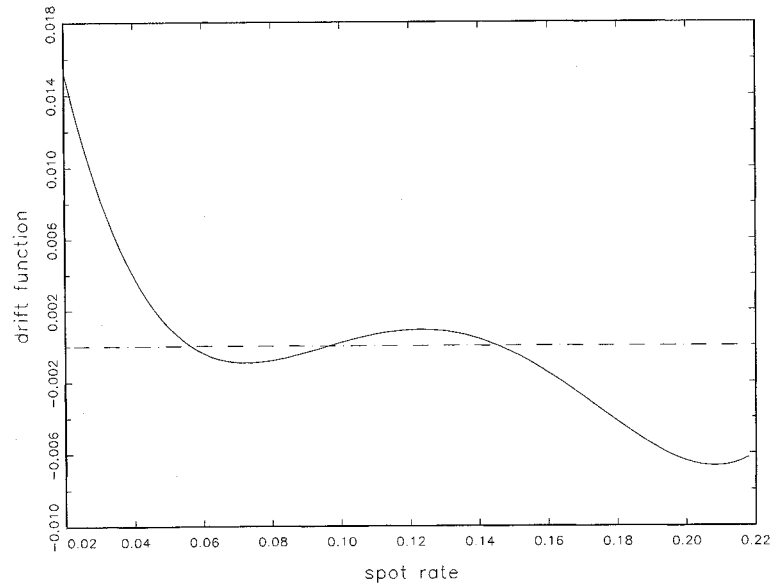


Figure 1b
Drift function of a two-regime model
 This figure plots the two-potential drift function which, along with the diffusion function in Figure 1c, defines from Equation (6) the density in Figure 1a.

always converge at the speed root n . Estimating nonparametrically higher-dimensional densities therefore requires larger sample sizes.

4. Empirical Tests of Spot Rate Models

4.1 The data

The short-term rate used is the 7-day Eurodollar deposit spot rate, bid-ask midpoint. The $n = 5505$ observations are daily from 1 June 1973 to 25 February 1995. Weekends and holidays have not been treated specifically (Monday is taken as the next day after Friday). Whereas weekend effects have been documented for stock prices [e.g., French and Roll (1986)], there does not seem to be a conclusive weekend effect in money market instruments.¹⁵ Table 2 reports the descriptive statistics. Dickey-Fuller nonstationarity tests have been conducted, and the presence of a unit root is rejected, both for the full period and the subperiod 1983 to 1994. Since the test is known

¹⁵ The ratio of weekend to weekday mean and standard deviation of S&P 500 returns are, respectively, -0.652 and 1.311 between 2 June 1973 and 30 December 1994. The corresponding numbers are 1.004 and 1.003 for the 7-day Eurodollar rate.

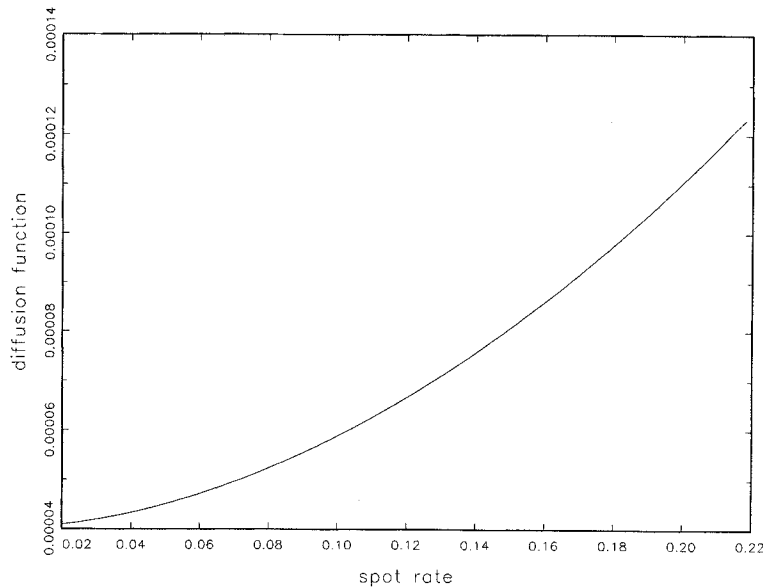


Figure 1c

Diffusion function of a two-regime model

This figure plots the CEV diffusion function which, when combined with the drift function in Figure 1b, gives rise to the density in Figure 1a.

to have low power, even a slight rejection means that existence of a unit root is unlikely.

A time-series plot of the data is provided in Figure 2. Due to the shift in monetary policy, the 1980 to 1982 years are characterized by substantially higher interest rate levels than the rest of the sample period. There exists evidence¹⁶ that the parameters of a linear drift CEV diffusion are different during the 1980 to 1982 period than the rest of the sample [e.g., Bliss and Smith (1994)]. More precisely, the evidence means that this particular parametrization is not time-homogenous. For example, the mean α of the process with drift $\mu(r, \theta) = \beta(\alpha - r)$ estimated over 1980 to 1982 is significantly higher than the mean estimated on the rest of the sample. As we shall see, a better functional dependence of the drift on the spot rate—with no time-varying parameters—can capture the dynamics of the process since the shift is associated with higher interest rate levels. Misspecified models, like linear drift with CEV diffusion, will mask nonlinearities as changes in parameters.

Two additional series have also been used to check the robustness

¹⁶ Typically by Chow tests on a discrete approximation with monthly data.

Table 2
Descriptive statistics

Source	Bank of America 7-day Eurodollar (deposit rate midpoint bid-ask)	
Frequency	Daily	
Sample period	1 June 1973–25 February 1995	
Sample size	5505 observations	
Type	Continuously compounded yield-to-maturity (annualized rate)	
	Spot interest rate	First difference of spot interest rate
Mean	0.08362	-0.000035
standard deviation	0.03591	0.004063
monthly ρ_1	0.9389	0.02136
ρ_2	0.8785	-0.00689
ρ_3	0.8300	-0.01658
ρ_4	0.8014	0.00242
ρ_5	0.7783	0.00858
ρ_6	0.7715	0.01573
ρ_7	0.7361	0.00056
Augmented daily Dickey-Fuller	-2.60	
H_0 : Nonstationary	Reject at 90% (critical value = -2.57)	

In the table, the coefficient ρ_i designates the autocorrelation of the series at lag i . The augmented Dickey-Fuller test statistic is computed as $\hat{\tau}_\mu = \hat{\phi}/\text{ase}(\hat{\phi})$ in the model: $\Delta r_t = \mu + \phi r_{t-1} - \sum_{j=1}^p \phi_j \Delta r_{t-j} + u_t$, with $p = 5$ lags [see e.g., Harvey (1993: sec. 5.4.)].

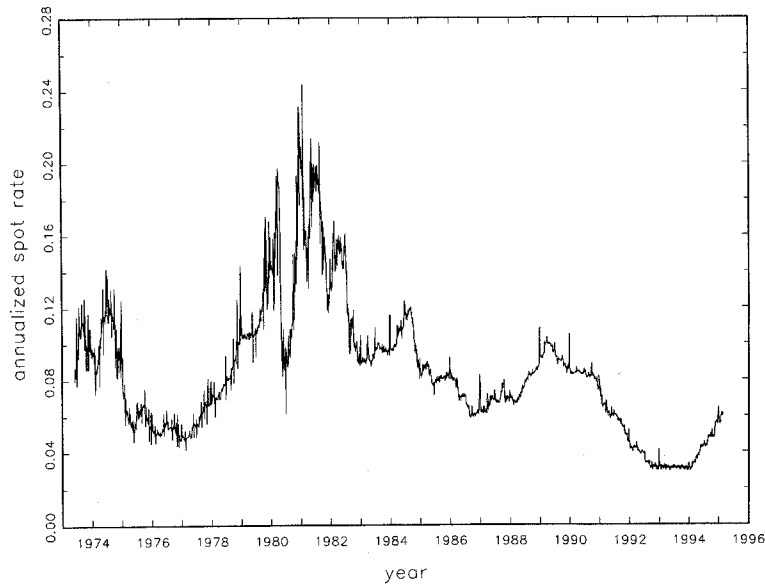


Figure 2
Time series of the 7-day Eurodollar rate

of the results. The other proxies for the spot rate are the overnight yield for federal funds, computed daily by the Federal Reserve Bank of New York (source: Telerate Systems, Inc.), and the 1-month continuously compounded bond equivalent yield on Treasury bills (source: Bank of America). All three series produce qualitatively similar results, with the provision that 1-month rates tend to exhibit substantially less short-term volatility than 1-week rates, which in turn are more stable than overnight rates.¹⁷

Choosing a 7-day rate—such as the 7-day Eurodollar—as the underlying factor for pricing derivatives is a necessary compromise between (1) literally taking an “instantaneous” rate that does not already embed the result of a pricing operator, and (2) avoiding some of the spurious microstructure effects associated with overnight rates. For example, the second Wednesday settlement effect in the federal funds market creates a spike in the raw federal funds data that has to be smoothed [see Hamilton (1996)]. More generally short-term supply and demand effects in overnight markets can create excess volatility at the short end of the yield curve that is often irrelevant for the rest of the curve.

4.2 Parametric specifications of the short rate process

The drift-diffusion parametrization considered for the empirical test is

$$\begin{cases} \mu(r, \theta) = \alpha_0 + \alpha_1 r + \alpha_2 r^2 + \alpha_3 / r \\ \sigma^2(r, \theta) = \beta_0 + \beta_1 r + \beta_2 r^{\beta_3} \end{cases} \quad (23)$$

The parametrization [Equation (23)] nests the single-factor diffusion models considered in Table 3. This general parametric model allows for departures from linearity in the drift and at the same time sufficient variability in the shapes of the diffusion function. The parameter vector is $\theta \equiv (\alpha_0, \alpha_1, \alpha_2, \alpha_3, \beta_0, \beta_1, \beta_2, \beta_3)'$. The implied marginal density is given by Equation (6).

