

ELE539A: Optimization of Communication Systems
Lecture 2: Convex Optimization and Lagrange Duality

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Lecture Outline

- Convex optimization
- Optimality condition
- Lagrange dual problem
- Interpretations
- KKT optimality condition
- Sensitivity analysis

Thanks: Stephen Boyd (some materials and graphs from Boyd and Vandenberghe)

Convex Optimization

A **convex optimization** problem with variables x :

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq 0, \quad i = 1, 2, \dots, m \\ & && a_i^T x = b_i, \quad i = 1, 2, \dots, p \end{aligned}$$

where f_0, f_1, \dots, f_m are convex functions.

- **Minimize convex** objective function (or maximize concave objective function)
- **Upper bound inequality** constraints on **convex** functions (\Rightarrow Constraint set is convex)
- **Equality** constraints must be **affine**

Convex Optimization

- Epigraph form:

$$\begin{aligned} & \text{minimize} && t \\ & \text{subject to} && f_0(x) - t \leq 0 \\ & && f_i(x) \leq 0, \quad i = 1, 2, \dots, m \\ & && a_i^T x = b_i, \quad i = 1, 2, \dots, p \end{aligned}$$

- Not in convex optimization form:

$$\begin{aligned} & \text{minimize} && x_1^2 + x_2^2 \\ & \text{subject to} && \frac{x_1}{1+x_2} \leq 0 \\ & && (x_1 + x_2)^2 = 0 \end{aligned}$$

Now **transformed** into a convex optimization problem:

$$\begin{aligned} & \text{minimize} && x_1^2 + x_2^2 \\ & \text{subject to} && x_1 \leq 0 \\ & && x_1 + x_2 = 0 \end{aligned}$$

Locally Optimal \Rightarrow Globally Optimal

Given x is locally optimal for a convex optimization problem, *i.e.*, x is feasible and for some $R > 0$,

$$f_0(x) = \inf\{f_0(z) \mid z \text{ is feasible}, \|z - x\|_2 \leq R\}$$

Suppose x is not globally optimal, *i.e.*, there is a feasible y such that $f_0(y) < f_0(x)$

Since $\|y - x\|_2 > R$, we can construct a point $z = (1 - \theta)x + \theta y$ where $\theta = \frac{R}{2\|y - x\|_2}$. By convexity of feasible set, z is feasible. By convexity of f_0 , we have

$$f_0(z) \leq (1 - \theta)f_0(x) + \theta f_0(y) < f_0(x)$$

which contradicts local optimality of x

Therefore, there exists no feasible y such that $f_0(y) < f_0(x)$

Optimality Condition for Differentiable f_0

x is optimal for a convex optimization problem iff x is feasible and for all feasible y :

$$\nabla f_0(x)^T (y - x) \geq 0$$

$-\nabla f_0(x)$ is supporting hyperplane to feasible set

Unconstrained convex optimization: condition reduces to:

$$\nabla f_0(x) = 0$$

Proof: take $y = x - t\nabla f_0(x)$ where $t \in \mathbf{R}_+$. For small enough t , y is feasible, so $\nabla f_0(x)^T (y - x) = -t\|\nabla f_0(x)\|_2^2 \geq 0$. Thus $\nabla f_0(x) = 0$

Unconstrained Quadratic Optimization

Minimize $f_0(x) = \frac{1}{2}x^T P x + q^T x + r$

P is positive semidefinite. So it's a convex optimization problem

x minimizes f_0 iff (P, q) satisfy this linear equality:

$$\nabla f_0(x) = P x + q = 0$$

- If $q \notin \mathcal{R}(P)$, no solution. f_0 unbounded below
- If $q \in \mathcal{R}(P)$ and $P \succ 0$, there is a unique minimizer $x^* = -P^{-1}q$
- If $q \in \mathcal{R}(P)$ and P is singular, set of optimal x : $-P^\dagger q + \mathcal{N}(P)$

Duality Mentality

Bound or solve an optimization problem via a different optimization problem!

