TESTING NONNESTED HYPOTHESES*

by

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ECONOMETRIC RESEARCH PROGRAM
Research Memorandum No. 140
May 1972

*I am indebted to Gregory C. Chow, David R. Cox, Stephen M. Goldfeld and Alan Stuart for helpful comments and suggestions. Of course, I am alone responsible for errors. Financial support from the National Science Foundation is gratefully acknowledged.

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1. Theoretical Considerations

The standard problem of testing hypotheses arises as follows: Let y be a random variable with probability density function (pdf) $f(y,\theta)$, where θ is a p-dimensional vector of parameters. Letting Ω represent p-dimensional Cartesian space, $\theta \epsilon \Omega$ in general. The null hypothesis H_{0} is expressed by the restriction $\theta \epsilon \Omega_{0}$, where $\Omega_{0} G \Omega = \Omega_{0}$. It is this circumstance which makes likelihood ratio tests possible, for denoting the loglikelihood function by $L(\theta)$, it guarantees that

$$\ell = \sup_{\theta \in \Omega_{O}} L(\theta) - \sup_{\theta \in \Omega} L(\theta) \le 0$$
 (1-1)

This condition is obviously also necessary for the asymptotic theorem, which holds under certain broad regularity conditions, that -2% has χ^2 distribution with degrees of freedom equal to the number of restrictions imposed by the hypothesis on Ω .1

The standard theory is not applicable if the null hypothesis and the alternative hypothesis are disparate or nonnested in the following sense. Let there be two hypotheses denoted by H_1 and H_2 . According to H_1 , the random variable y has pdf $f_1(y, \theta_1)$ with $\theta_1 \in \Omega_1$ and according to H_2 , y has pdf $f_2(y, \theta_2)$ with $\theta_2 \in \Omega_2$. Finally, assume that $\Omega_1 \cap \Omega_2 \neq \Omega_1$

¹See [10], pp. 230-1.

and $\Omega_1 \cap \Omega_2 \neq \Omega_2$. Cases of this type may be more common in econometrics than is usually recognized. A brief list of examples is as follows: (1) Test of the hypothesis that personal incomes have the lognormal distribution as against the alternative that they have Pareto distribution, (2) Test of the hypothesis that the error term in a Cobb Douglas type production function enters the equation multiplicatively as e^{u} against the alternative that it enters additively as e^{u} against the regression equation has one form against the alternative that it has some other form.

Although these and other questions of this type have been investigated frequently by various more or less ad hoc methods, 2 only few studies have explored systematically the statistical aspects of choosing between competing models and of testing hypotheses of this type. In a regression context and under the classical assumptions Theil has shown that a choice between models based on maximizing the multiple r^2 , adjusted for degrees of freedom, will on the average produce the correct statistical decision. More general are the works of Cox and Atkinson. Cox's main procedure is based on the generalized loglikelihood ratio $L_1(\theta_1) - L_2(\theta_2)$ where L_1 and L_2 are the likelihood functions appropriate for H_1 and H_2 respectively. In a recent paper Pesaran specializes this approach to the choice between competing regression models, both under the classical assumptions and also in the presence of first order serial correlation of the error term.

²See [2], [4], [15].

See [16], pp. 211-214 for Theil's argument and Pesaran's work [12] for some criticisms of it.

⁴See [1], [5], [6].

⁵See [12]:

Cox introduces and Atkinson further elaborates another procedure by which two competing pdf's are combined and their respective parameters are embedded in a larger space with the aid of a choice parameter λ . The pdf generating the sample is taken as

$$h(y,\theta_1,\theta_2,\lambda) = kf_1(y,\theta_1)^{\lambda} f_2(y,\theta_2)^{1-\lambda}$$
(1-2)

and it is suggested that this combined pdf, representing a compound statistical model, be used to make inferences about λ . 6

The difficulty with (1-2) is that in order for $h(y,\theta_1,\ \theta_2,\lambda)$ to be a density function, the factor of proportionality must be

$$k = \frac{1}{\int_{\infty}^{\infty} f_1(y, \theta_1)^{\lambda} f_2(y, \theta_2)^{1-\lambda} dy}$$
(1-3)

Hence the loglikelihood function is

$$L = \sum_{i=1}^{n} \log h(y_i, \theta_1, \theta_2, \lambda) = \lambda \sum_{i=1}^{n} \log f_1(y_i, \theta_1) + (1-\lambda) \sum_{i=1}^{n} \log f_2(y_i, \theta_2)$$

$$- \sum_{i=1}^{n} \log \int_{-\infty}^{\infty} f_1(y, \theta_1)^{\lambda} f_2(y, \theta_2)^{1-\lambda} dy \qquad (1-4)$$

which must be maximized with respect to θ_1, θ_2 and λ . Since, in general, the integral in (1-4) will be computable only by numerical quadrature, the maximization of (1-4) is likely to be a difficult task.

⁶ For further discussion of these and related issues see [7].

Even though the exponential combination of pdf's is convenient for many frequently occurring distributions, it is of some interest to explore the possibilities of hypothesis testing with the linear combination of pdf's given by

$$h(y,\theta_1,\theta_2,\lambda) = \lambda f_1(y,\theta_1) + (1-\lambda) f_2(y,\theta_2)$$
 (1-5)

There are several reasons for preferring (1-5) to (1-4). (1) The resulting pdf is a convex combination of pdf's and is capable of intuitively easier interpretation. (2) It is formally identical with the pdf of a random variable that is produced by a mixture of two distributions. Under the interpretation of a mixture distribution, λ may be interpreted (unlike in (1-4)) as the probability that nature has chosen pdf $f_1(y,\theta_1)$ for generating values of y. (3) No normalizing constant is required in this case and the maximization of the likelihood function becomes a relatively straightforward numerical optimization problem.