Natural restrictions have to be imposed on the parameter values to satisfy the requirements of properties 1 through 5 from Section 2, and are derived in the Appendix. They are

$$\begin{aligned} &\beta_0 \geq 0 \text{ (and } \beta_2 > 0 \text{ if } \beta_0 = 0 \text{ and } 0 < \beta_3 < 1, \\ &\text{or } \beta_1 > 0 \text{ if } \beta_0 = 0 \text{ and } \beta_3 > 1) \end{aligned} \quad (24a)$$

$$\begin{aligned} &\beta_2 > 0 \text{ if either } \beta_3 > 1 \text{ or } \beta_1 = 0, \text{ and } \beta_1 > 0 \\ &\text{if either } 0 < \beta_3 < 1 \text{ or } \beta_2 = 0 \end{aligned} \quad (24b)$$

¹⁷ Duffee (1994) documents the idiosyncratic variation of several short maturity yields and recommends the adoption of Eurodollar yields instead of Treasury bill yields for the purpose of calibrating term structure models.

Table 3
Tests of parametric specifications of the continuous-time spot rate process

Drift function $\mu(x, \theta)$	Diffusion function $\sigma^2(x, \theta)$	Reference	Test statistic \widehat{M}	95% critical value	95% result
$\alpha_0 + \alpha_1 x$	β_0	Vasicek (1977) (0 attainable)	15.09	6.32	Reject
$\alpha_0 + \alpha_1 x$	$\beta_1 x$	Cox, Ingersoll, and Ross (1985) Brown and Dybvig (1986) Gibbons and Ramaswamy (1993) Pearson and Sun (1994)	42.01	6.32	Reject
$\alpha_0 + \alpha_1 x$	$\beta_2 x^2$	Brennan and Schwartz (1979) Courtadon (1982)	129.49	6.32	Reject
$\alpha_0 + \alpha_1 x$	$\beta_2 x^{\beta_3}$	Chan et al. (1992) (0 unattainable: $\beta_3 \geq 1$) Figures 3a,b,c	38.56	6.32	Reject
$\alpha_0 + \alpha_1 x$ $+ \alpha_2 x^2 + \alpha_3/x$	$\beta_2 x^{\beta_3}$	General drift, CEV diffusion	6.79	6.32	Reject
$\alpha_0 + \alpha_1 x$ $+ \alpha_2 x^2 + \alpha_3/x$	$\beta_0 + \beta_1 x + \beta_2 x^{\beta_3}$	General parametric model 1973–1995: Figures 4a,b,c 1983–1995: Figures 5a,b,c		6.32	Cannot reject
			0.350		
			0.289		

Table 3 reports the value \widehat{M} of the M test statistic and the result of the test for a sample of the models considered.

$$\alpha_2 \leq 0 \text{ and } \alpha_1 < 0 \text{ if } \alpha_2 = 0 \tag{24c}$$

$$\alpha_3 > 0 \text{ and } 2\alpha_3 \geq \beta_0 \geq 0, \text{ or } \alpha_3 = 0, \alpha_0 > 0, \beta_0 = 0, \beta_3 > 1$$

$$\text{and } 2\alpha_0 \geq \beta_1 > 0 \tag{24d}$$

Equation (24a) (resp. (24b)) is necessary for σ_2 to be positive in the neighborhood of the zero (resp. infinity) boundary. Equation (24c) ensures that the drift is mean-reverting at high interest rate values. It is sufficient here to make infinity unattainable. Equation (24d) guarantees that zero is unattainable.

4.3 Results of the specification test

The results of the test are in Table 3. First, models that are strictly more parsimonious than Equation (23) are rejected even by the marginal

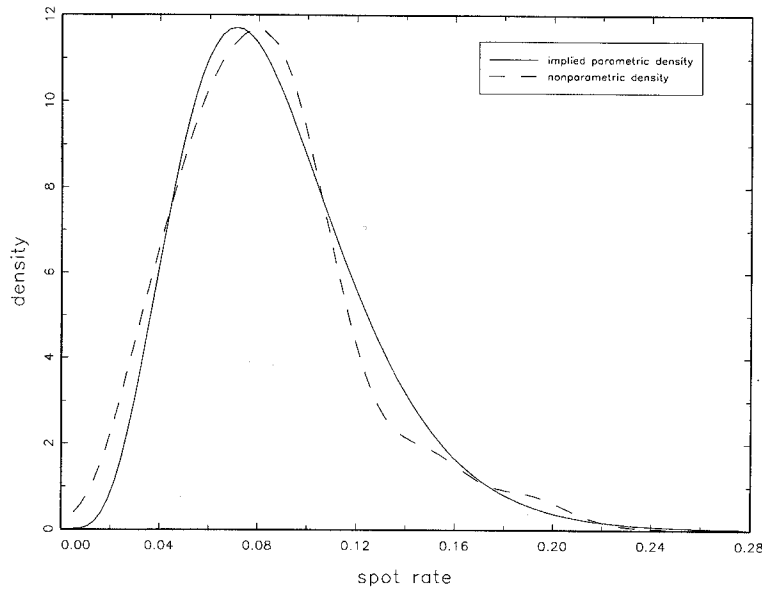


Figure 3a
Density comparison with linear drift and CEV diffusion, 1973–1995

This figure plots the nonparametric estimate $r \mapsto \hat{\pi}_0(r)$ given by Equation (11) and the parametric estimate $r \mapsto \pi(r, \hat{\theta}_M)$ evaluated at the parameter vector of Equation (10). The parameter values are given in Table 4. The parametric estimator is for the model [Equations (23) and (24)] under the additional restrictions $\alpha_2 = \alpha_3 = 0$ and $\beta_0 = \beta_1 = 0$. This model is rejected by the test of Equation (13). From Equation (6), this parametric density is generated by the drift and diffusion functions reported in Figures 3b and 3c, respectively.

density-based test. Second, the estimated μ and σ_2 functions of the spot rate have features that had not been previously documented. The ability to reject nontrivial parametric models such as linear drift with CEV diffusion against a nonparametric alternative suggests that the power of the test is significant at the sample sizes considered.

Figure 3 (a, b, and c) corresponds to the model obtained under the restriction that the drift be linear mean-reverting ($\alpha_2 = \alpha_3 = 0$) with a CEV diffusion ($\beta_0 = \beta_1 = 0$) under Equation (24). This model is rejected at the 95 percent level. The rejection is not surprising given the nonparametric shape of the diffusion found in Ait-Sahalia (1992b) when the drift is linear. A CEV diffusion function constrains the volatility to be uniformly increasing. In a less constrained model the diffusion function is found to be nonmonotonic, whether the drift is linear [see Ait-Sahalia (1992b)] or not (Figure 4c).

We find strong evidence in the data that CEV diffusions are not a perfect match for linear drifts. There are two reasons for this. First, the behavior of the diffusion for large values of the spot rate constrains the parameter β_3 . The shape of the marginal density requires a rel-

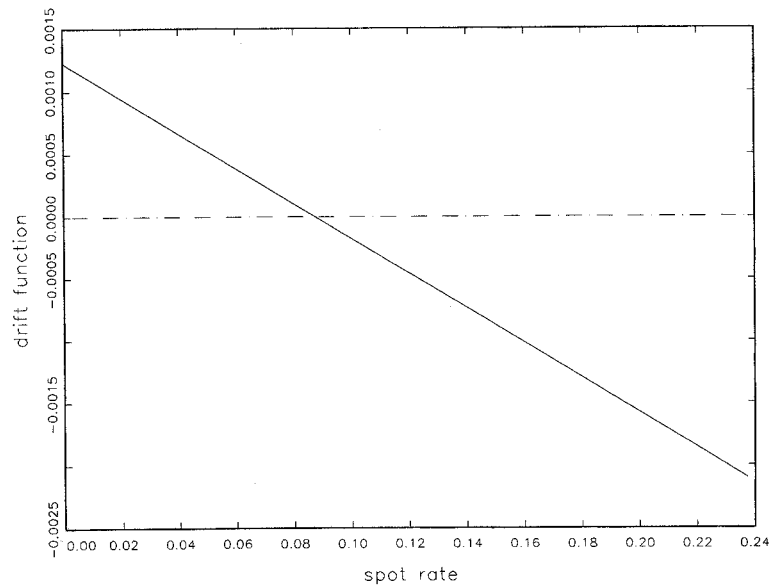


Figure 3b
Estimated linear drift, 1973–1995

This figure plots the drift function $r \mapsto \mu(r, \hat{\theta}_M)$ corresponding to the parametric density $r \mapsto \pi(r, \hat{\theta}_M)$ in Figure 3a.

atively low rate of growth of the diffusion as the interest rate grows (β_3 small), because of the slow mean-reversion effect imposed by a linear drift. A rapidly increasing diffusion function would generate a probability of large values, given the linearity of the drift, that would be higher than observed in the data. The second constraint is due to the unattainability of zero. This, on the contrary, imposes a fast rate of decay of the diffusion as interest rates become close to zero (β_3 large). The CEV specification obviously has β_3 constant, and these two effects are incompatible in the data.