We'll develop the basic Lagrange duality theory for a general optimization problem, then specialize for convex optimization

Lagrange Dual Function

An optimization problem in standard form:

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq 0, \quad i = 1, 2, \dots, m \\ & && h_i(x) = 0, \quad i = 1, 2, \dots, p \end{aligned}$$

Variables: $x \in \mathbf{R}^n$. Assume nonempty feasible set

Optimal value: p^* . Optimizer: x^*

Idea: augment objective with a weighted sum of constraints

Lagrangian $L(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x)$

Lagrange multipliers (dual variables): $\lambda \succeq 0, \nu$

Lagrange dual function: $g(\lambda, \nu) = \inf_x L(x, \lambda, \nu)$

Lower Bound on Optimal Value

Claim: $g(\lambda, \nu) \leq p^*$, $\forall \lambda \succeq 0, \nu$

Proof: Consider feasible \tilde{x} :

$$L(\tilde{x}, \lambda, \nu) = f_0(\tilde{x}) + \sum_{i=1}^m \lambda_i f_i(\tilde{x}) + \sum_{i=1}^p \nu_i h_i(\tilde{x}) \leq f_0(\tilde{x})$$

since $f_i(\tilde{x}) \leq 0$ and $\lambda_i \geq 0$

Hence, $g(\lambda, \nu) \leq L(\tilde{x}, \lambda, \nu) \leq f_0(\tilde{x})$ for all feasible \tilde{x}

Therefore, $g(\lambda, \nu) \leq p^*$

Lagrange Dual Function and Conjugate Function

- Lagrange dual function $g(\lambda, \nu)$
- Conjugate function: $f^*(y) = \sup_{x \in \text{dom } f} (y^T x - f(x))$

Consider linearly constrained optimization:

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && Ax \preceq b \\ & && Cx = d \end{aligned}$$

$$\begin{aligned} g(\lambda, \nu) &= \inf_x \left(f_0(x) + \lambda^T (Ax - b) + \nu^T (Cx - d) \right) \\ &= -b^T \lambda - d^T \nu + \inf_x \left(f_0(x) + (A^T \lambda + C^T \nu)^T x \right) \\ &= -b^T \lambda - d^T \nu - f_0^*(-A^T \lambda - C^T \nu) \end{aligned}$$

Example

We'll use the simplest version of **entropy maximization** as our example for the rest of this lecture on duality. Entropy maximization is an important basic problem in information theory:

$$\begin{aligned} &\text{minimize} && f_0(x) = \sum_{i=1}^n x_i \log x_i \\ &\text{subject to} && Ax \preceq b \\ &&& \mathbf{1}^T x = 1 \end{aligned}$$

Since the conjugate function of $u \log u$ is e^{y-1} , by independence of the sum, we have

$$f_0^*(y) = \sum_{i=1}^n e^{y_i - 1}$$

Therefore, dual function of entropy maximization is

$$g(\lambda, \nu) = -b^T \lambda - \nu - e^{-\nu-1} \sum_{i=1}^n e^{-a_i^T \lambda}$$

where a^i are columns of A

Lagrange Dual Problem

Lower bound from Lagrange dual function depends on (λ, ν) . What's the best lower bound that can be obtained from Lagrange dual function?

$$\begin{array}{ll} \text{maximize} & g(\lambda, \nu) \\ \text{subject to} & \lambda \succeq 0 \end{array}$$

This is the **Lagrange dual problem** with dual variables (λ, ν)

Always a convex optimization! (Dual objective function always a concave function since it's the infimum of a family of affine functions in (λ, ν))

Denote the optimal value of Lagrange dual problem by d^*

Weak Duality

What's the relationship between d^* and p^* ?

