## Lecture 6

ELE 301: Signals and Systems

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## Outline

- LTI System Response
- Filtering

#### Transfer Function

• Response to LTI system h.

Continuous time: 
$$e^{st} \longrightarrow^h H_c(s)e^{st}$$
,  
Discrete time:  $z^n \longrightarrow^h H_d(z)z^n$ .

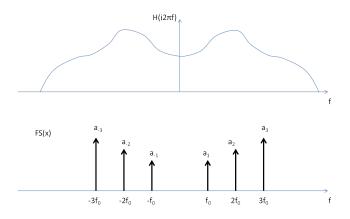
• We are interested in the cases  $s = i2\pi f$  and  $z = e^{i2\pi f}$ .

Continuous time: 
$$y(t) = \sum_{k=-\infty}^{\infty} a_k H_c(i2\pi f_0 k) e^{i2\pi f_0 kt}$$
,

Discrete time:  $y[n] = \sum_{k=-\infty}^{\infty} a_k H_d(e^{i2\pi f_0 k}) e^{i2\pi f_0 kn}$ .

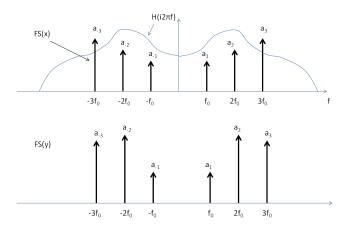
where  $a_k$  are the Fourier Series coefficients of the input with period  $\mathcal{T}=1/f_0$ .

## Intuitive Visualization



Note: Plots aren't technically accurate because complex numbers are not one-dimensional.

## Intuitive Visualization



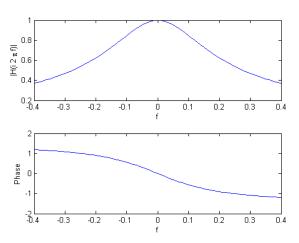
Note: Plots aren't technically accurate because complex numbers are not one-dimensional.

# Filtering Example

$$h(t) = e^{-t}u(t),$$
  
$$H(i2\pi f) = ?.$$

# First-order low-pass filter

$$H(i2\pi f) = \frac{1}{1+i2\pi f}.$$



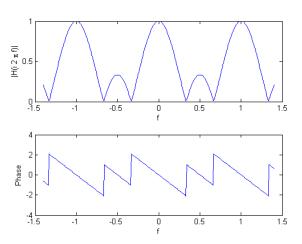
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# Filtering example - running average

$$h[n] = \frac{1}{3}(\delta[n] + \delta[n-1] + \delta[n-2]),$$
  
 $H(e^{i2\pi f}) = ?.$ 

# Running average

$$H(i2\pi f) = \frac{1}{3} \left( 1 + e^{-i2\pi f} + e^{-i4\pi f} \right).$$



# Filtering example - Differentiator

What is the impulse response of a differentiator?

$$h(t) = ?$$

#### Unit Doublet

- Another invented pseudo-function
- Conceptually the derivative of the Dirac delta function
- Properties

$$\delta' * f = f'$$

$$f(t)\delta'(t-t_0) = -f'(t_0)\delta(t-t_0)$$

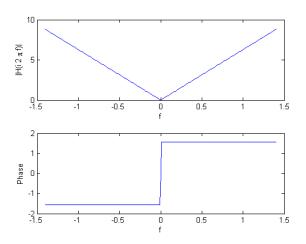
$$b \delta'(-t) = -\delta'(t)$$

## Differentiator

$$h(t) = \delta'(t),$$
  
$$H(i2\pi f) = ?.$$

# High-pass filter (Differentiator)

$$H(i2\pi f) = i2\pi f.$$



# Filtering example - discrete difference

$$h[n] = \frac{1}{2}(\delta[n] - \delta[n-1]),$$
  
$$H(e^{i2\pi f}) = ?.$$

## Discrete Difference

$$H(i2\pi f) = i e^{-i\pi f} \sin(\pi f).$$