This incompatibility is exemplified by the comparison of the Vasicek (1977), Cox, Ingersoll, and Ross (1985), and Courtadon (1982) models. In the Vasicek model ($\beta_3 = 0$), zero is attainable, and the model is easily rejected but by a smaller margin than the Courtadon model ($\beta_3 = 2$). The best fit is provided by the Cox, Ingersoll, and Ross model ($\beta_3 = 1$), which is a compromise between these two competing effects.

4.4 A nonlinear spot rate model

The empirical evidence so far suggests that misspecification of the models in the literature is caused jointly by the linearity of the drift

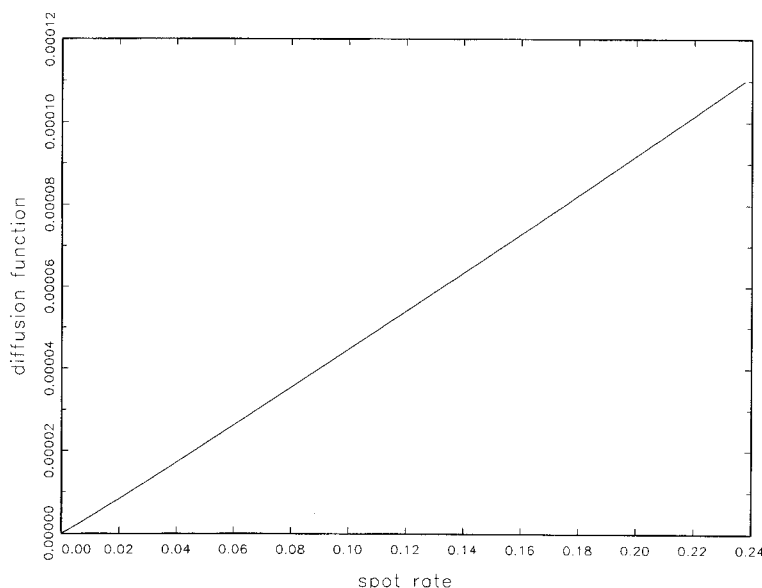


Figure 3c
Estimated CEV diffusion, 1973–1995

This figure plots the diffusion function $r \mapsto \sigma^2(r, \hat{\theta}_M)$ corresponding to the parametric density $r \mapsto \pi(r, \hat{\theta}_M)$ in Figure 3a.

and the CEV specification of the diffusion. We now relax these two assumptions and examine the features of the resulting model. Figure 4 (a, b, and c) plot, respectively, the density (π), drift (μ), and diffusion (σ^2) functions corresponding to the most parsimonious model that cannot be rejected at the 95 percent level. The drift and diffusion are as Equation (23), unconstrained other than Equation (24). The first interesting feature of Figure 4b is that in the middle region of the rate spectrum (4 to 17 percent) the drift is essentially zero. In this region, the spot rate is locally nonstationary as it behaves like a random walk, with no drift and a nonzero diffusion component. This explains why it is difficult, on relatively short time periods, to reject the existence of a unit root in time series of spot rates. This finding is consistent with the insights of the literature on vector autoregressions in macroeconomics, where it is common to model high-frequency interest rate data as nonstationary [e.g., Stock and Watson (1993, p. 800)].

However, the second finding is that the nonlinear mean-reverting drift pulls the rate back strongly into this middle region whenever it wanders outside (for example, below 4 percent in 1993 and early 1994 or above 17 percent in 1981 to 1982). This makes the process globally stationary. Overall, the process estimated from the data is very

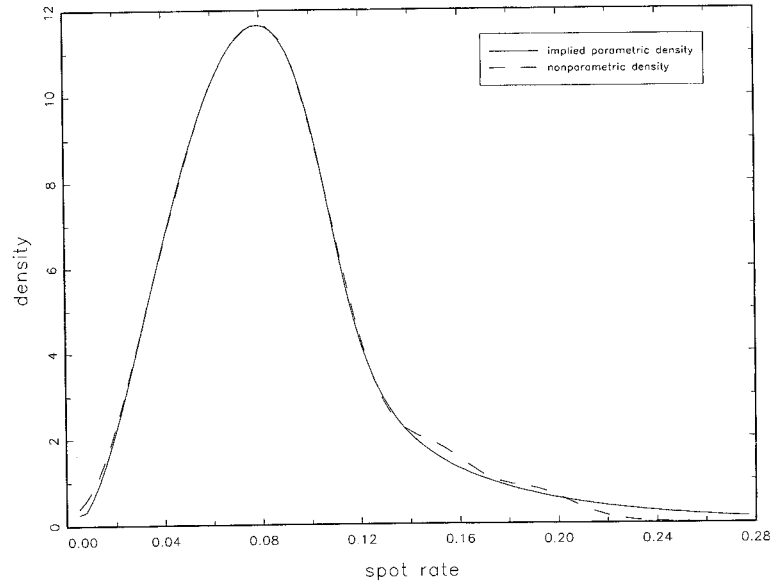


Figure 4a
Density comparison with nonlinear drift and diffusion, 1973–1995

This figure plots the nonparametric estimate $r \mapsto \hat{\pi}_0(r)$ given by Equation (11) and the parametric estimate $r \mapsto \pi(r, \hat{\theta}_M)$ evaluated at the parameter vector of Equation (10). The parameter values can be found in Table 4. The parametric estimator is for the nonlinear model [Equations (23) and (24)] under no additional restrictions. This model is not rejected by the test of Equation (13).

similar to the target band model used in the exchange rate literature: a Brownian motion with two reflecting barriers. We would obviously expect a different result in a hyperinflationary economy.

The diffusion function in Figure 4c is larger when far away from the central region (4 to 17 percent). It has long been thought that the volatility of the spot rate should increase with the level of the rate: beyond avoiding negative nominal rates, this was one of the rationales for the Cox, Ingersoll, and Ross specification compared to Vasicek's. The finding here is that the spot rate is more volatile—albeit less so—when below its long-term mean. This documents yet another aspect of the process. Loosely speaking, markets may become more nervous outside the central region, at both ends of the interest rate spectrum. Market participants may expect the Federal Reserve to credibly return the short-term interest rate to its middle range at some point, but are uncertain about the precise timing of the intervention. This rather speculative interpretation would also be consistent with the strong pull-back drift of Figure 4b at either end of the spectrum.

We also report results for the 1983 to 1995 subsample [Figure 5 (a, b, and c)]. The shapes of the drift and diffusion functions are remarkably

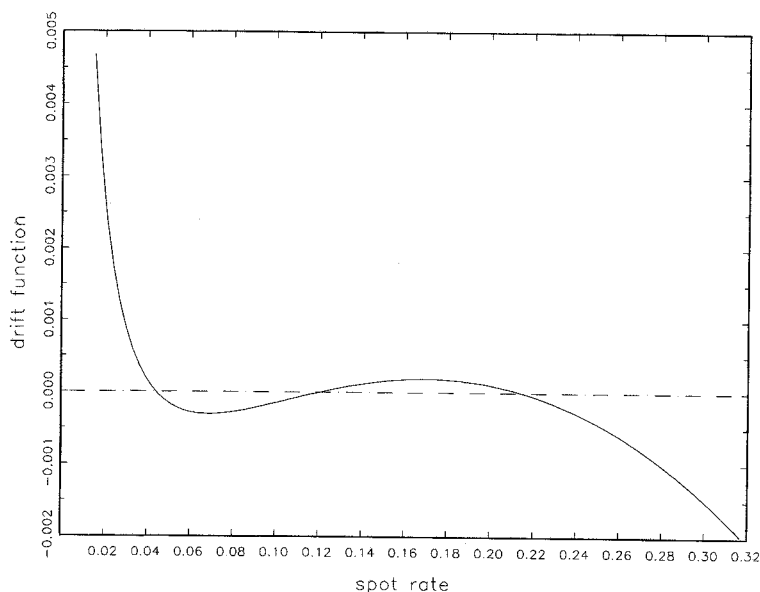


Figure 4b
Estimated nonlinear drift, 1973–1995

This figure plots the drift function corresponding to the parametric density in Figure 4a. When the spot rate is far away from its mean the estimated drift mean-reverts strongly but is essentially zero in that middle region. This finding is consistent with interest rates often appearing to be nonstationary processes on short time periods, while being overall stationary.

similar to the full 1973 to 1995 sample, although shifted to the left by the absence of high interest rates observed during this period. The parameter estimates corresponding to all these configurations are in Table 4.