Weak duality always hold (even if primal problem is not convex):

$$d^* \leq p^*$$

Optimal duality gap:

$$p^* - d^*$$

Efficient generation of lower bounds through (convex) dual problem

Strong Duality

Strong duality (zero optimal duality gap):

$$d^* = p^*$$

If strong duality holds, solving dual is 'equivalent' to solving primal. But strong duality does **not** always hold

Convexity and **constraint qualifications** \Rightarrow Strong duality

A simple constraint qualification: **Slater's condition** (there exists strictly feasible primal variables $f_i(x) < 0$ for non-affine f_i)

Another reason why convex optimization is 'easy'

Example

Primal optimization problem (variables x):

$$\begin{aligned} & \text{minimize} && f_0(x) = \sum_{i=1}^n x_i \log x_i \\ & \text{subject to} && Ax \preceq b \\ & && \mathbf{1}^T x = 1 \end{aligned}$$

Dual optimization problem (variables λ, ν):

$$\begin{aligned} & \text{maximize} && -b^T \lambda - \nu - e^{-\nu-1} \sum_{i=1}^n e^{-a_i^T \lambda} \\ & \text{subject to} && \lambda \succeq 0 \end{aligned}$$

Analytically maximize over the unconstrained $\nu \Rightarrow$ Simplified dual optimization problem (variables λ):

$$\begin{aligned} & \text{maximize} && -b^T \lambda - \log \sum_{i=1}^n \exp(-a_i^T \lambda) \\ & \text{subject to} && \lambda \succeq 0 \end{aligned}$$

Strong duality holds

Saddle Point Interpretation

Assume no equality constraints. We can express primal optimal value as

$$p^* = \inf_x \sup_{\lambda \succeq 0} L(x, \lambda)$$

By definition of dual optimal value:

$$d^* = \sup_{\lambda \succeq 0} \inf_x L(x, \lambda)$$

Weak duality (max min inequality):

$$\sup_{\lambda \succeq 0} \inf_x L(x, \lambda) \leq \inf_x \sup_{\lambda \succeq 0} L(x, \lambda)$$

Strong duality (saddle point property):

$$\sup_{\lambda \succeq 0} \inf_x L(x, \lambda) = \inf_x \sup_{\lambda \succeq 0} L(x, \lambda)$$

Economics Interpretation

- Primal objective: cost of operation
- Primal constraints: can be violated
- Dual variables: price for violating the corresponding constraint (dollar per unit violation). For the same price, can sell 'unused violation' for revenue
- Lagrangian: total cost
- Lagrange dual function: optimal cost as a function of violation prices
- Weak duality: optimal cost when constraints can be violated is less than or equal to optimal cost when constraints cannot be violated, for any violation prices
- Duality gap: minimum possible arbitrage advantage
- Strong duality: can price the violations so that there is no arbitrage advantages

Complementary Slackness

Assume strong duality holds:

$$\begin{aligned} f_0(x^*) &= g(\lambda^*, \nu^*) \\ &= \inf_x \left(f_0(x) + \sum_{i=1}^m \lambda_i^* f_i(x) + \sum_{i=1}^p \nu_i^* h_i(x) \right) \\ &\leq f_0(x^*) + \sum_{i=1}^m \lambda_i^* f_i(x^*) + \sum_{i=1}^p \nu_i^* h_i(x^*) \\ &\leq f_0(x^*) \end{aligned}$$

So the two inequalities must hold with equality. This implies:

$$\lambda_i^* f_i(x^*) = 0, \quad i = 1, 2, \dots, m$$

Complementary Slackness Property:

$$\begin{aligned} \lambda_i^* > 0 &\Rightarrow f_i(x^*) = 0 \\ f_i(x^*) < 0 &\Rightarrow \lambda_i^* = 0 \end{aligned}$$

KKT Optimality Conditions

Since x^* minimizes $L(x, \lambda^*, \nu^*)$ over x , we have

$$\nabla f_0(x^*) + \sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) + \sum_{i=1}^p \nu_i^* \nabla h_i(x^*) = 0$$