4.5 Transition densities

Figure 6a reports the nonparametric estimate of the joint density of the spot rate at 1-day intervals—the basic input for the method proposed in Section 2. The joint density brings some interesting information regarding the interest rate process. Most of the mass is around the 45-degree line, since most day-to-day changes are small. Intuitively, the strength of the drift can then be read from the steepness of the off-diagonal slopes. The unconstrained model [Equation (23)] is not rejected by the transition-based test. To see how close the answer from the two tests can be, Figure 6b reports the transition discrepancy $(r_i, r_{i+\Delta}) \mapsto \hat{m}(\Delta, r_i, r_{i+\Delta}, \hat{\theta}_M)$ defined in Equations (18) through (20) and evaluated under the unconstrained parametrization of Equations (23) and (24) at the parameter values of Equation (10) estimated in the course of running the marginal density test. Figure 6c plots the

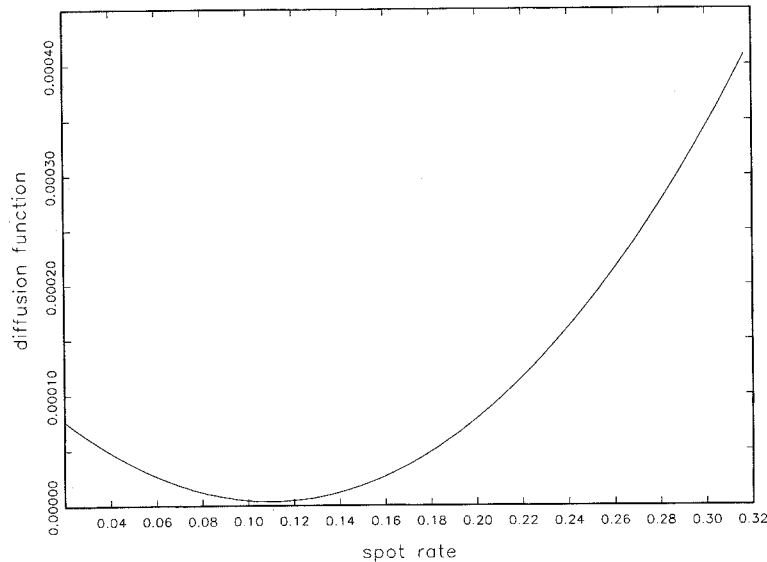


Figure 4c
Estimated nonlinear diffusion, 1973–1995

This figure plots the diffusion function corresponding to the parametric density in Figure 4a. The spot rate appears more volatile when outside the middle region, at both ends of the spectrum.

transition discrepancy for the linear drift CEV diffusion model, also evaluated at the parameters estimated from the marginal test. From Equations (20) and (22), large discrepancies lead to rejection of a given model. We find that the magnitude of the discrepancy in Figure 6c is significantly larger than that of Figure 6b. Like the marginal-based test, the transition-based test does reject the linear drift CEV diffusion model, but not the general parametric model.

4.6 A discrete look at nonlinearities in the drift

Figure 7 (a, b) show estimates of the μ and σ^2 functions obtained from discretizing the continuous-time moments in Equation (23). Feasible generalized least squares is a two-stage estimator, where residuals are computed from a first-stage ordinary least squares regression of the spot rate change. The specification of the regression is the crude discretization of the drift in Equation (23): $E[r_{t+1} - r_t | r_t] = \alpha_0 + (\alpha_1 - 1)r_t + \alpha_2 r_t^2 + \alpha_3 / r_t$. The squared residuals ε_{t+1}^2 from this first-stage regression are then regressed by nonlinear least squares, with a discretization of the diffusion in Equation (23): $E[\varepsilon_{t+1}^2 | r_t] = \beta_0 + \beta_1 r_t + \beta_2 r_t^{\beta_3}$.

The second-stage regression for the drift uses the fitted values from the diffusion regression to form the weighting matrix for the

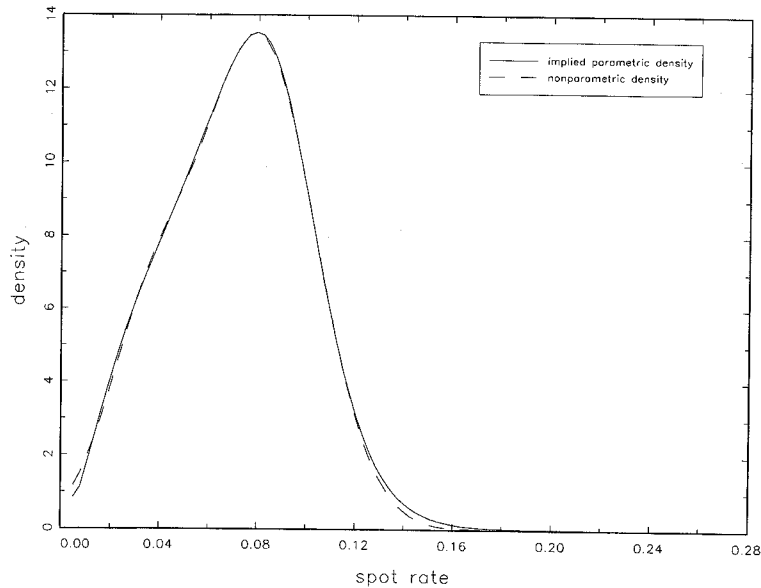


Figure 5a
Density comparison with nonlinear drift and diffusion, 1983–1995

This figure is obtained under the same circumstances as Figure 4a except that the sample is restricted to the years posterior to the Federal Reserve's "monetarist experiment" from October 1979 to September 1982. The parameter values are reported in Table 4. The unrestricted model of Equations (23) and (24) is not rejected with this truncated sample.

generalized least squares estimation of the discretized drift. The resulting FGLS drift parameters are in Figure 7a, along with a scatter plot of the actual spot rate changes. To avoid cluttering the graphs, each point in Figure 7 (a, b, and c) represents 50 daily observations. Figure 7b reports the fitted values from the diffusion equation next to a scatter plot of the first-stage squared residuals. Figure 7c reports the first-stage residuals scaled by the fitted standard errors $\left(\varepsilon_{t+1} / \sqrt{\hat{\beta}_0 + \hat{\beta}_1 r_t + \hat{\beta}_2 r_t^3} \right)$. This plot shows that the heteroskedasticity apparent in Figure 7b is removed by the FGLS procedure: the scaled residuals in Figure 7c are essentially white noise. A Chow test to detect parameter shifts between the 1980 to 1982 period and the rest of the sample does not reject the null hypothesis of parameter equality. The same test for the linear drift CEV diffusion model rejects the null, emphasizing again the misspecification of this parametrization.

This FGLS estimation would be asymptotically efficient if the discretized moments were exact. But this is not the case with a crude discretization, and the difference introduces a discretization bias—likely to be less severe with daily data than monthly data. In general,

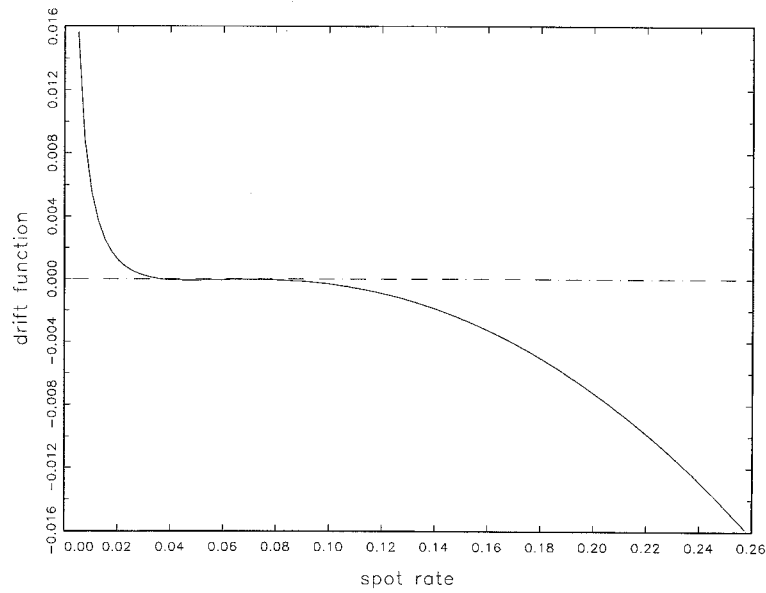


Figure 5b
Estimated nonlinear drift, 1983–1995
This figure reports the drift function corresponding to the parametric density in Figure 5a. Note that the overall shape of the estimated drift is similar to that of Figure 4b.

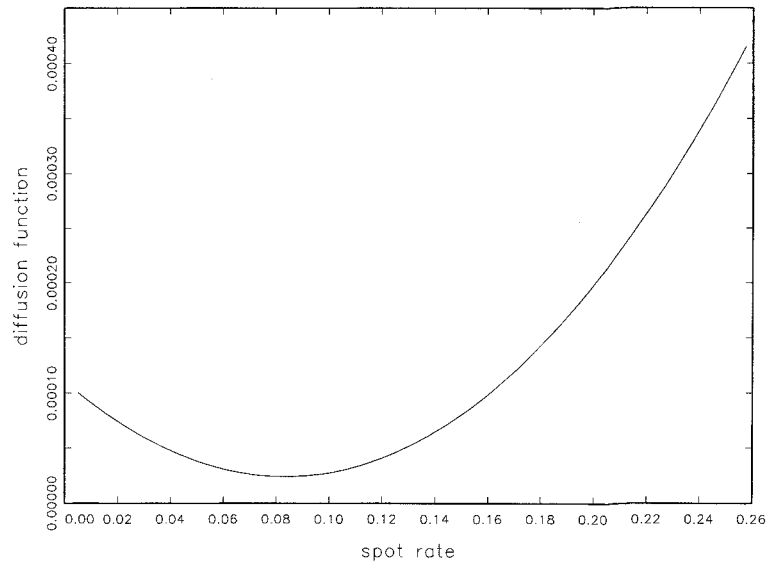


Figure 5c
Estimated nonlinear diffusion, 1983–1995
This figure reports the diffusion function corresponding to the parametric density in Figure 5a. The overall shape of the estimated diffusion also matches that of Figure 4c.

Table 4
Estimated parameter values for the continuous-time spot rate process

Estimated parameter values	Linear drift, CEV diffusion	Linear drift, CEV diffusion, 0 attainable	General parametric model 1973–1995	General parametric model 1983–1995
$\hat{\theta}_M$		Figures 3a,b,c Figure 6c	Figures 4a,b,c Figure 6b	Figures 5a,b,c
$\mu(x, \theta)$	α_0 2.935×10^{-3}	1.224×10^{-3}	-4.643×10^{-3}	-5.652×10^{-3}
	α_1 -3.688×10^{-2}	-1.400×10^{-2}	4.333×10^{-2}	9.648×10^{-2}
	α_2 Constrained = 0	Constrained = 0	-1.143×10^{-1}	-5.349×10^{-1}
	α_3 Constrained = 0	Constrained = 0	1.304×10^{-4}	1.041×10^{-4}
$\sigma^2(x, \theta)$	β_0 Constrained = 0	Constrained = 0	1.108×10^{-4}	1.099×10^{-4}
	β_1 Constrained = 0	Constrained = 0	-1.883×10^{-3}	-2.007×10^{-3}
	β_2 1.796×10^{-4}	4.902×10^{-4}	9.681×10^{-3}	1.329×10^{-2}
	β_3 0.29 (unconstrained)	1.04 Constrained ≥ 1	2.073	2.051
Test statistic \bar{M}	13.15	38.56	0.350	0.289

The estimated parameter vector reported in Table 4 is from Equation (10). These parameter values correspond to a spot rate that is continuously compounded, annualized, and expressed as a decimal number (0.07 for 7 percent). All the coefficients are significant at the 95 percent level. The table also indicates the parameter values corresponding to the relevant figures. The relative scale of the drift and diffusion, μ/σ^2 , is arbitrary. To report consistent results across models we fix the scale by matching the average level of interest rate volatility observed in the sample. The otherwise unconstrained estimates of the general parametric model [Equation (23)] reported in the last two columns of the table satisfy the parameter restrictions [Equation (24)].

there are no closed-form expressions available for the moments of r_{t+1} given r_t , so no better discretization can be proposed.¹⁸ For this reason, this section is provided only for comparison purposes with the other results in the literature [e.g., Chan et al. (1992)]. The test of the continuous-time model with discrete data test in this article, and the nonparametric estimation of the diffusion in Ait-Sahalia (1992b), both take explicitly into account the effect of estimating a continuous-time model sampled at a discrete frequency and do not suffer from discretization bias.

5. Conclusions

Stochastic differential equations are a powerful tool in the hands of finance theorists. But it is often hard to justify on empirical grounds the particular specifications being adopted in any given model. This article provides a first step in that direction. Many other processes of

¹⁸ Cases where closed-form expressions are available include the Vasicek [(1977, p. 185, Equations (25) and (26)] and Cox, Ingersoll, and Ross [(1985, p. 392, Equation (19)] models. Every model with a linear drift has the same conditional mean, regardless of its diffusion [Ait-Sahalia (1992b, Equation (2.4)].

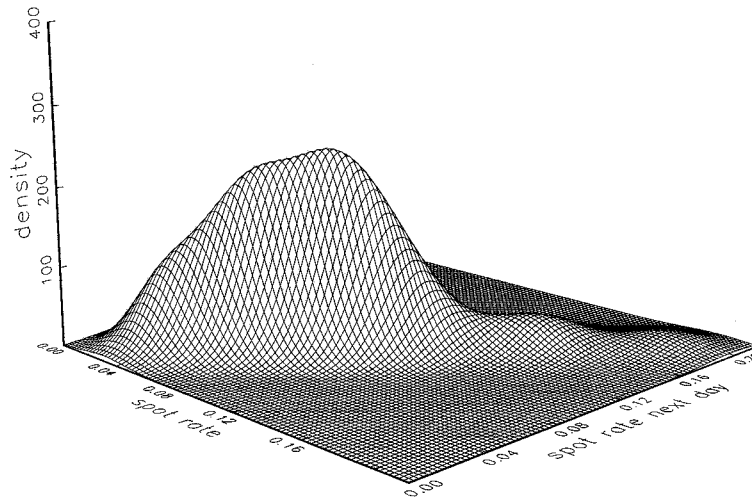


Figure 6a

Nonparametric transition densities

This figure reports the estimated nonparametric transition densities $(r_t, r_{t+\Delta}) \mapsto \hat{p}_0(\Delta, r_{t+\Delta} | r_t)$ from Equation (21) for the full sample of 1973 to 1995. The sampling interval is $\Delta = 1$ day. These densities are then used to compute the transition discrepancy $\hat{m}(\Delta, r_{t+\Delta}, r_t, \theta)$ in Equation (20).

interest in finance, for example, stock returns or exchange rates, could be subjected to the same type of inquiry.

We test the specification of parametric interest rate models by examining how closely the parametric model can reproduce features of its nonparametric counterpart. We examine the sources of the rejection of the models tested. We propose a simple model that captures well the dynamics of the spot rate. This model has the appealing feature of being a random walk for middle values of the spot rate, while still being globally stationary. This article provides evidence of nonlinear effects in the dynamics of the spot interest rate.

The results in this article can be generalized. For example, certain situations may dictate the choice of the distance metric between the parametric and nonparametric densities. We may be particularly interested in how the model performs in the tails of the distribution. Then the class of distance metrics $\min_{\theta \in \Theta} \int_{\underline{x}}^{\bar{x}} (\pi(u, \theta) - \pi_0(u))^2 \omega_0(u) du$ can be used where the weighting function ω_0 is chosen to emphasize the tails (as opposed to $\omega_0 = \pi_0$ which has the opposite effect). As another example, if the current spot rate level is r_t and we are interested in the performance of the model over the next few weeks, it may be natural to minimize the distance $\min_{\theta \in \Theta} \int_{\underline{x}}^{\bar{x}} \{m(\Delta, y, r_t, \theta)\}^2 p_0(\Delta, y, r_t) dy$, that is, conditioning on the current value.

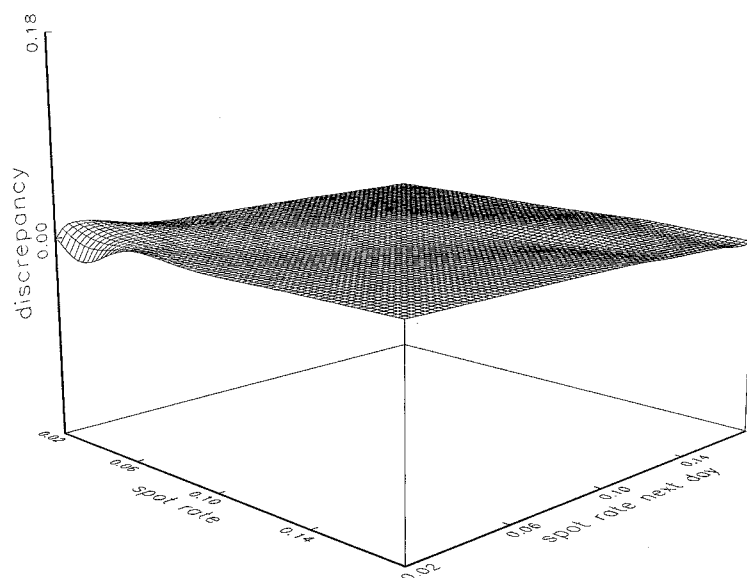


Figure 6b
Transition discrepancy for the nonlinear model
 This figure plots the estimated transition discrepancy \hat{m} from Equation (20), evaluated for the unrestricted model of Equations (23) and (24) at the same parameter values $\hat{\theta}_M$ as in Figures 4a, b, and c. Under the null hypothesis of correct specification, the transition discrepancy must be zero.

Appendix

Assumptions

Assumption A0. The parameter space $\Theta \subset R^K$ is compact. In a neighborhood of the true parameter θ_0 , $\pi(x, \theta)$ is twice continuously differentiable in θ , $E[(\partial\pi(x, \theta)/\partial\theta)(\partial\pi(x, \theta)/\partial\theta)']$ has full rank, and $\partial^2\pi(x, \theta)/\partial\theta_i\partial\theta_j$ is bounded in absolute value for all θ in Θ , x in D , i and j .

This assumption ensures the identifiability of θ_0 in the parametric class of densities considered. The relative scale of μ and σ_2 is arbitrary and θ_0 is defined to incorporate only the identified parameters. For identification purposes, β_3 can be neither 0 (unless $\beta_0 \equiv 0$) nor 1 (unless $\beta_1 \equiv 0$).

We first impose constraints on the signs of the parameters to ensure that $\sigma^2(\cdot, \theta) > 0$ on D and $\lim_{x \rightarrow 0} \mu(x, \theta) > 0$, $\lim_{x \rightarrow +\infty} \mu(x, \theta) < 0$. In particular for Equation (23) it is necessary that (i) $\alpha_2 \leq 0$ (and $\alpha_1 < 0$ if $\alpha_2 = 0$); (ii) $\alpha_3 \geq 0$ (and $\alpha_0 > 0$ if $\alpha_3 = 0$); (iii) $\beta_0 \geq 0$ (and $\beta_2 > 0$ if $\beta_0 = 0$ and $0 < \beta_3 < 1$, or $\beta_1 > 0$ if $\beta_0 = 0$ and $\beta_3 > 1$); (iv) $\beta_2 > 0$ if $\beta_3 > 1$ or $\beta_1 = 0$; and (v) $\beta_1 > 0$ if $0 < \beta_3 < 1$ or $\beta_2 = 0$.