Karush-Kuhn-Tucker optimality conditions:

$$f_i(x^*) \leq 0, \quad h_i(x^*) = 0, \quad \lambda_i^* \succeq 0$$

$$\lambda_i^* f_i(x^*) = 0$$

$$\nabla f_0(x^*) + \sum_{i=1}^m \lambda_i^* \nabla f_i(x^*) + \sum_{i=1}^p \nu_i^* \nabla h_i(x^*) = 0$$

- Any optimization (with differentiable objective and constraint functions) with strong duality, KKT condition is necessary condition for primal-dual optimality
- Convex optimization (with differentiable objective and constraint functions) with Slater's condition, KKT condition is **also sufficient** condition for primal-dual optimality (useful for theoretical and numerical purposes)

Waterfilling

$$\begin{aligned} & \text{maximize} && \sum_{i=1}^n \log(\alpha_i + x_i) \\ & \text{subject to} && x \succeq 0, \mathbf{1}^T x = 1 \end{aligned}$$

Variables: x (powers). Constants: α (noise)

KKT conditions:

$$\begin{aligned} x^* & \succeq 0, \mathbf{1}^T x^* = 1, \lambda^* \succeq 0 \\ \lambda_i^* x_i^* & = 0, -1/(\alpha_i + x_i) - \lambda_i^* + \nu^* = 0 \end{aligned}$$

Since λ^* are slack variables, reduce to

$$\begin{aligned} x^* & \succeq 0, \mathbf{1}^T x^* = 1 \\ x_i^* (\nu^* - 1/(\alpha_i + x_i^*)) & = 0, \nu^* \geq 1/(\alpha_i + x_i^*) \end{aligned}$$

If $\nu^* < 1/\alpha_i$, $x_i^* > 0$. So $x_i^* = 1/\nu^* - \alpha_i$. Otherwise, $x_i^* = 0$

Thus, $x_i^* = [1/\nu^* - \alpha_i]^+$ where ν^* is such that $\sum_i x_i^* = 1$

Global Sensitivity Analysis

Perturbed optimization problem:

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq u_i, \quad i = 1, 2, \dots, m \\ & && h_i(x) = v_i \quad i = 1, 2, \dots, p \end{aligned}$$

Optimal value $p^*(u, v)$ as a **function** of parameters (u, v)

Assume strong duality and that dual optimum is attained:

$$\begin{aligned} p^*(0, 0) = g(\lambda^*, \nu^*) &\leq f_0(x) + \sum_i \lambda_i^* f_i(x) + \sum_i \nu_i^* h_i(x) \leq f_0(x) + \lambda^{*T} u + \nu^{*T} v \\ p^*(u, v) &\geq p^*(0, 0) - \lambda^{*T} u - \nu^{*T} v \end{aligned}$$

- If λ_i^* is large, tightening i th constraint ($u_i < 0$) will increase optimal value greatly
- If λ_i^* is small, loosening i th constraint ($u_i > 0$) will reduce optimal value only slightly

Local Sensitivity Analysis

Assume that $p^*(u, v)$ is differentiable at $(0, 0)$:

$$\lambda_i^* = -\frac{\partial p^*(0, 0)}{\partial u_i}, \quad \nu_i^* = -\frac{\partial p^*(0, 0)}{\partial v_i}$$

Shadow price interpretation of Lagrange dual variables

Small λ_i^* means tightening or loosening i th constraint will not change optimal value by much

Lecture Summary

- **Convexity mentality.** Convex optimization is 'nice' for several reasons: local optimum is global optimum, zero optimal duality gap (under technical conditions), KKT optimality conditions are necessary and sufficient
- **Duality mentality.** Can always bound primal through dual, sometimes solve primal through dual
- Primal-dual: where is the **optimum**, how **sensitive** it is to perturbations

Readings: Sections 4.1-4.2 and 5.1-5.6 in Boyd and Vandenberghe