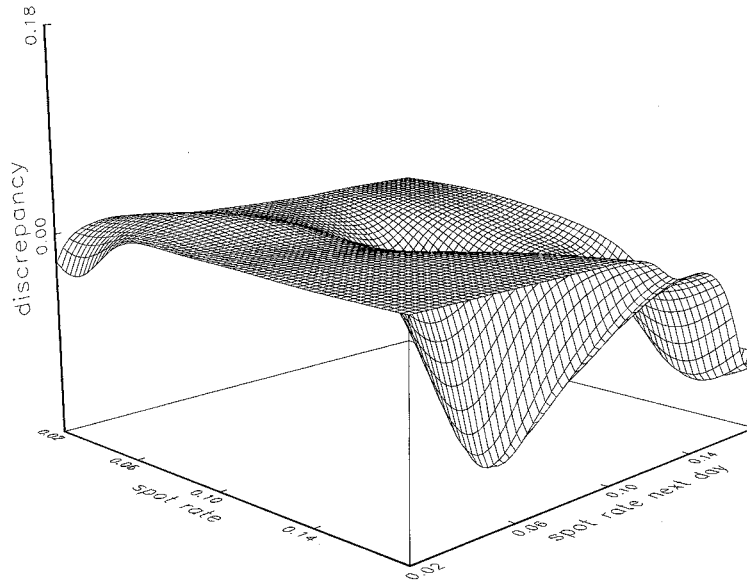


Figure 6c
Transition discrepancy for the linear drift and CEV diffusion model
 This figure plots the estimated transition discrepancy \hat{m} from Equation (20) for the same restricted model as in Figures 3a, b, and c and evaluated at the same parameter values $\hat{\theta}_M$.

Assumption A1. For every θ in Θ :

- (i) The drift and the diffusion functions are six times continuously differentiable in x on $D = (0, \infty)$, and $\sigma^2 > 0$ on $(0, \infty)$.
- (ii) The integral of $m(v, \theta) \equiv (1/\sigma^2(v, \theta)) \exp\{-\int_v^{\bar{v}} [2\mu(u, \theta)/\sigma^2(u, \theta)] du\}$, the speed measure M , converges at both boundaries of D .
- (iii) The integral of $s(v, \theta) \equiv \exp\{\int_v^{\bar{v}} [2\mu(u, \theta)/\sigma^2(u, \theta)] du\}$, the scale measure S , diverges at both boundaries of D .

In assumption A1 (ii) and (iii), \bar{v} is fixed in D and its particular choice is irrelevant. Assumption A1 (i) and (ii) guarantees that stochastic differential Equation (1) admits a unique strong solution, which is a Markov process with time-homogenous transition densities and a stationary marginal density [note that Equation (6) is proportional to the speed measure]. Assumption A1 (i) and (ii) is considerably less restrictive than the *global* Lipschitz and growth conditions usually imposed on μ and σ^2 to obtain the existence and unicity of a solution. Assumption A1 (i) implies *local* Lipschitz and growth properties (on every compact in D) by the mean-value theorem. The local Lipschitz condition is sufficient to ensure strong uniqueness of the solution. For example, in Equation (23), any of the nonlinear μ models

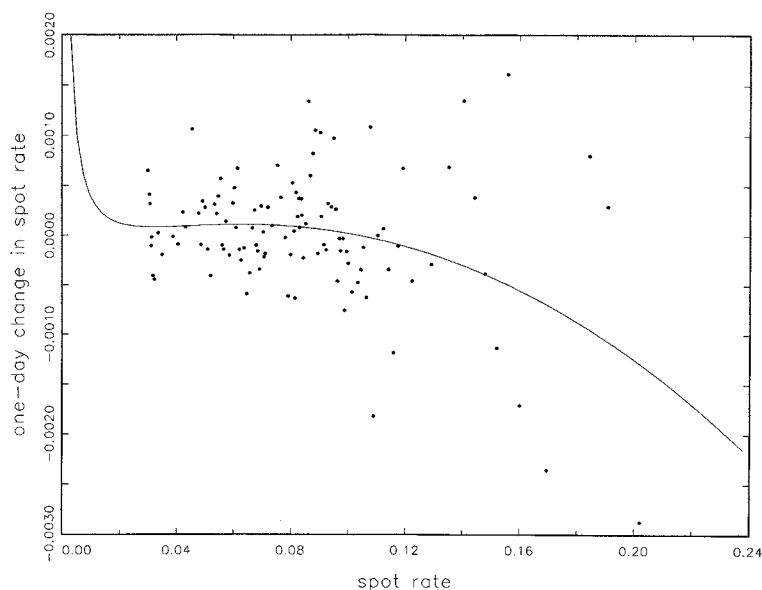


Figure 7a
FGLS drift regression

This figure reports the feasible generalized least squares estimate of the discretized drift corresponding to the unrestricted model of Equations (23) and (24). The discretization replaces the continuous-time change in the spot rate by the 1-day observed change, and the conditional mean of the 1-day change by the drift. The weights for the least squares regressions are computed from the estimated diffusion in Figure 7b.

($\alpha_2 < 0$ and/or $\alpha_3 > 0$) or nonlinear σ^2 (with $\beta_3 > 1$) fail the global growth condition.

Assumption A1 (iii) guarantees that starting from any point in the interior of the state space $D = (0, \infty)$, the boundaries $\underline{x} = 0$ and $\bar{x} = +\infty$ cannot be attained in finite expected time. If in addition we were to assume *iv*—starting from either of the boundaries $\underline{x} = 0$ or $\bar{x} = +\infty$, an interior point in $D = (0, \infty)$ is reached in finite expected time—then the boundaries are entrance boundaries. Otherwise, the process cannot restart from the boundaries and the boundaries are natural¹⁹ [see Feller’s classification of boundaries in Karlin and Taylor (1981, Lemma 15.6.3, Table 15.6.2)]. How the interest rate process would restart from the boundaries is not particularly relevant from the

¹⁹ It can be established that a process with entrance boundaries must have a stationary marginal distribution (that is, assumption A1 (ii) is automatically satisfied)—and is also ergodic: that is, $\lim_{\Delta \rightarrow \infty} p(\Delta, x | y, \theta) = \pi(x, \theta)$. It is not necessary however to have entrance boundaries for the stationary distribution to exist. Natural boundaries cannot be reached from the interior of the state space, but the process cannot be started from natural boundaries. A stationary distribution may or may not exist if both boundaries are natural [depending upon whether assumption A1 (ii) is satisfied].

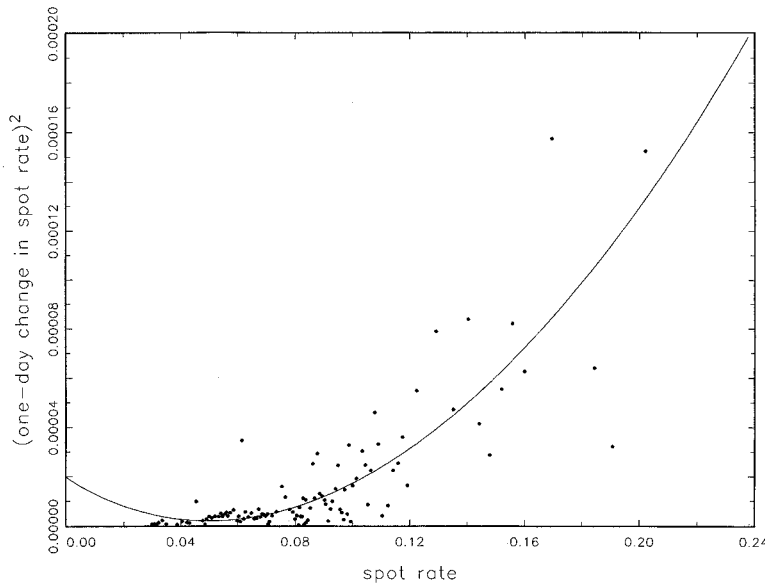


Figure 7b
FGLS diffusion regression

This figure reports the feasible generalized least squares estimate of the discretized diffusion corresponding to the unrestricted model of Equations (23) and (24). Similar to Figure 7c, the conditional variance of the 1-day change is replaced by the diffusion function.

economic standpoint, and we therefore allow both types of behaviors.

We now derive the parameter restrictions imposed by assumption A1 on Equation (23). We first examine the boundary behavior of the speed and scale measures near zero. When $\alpha_3 > 0$ and $\beta_0 > 0$, $\mu(u, \theta)/\sigma^2(u, \theta) \propto (1/\beta_0)(\alpha_3/u)$ so $m(v, \theta) \propto (1/\beta_0)v^{2\alpha_3/\beta_0}$ and $s(v, \theta) \propto (1/v)^{2\alpha_3/\beta_0}$. Therefore, in this case we require $2\alpha_3 \geq \beta_0 > 0$. When $\alpha_3 > 0$ and $\beta_0 = 0$, assumption A1 is satisfied. The only other admissible case is $\alpha_3 = 0, \alpha_0 > 0, \beta_0 = 0, \beta_3 > 1$, and $2\alpha_0 \geq \beta_1 > 0$ [then $\mu(u, \theta)/\sigma^2(u, \theta) \propto \alpha_0/(\beta_1 u)$]. Note in particular that the Cox, Ingersoll, and Ross model satisfies assumption A1 when $2\alpha_0 \geq \beta_1$, while the Vasicek model does not: assumption A1 (iii) is violated and zero—as well as negative values—are attainable.

Near infinity, if $\alpha_2 < 0$ and $\beta_3 > 1$ then $\mu(u, \theta)/\sigma^2(u, \theta) \propto (\alpha_2 u^2)/(\beta_2 u^{\beta_3})$ so $s(v, \theta) \propto \exp(-2\alpha_2/\beta_2(3 - \beta_3)v^{3-\beta_3})$ if $\beta_3 \neq 3$ and $s(v, \theta) \propto v^{-2\alpha_2/\beta_2}$ if $\beta_3 = 3$. Then $m(v, \theta) \propto (1/\beta_2 v^{\beta_3})(1/s(v, \theta))$ and assumption A1 is satisfied.^{20,21} If $\alpha_2 < 0$ and $0 < \beta_3 < 1$, assumption

²⁰ It is counterintuitive at first that assumption A1 is still satisfied when $\beta_3 > 3$. The intuition provided by Conley et al. (1995) is the following (“diffusion-induced mean reversion”): when σ^2 is large at high spot rate values, moves to higher interest rate levels are more likely, but so are large

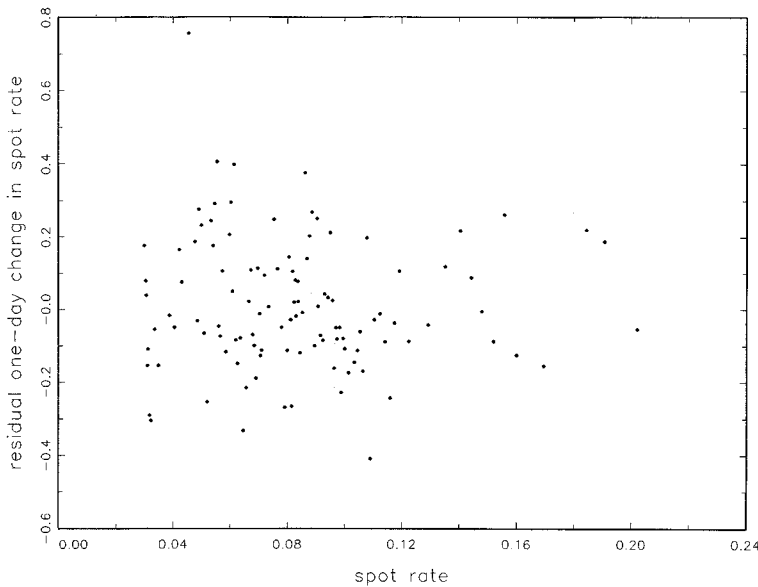


Figure 7c
Scaled residuals from FGLS drift regression

This figure shows that the FGLS correction has removed most of the conditional heteroskedasticity that was apparent in Figure 7b.

A1 is satisfied. If $\alpha_2 = 0$, $\alpha_1 < 0$, and $\beta_3 > 1$ then assumption A1 is similarly satisfied since then $s(v, \theta) \propto \exp(-2\alpha_1/\beta_2(2 - \beta_3)v^{2-\beta_3})$. If $\alpha_2 = 0$, $\alpha_1 < 0$, and $0 < \beta_3 < 1$, assumption A1 is satisfied since $s(v, \theta) \propto \exp(-2\alpha_1/\beta_1)v$.

The next assumption restricts the amount of dependence allowed in the discrete interest rate observations, so classical asymptotic theory can be applied (property 5).

Assumption A2. The observed data sequence $\{r_i\}$ is a strictly stationary β -mixing sequence satisfying: $k^\delta \beta(k) \xrightarrow{k \rightarrow +\infty} 0$ for some fixed $\delta > 1$.

A condition on the drift and diffusion sufficient to ensure that the discrete observations will satisfy assumption A2 is the following.²²

downward moves following a large upward move.

²¹ When $\beta_3 > 3$ no restrictions on the drift coefficients are needed to satisfy assumption A1. When $\beta_3 = 3$, only $2\alpha_2 < \beta_2$ is necessary. It is only when $\beta_3 < 3$ that the leading term of the drift must be negative. We will however always impose that either $\alpha_2 < 0$ or $\alpha_1 < 0$ if $\alpha_2 = 0$, that is, the process does mean revert at high values of the spot rate.

²² Under this assumption, the conditional expectation operator is a contraction [Hansen and Scheinkman (1995)] and then the desired mixing property of the discrete observations follows [see Ait-Sahalia (1992b)].

Assumption A2'. Assume that

- (i) $\lim_{x \rightarrow 0 \text{ or } x \rightarrow \infty} \sigma(x, \theta)\pi(x, \theta) = 0$
- (ii) $\lim_{x \rightarrow 0 \text{ or } x \rightarrow \infty} |\sigma(x, \theta)/\{2\mu(x, \theta) - \sigma(x, \theta)[\partial\sigma(x, \theta)/\partial x]\}| < \infty$.

For Equation (23), this condition is always satisfied under the parameter restrictions already made.

Assumption A3.

(i) The true density π_0 is positive on the interior of its support D and both π_0 and π_0^2 are in $L^2(D)$. The joint density p_0 is six times continuously differentiable.

(ii) The initial random variable r_0 is distributed as π_0 .

(iii) The true drift and diffusion functions satisfy assumptions A1 and A2.

Note that under assumption A1 (i), π_0 will be six times continuously differentiable. Assumption A3 (i) is required to derive the asymptotic distributions of the test statistics. Assumption A3 (ii) ensures that the process is initialized with the appropriate distribution to be stationary.

Assumption A4. The kernel function $K(\cdot)$ integrates to one and is of order $r = 2$.²³ K is bounded, twice continuously differentiable on R . K and its derivatives are in $L^2(R)$.

The next assumption determines how fast the bandwidth b_n should go to zero as the sample size n increases.

Assumption A5. To estimate the marginal density, the bandwidth is chosen such that $\lim_{n \rightarrow \infty} nb_n = \infty$ and $\lim_{n \rightarrow \infty} nb_n^{4.5} = 0$.

The empirical results are obtained with a Gaussian kernel $K(u) = \exp(-u^2/2)/\sqrt{2\pi}$ of order $r = 2$. More generally, for a d -dimensional density and kernel of order r , $\lim_{n \rightarrow \infty} nb_n^d = \infty$ and $\lim_{n \rightarrow \infty} nb_n^{2r+(d/2)} = 0$. The quality of density estimates is now widely recognized to be determined primarily by the choice of the bandwidth rather than that of the kernel. The bandwidth here is $b_n = c_n n^{-1/4.5}$, where $c_n = c$ times the standard deviation of the spot rate time series $\{r_i\}$, divided by $\ln(n)$. Then c is chosen to minimize the mean integrated square error of the estimator, under the constraint that the bandwidth rate undersmooths as prescribed by assumption A5. In the empirical application, we find $b_n = 1.347 \cdot 10^{-2}$ for the full 1973 to 1995 sample and $b_n = 1.653 \cdot 10^{-2}$ for the subsample 1983 to 1995. The results are qualitatively robust to the choice of the kernel as well as small changes in the bandwidth parameter around the optimal value.

²³ The order of a kernel $K(\cdot)$ is defined as the integer r such that $\int_{-\infty}^{+\infty} x^i K(x) dx = 0$ $i = 1, \dots, r-1$, and $\int_{-\infty}^{+\infty} x^r K(x) dx \neq 0$, $\int_{-\infty}^{+\infty} |x|^r |K(x)| dx < \infty$.

Assumption A5'. To compute the transition-based test statistic, the bandwidth is chosen such that $\lim_{n \rightarrow \infty} nb_n^5 = \infty$ and $\lim_{n \rightarrow \infty} nb_n^9 = 0$.

The empirical plot of the transition density is obtained with a product Gaussian kernel, $k(u, v) = K(u)K(v)$. The test statistic can be calculated with bandwidth $b_n = c_n n^{-1/9}$ where $c_n = c$ times the standard deviation of the spot rate time series $\{r_t\}$, divided by $\ln(n)$. Then c is chosen to minimize the mean integrated square error of the estimator, under the constraint that the bandwidth rate undersmooths as prescribed by assumption A5'.

Proof of Equation (12). In this proof and the next, $F_0(\cdot)$ will denote the cumulative density function associated with the density $\pi_0(\cdot)$. To obtain the limiting distribution of $\hat{\theta}_M$, we define the functional

$$\Theta_M[F] \equiv \arg \min_{\theta \in \Theta} \int_{\underline{x}}^{\bar{x}} (\pi(x, \theta) - \pi_0(x))^2 \pi_0(x) dx.$$

We need to compute the functional derivative of the $K \times 1$ parameter vector $\Theta_M(\cdot)$. The functional and its perturbation by H (with density $b = H'$) around F_0 are the implicit solutions of the first-order conditions:

$$\begin{cases} \int_{\underline{x}}^{\bar{x}} \frac{\partial \pi(x, \Theta_M[F_0])}{\partial \theta} (\pi(x, \Theta_M[F_0]) - \pi_0(x)) \pi_0(x) dx \equiv 0 \\ \int_{\underline{x}}^{\bar{x}} \frac{\partial \pi(x, \Theta_M[F_0 + H])}{\partial \theta} (\pi(x, \Theta_M[F_0 + H]) - (\pi_0 + b)(x)) (\pi_0 + b)(x) dx \equiv 0 \end{cases}$$

where the gradients $\frac{\partial \pi(x, \theta)}{\partial \theta}$ are $K \times 1$. To compute the $K \times 1$ functional derivative $\varphi(F_0)$, consider the expansion $\Theta_M[F_0 + H] = \Theta_M[F_0] + \int_{\underline{x}}^{\bar{x}} \varphi[F_0](u) b(u) du + O(\|b\|_{L^2}^2)$. The L^2 norm of b is $\|b\|_{L^2} = \left\{ \int_{\underline{x}}^{\bar{x}} |b(x)|^2 dx \right\}^{1/2}$. The derivative of Θ_M is computed as

$$\begin{aligned} \varphi[F_0](u) &= \left\{ \int_{\underline{x}}^{\bar{x}} \frac{\partial \pi(x, \Theta_M[F_0])}{\partial \theta} \frac{\partial \pi(x, \Theta_M[F_0])}{\partial \theta'} \pi_0(x) dx \right\}^{-1} \\ &\quad \times \frac{\partial \pi(u, \Theta_M[F_0])}{\partial \theta} \pi_0(u) \\ &= E \left[\frac{\partial \pi(x, \theta_0)}{\partial \theta} \frac{\partial \pi(x, \theta_0)}{\partial \theta'} \right]^{-1} \frac{\partial \pi(u, \theta_0)}{\partial \theta} \pi_0(u) \end{aligned}$$

and therefore $\varphi[F_0](\cdot)$ is continuous in F_0 . The asymptotic distribution of $\hat{\theta}_M = \Theta_M[\hat{F}_0]$ follows immediately from Ait-Sahalia (1992a), $n^{1/2} \{ \hat{\theta}_M - \theta_0 \} \xrightarrow{d} N(0, \Omega_M)$, with asymptotic variance given by

$$\Omega_M \equiv Var(\varphi[F](x_t)) + \sum_{k=1}^{+\infty} \{ Cov(\varphi[F](x_t), \varphi[F](x_{t+k})) + Cov(\varphi[F](x_{t+k}), \varphi[F](x_t)) \}.$$

A consistent estimate of Ω_M can be obtained by replacing the unknown parameter θ_0 by $\hat{\theta}_M$ in $\varphi[F](\cdot)$ and by truncating the infinite sum as in Newey-West.

Proof of Equation (13). We now need to compute a Taylor expansion for the functional $M(\cdot)$ defined as

$$\begin{aligned} M[F_0] &\equiv \min_{\theta \in \Theta} \int_{\underline{x}}^{\bar{x}} (\pi(x, \theta) - \pi_0(x))^2 \pi_0(x) dx \\ &= \int_{\underline{x}}^{\bar{x}} (\pi(x, \Theta_M[F_0]) - \pi_0(x))^2 \pi_0(x) dx. \end{aligned}$$

It can easily be shown that under the null hypothesis the functional Taylor expansion of $M(\cdot)$ has the form

$$\begin{aligned} M[F_0 + H] &= M[F_0] + \int_{\underline{x}}^{\bar{x}} \left\{ \frac{\partial \pi(x, \theta_0)}{\partial x} \int_{\underline{x}}^{\bar{x}} \varphi[F_0](u) b(u) du - b(x) \right\}^2 \\ &\quad \times \pi_0(x) dx + O(\|b\|_{L^2}^3) \\ &\equiv M[F_0] + \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \ell[F_0](x, y) dH(x) dH(y) + O(\|b\|_{L^2}^3). \end{aligned}$$

The linear term in the expansion is zero because under H_0 $\pi(x, \theta_0) - \pi_0(x) = 0$. Therefore, the term driving the asymptotic distribution of Λ in the delta method will be quadratic. Now the form of $\ell[F](x, y)$ is $\ell[F](x, y) = g[F](x, y) + \pi_0(x)\delta_{(x)}(y)$ where the functional g is continuous. Then b is replaced by $\hat{\pi}_0 - \pi_0$ by the continuous mapping theorem, it can be shown that the term $\int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} g[F](x, y) dH(x) dH(y)$ will converge at speed n [to a sum of independent χ^2 distributions for i.i.d. data, a classical U -statistics result (see e.g., Serfling (1980, p. 226–227, Theorem B); the speed of convergence is still n with dependent data]. However, when b is replaced by $\hat{\pi}_0 - \pi_0$ the term

$\int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \pi_0(x) \delta_{(x)}(y) dH(x) dH(y) = \int_{\underline{x}}^{\bar{x}} \pi_0(x) b(x)^2 dx$ will converge (i) at the slower speed nb_n and (ii) to a normal distribution [by extending to dependent data the result of Bickel and Rosenblatt (1973, p. 1073)]; it can be shown with the tools of Ait-Sahalia (1992a) that the asymptotic distribution of this term is unchanged for dependent data.

Therefore, recalling that $M[F_0] = 0$, $\widehat{M} = nb_n M[\widehat{F}_0]$ converges at speed $b_n^{-1/2}$, and to the same asymptotic distribution as $nb_n \int_{\underline{x}}^{\bar{x}} \{\widehat{\pi}_0(x) - \pi_0(x)\}^2 \pi_0(x) dx$. The asymptotic distribution is $b_n^{-1/2} \{\widehat{M} - E_M\} \xrightarrow{d} N(0, V_M)$ where

$$\begin{cases} E_M \equiv \left(\int_{-\infty}^{+\infty} K^2(x) dx \right) \left(\int_{\underline{x}}^{\bar{x}} \pi_0^2(x) dx \right) \\ V_M \equiv 2 \left(\int_{-\infty}^{+\infty} \left\{ \int_{-\infty}^{+\infty} K(u)K(u+x) du \right\}^2 dx \right) \left(\int_{\underline{x}}^{\bar{x}} \pi_0^4(x) dx \right). \end{cases}$$

Proof of Equation (22). This proof is similar to that of Equation (13), albeit more complicated. Compute an expansion of Equation (19): $T[F_0] \equiv \min_{\theta \in \Theta} \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \{m(\Delta, y, x, \theta)\}^2 p_0(\Delta, y, x) dx dy$ at $F_0 + H$, with F now being the joint *cdf* of X_t and $X_{t+\Delta}$. First, replace the conditional density appearing in $m(\cdot)$ with the joint and marginal densities and then expand $p_0(\Delta, y | x) = p_0(\Delta, y, x) / \pi_0(x)$. Next note that

$$\begin{aligned} & \frac{\partial^2}{\partial y^2} (\sigma^2(y, \theta) b(\Delta, y, x)) - b(\Delta, y, x) \frac{\partial^2 \sigma^2(y, \theta)}{\partial y^2} + 2 \frac{\partial \sigma^2(y, \theta)}{\partial y} \\ & \times \frac{\partial b(\Delta, y, x)}{\partial y} + \sigma^2(y, \theta) \frac{\partial^2 b(\Delta, y, x)}{\partial y^2}. \end{aligned}$$

Higher order derivatives of b converge slower so only the last of the three terms on the right-hand side above contribute to the asymptotic distribution. Thus the term in the expansion giving the asymptotic distribution of the \widehat{T} is

$$\begin{aligned} I \equiv & \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \left\{ \frac{\sigma^2(y, \theta)}{2\pi_0(x)} \frac{\partial^2 b(\Delta, y, x)}{\partial y^2} - \frac{\sigma^2(x, \theta)}{2\pi_0(x)} \frac{\partial^2 b(\Delta, y, x)}{\partial x^2} \right. \\ & \left. + \frac{p_0(\Delta, y, x)}{\pi_0(x)} \sigma^2(x, \theta) \frac{\partial^2 b(x)}{\partial x^2} \right\}^2 p_0(\Delta, y, x) dx dy \end{aligned}$$

as the marginal density $\pi_0(\cdot)$ also converges faster than the conditional

density and its derivatives, but just faster enough to be included in the bias correction E_T below.

Evaluated at $b(\Delta, y, x) = \hat{p}_0(\Delta, y, x) - p_0(\Delta, y, x)$, the term I gives the asymptotic distribution of $\hat{T} = nb_n^6 I$: $b_n^{-1}\{\hat{T} - E_T\} \xrightarrow{d} N(0, V_T)$, where

$$\left\{ \begin{aligned} E_T &\equiv \frac{1}{4} \left\{ \int_{-\infty}^{+\infty} K^2(x) dx \int_{-\infty}^{+\infty} [K^{(2)}(x)]^2 dx \right. \\ &\quad \times \left(\int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \{ \sigma^4(y, \theta) + \sigma^4(x, \theta) \} \frac{p_0^2(\Delta, y, x)}{\pi_0^2(x)} dy dx \right) \\ &\quad - 2 \left(\int_{-\infty}^{+\infty} K(x) K^{(2)}(x) dx \right)^2 \\ &\quad \times \left. \left(\int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \{ \sigma^2(y, \theta) \sigma^2(x, \theta) \} \frac{p_0^2(\Delta, y, x)}{\pi_0^2(x)} dy dx \right) \right\} \\ &\quad + \frac{b_n}{4} \left(\int_{-\infty}^{+\infty} [K^{(2)}(x)]^2 dx \right) \left(\int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \sigma^4(x, \theta) \frac{p_0^3(\Delta, y, x)}{\pi_0^3(x)} dy dx \right) \\ V_T &\equiv \frac{1}{8} \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \{ \gamma(x, y, x_1, y_1, x_2, y_2) \}^2 \\ &\quad \times \frac{p_0^4(\Delta, y_1, x_1)}{\pi_0^4(x_1)} dy_1 dx_1 dy_2 dx_2 \end{aligned} \right.$$

with

$$\begin{aligned} \gamma(x, y, x_1, y_1, x_2, y_2) &\equiv \int_{\underline{x}}^{\bar{x}} \int_{\underline{x}}^{\bar{x}} \{ \sigma^2(y_1, \theta) K^{(2)}(y) K(x) \\ &\quad - \sigma^2(x_1, \theta) K^{(2)}(x) K(y) \} \\ &\quad \cdot \{ \sigma^2(y + y_2, \theta) K^{(2)}(y + y_2) K(x + x_2) \\ &\quad - \sigma^2(x + x_2, \theta) K^{(2)}(x + x_2) K(y + y_2) \} dy dx. \end{aligned}$$

To obtain consistent estimates of E_T and V_T replace π_0 and p_0 by their kernel estimates, θ_0 by its estimate, plug-in the kernel function K , and evaluate the integrals.

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