There are also some difficulties associated with using a composite pdf such as (1-5). (1) Departure from one hypothesis not in the direction of the other but in the opposite direction may yield values of λ outside the (0,1) interval which may cause some values of the density $h(y,\theta_1,\theta_2,\lambda)$ to become negative. (2) The reasonable restriction that λ not be outside the (0,1) interval means that we are attempting to estimate a boundary point of the range of λ 's; hence there will not exist an interval containing the true value of λ in which the regularity conditions guaranteeing the asymptotic normality of maximum likelihood estimates hold.

⁷See [9] and [14].

See [10], pp. 43-44. There is a singularity of a sort in the likelihood function at λ = 0 or 1 since when λ = 0, $h(y,\theta_1,\theta_2,\lambda)$ is not a function of θ_1 and when λ = 1 it is not a function of θ_2 .

In spite of some possible advantages that (1-5) may have over (1-4), it is clear that any embedding of this type retains a degree of arbitrariness, since a compound statistical model can be constructed in numerous ways. It is recognized that serious problems can arise if one type of embedding results in rejecting H_1 in favor of H_2 and another type in the reverse.

The remainder of this paper reports some computational experience with the formulation resulting from (1-5). Section 2 contains the results of some illustrative sampling experiments, while Section 3 is devoted to applying the test procedures to two concrete economic examples.

2. Some Sampling Experiments

Experiments were performed in a regression context designed to test the hypothesis that a linear regression equation generated the data as against the alternative that a linear regression equation holds for the data deflated by some other variable. Specifically, let the two hypotheses be given by

$$H_1: y_i = a_1 + b_1 x_i + u_i$$
 (2-1)

$$H_2: \frac{y_i}{z_i} = a_2 + b_2 \frac{x_i}{z_i} + \frac{v_i}{z_i}$$
 (2-2)

with u_i and v_i being distributed as $N(0,\sigma^2)$ in either case and with x_i and z_i being nonstochastic. Equ. (2-2) is equivalent to

Obviously this problem could be approached more directly by employing the residual sums of squares of a composite equation incorporating both hypotheses and of the equation incorporating only one of them. See [1], p. 327.

$$y_i = a_2 z_i + b_2 x_i + v_i$$
 (2-3)

and the density function (1-5) is then

$$h(y_{i}) = \frac{\lambda}{\sqrt{2\pi}\sigma_{1}} \exp\{-\frac{1}{2\sigma_{1}^{2}}(y_{i}-a_{1}-b_{1}x_{i})^{2}\} + \frac{(1-\lambda)}{\sqrt{2\pi}\sigma_{1}} \exp\{-\frac{1}{2\sigma_{2}^{2}}(y_{i}-a_{2}x_{i}-b_{2}x_{i})^{2}\}$$
(2-4)

Maximum likelihood estimates are obtained by maximizing

$$L = \sum_{i=1}^{n} logh(y_i)$$

$$i=1$$
(2-5)

with respect to a_1 , b_1 , σ_1 , a_2 , b_2 , σ_2 and λ .

The embedding of the parameters θ_1 and θ_2 in a larger space with the aid of λ has the consequence that we no longer test H_1 against H_2 but rather H_1 against the compound hypothesis H_3 (in which H_1 and H_2 are weighted by λ and $(1-\lambda)$ respectively) and also H_2 against H_3 . Whatever the decision criterion, the following cases may arise: (1) H_1 is rejected and H_2 is not; (2) H_2 is rejected and H_1 is not; (3) both H_1 and H_2 are rejected, (4) neither H_1 nor H_2 is rejected. The first two cases are straightforward and answer the original question of choice between H_1 and H_2 . Case (3) is equivalent to accepting the compound hypothesis H_3 . Case (4) signals that there is inadequate information to discriminate between the hypotheses.

There are at least two standard procedures that could be employed for the test procedure. First, one could attempt to estimate the asymptotic covariance matrix of the maximum likelihood estimates by 10

¹⁰See [10], pp. 52-55.

$$\left| \left| -\frac{3^2 L}{3 \hat{\theta} 3 \hat{\theta}'} \right| \right|^{-1}$$
 (2-6)

Denoting by $\hat{\lambda}$ the maximum likelihood estimate for λ and by $\hat{\sigma}_{\hat{\lambda}}$ the squareroot of the asymptotic variance for $\hat{\lambda}$, H_1 would be rejected (at some appropriate significance level) if the interval $(\hat{\lambda} - k_1 \hat{\sigma}_{\hat{\lambda}}, \hat{\lambda} + k_2 \hat{\sigma}_{\hat{\lambda}})$ did not overlap 1.0 for some appropriate positive constants k_1 and k_2 ; H_2 will be rejected if the interval does not overlap 0.0; both hypotheses will be rejected if the interval overlaps neighber 1.0 nor 0.0 and finally neither hypothesis will be rejected if the interval overlaps both 1.0 and 0.0. If asymptotic normality could be assumed, the value of 1.96 would be appropriate for k_1 and k_2 for a .05 level of significance. We shall examine the extent to which the use of 1.96 for k_1 and k_2 produces the correct statistical decision.

Secondly, we may consider the loglikelihood ratios ℓ_1 and ℓ_2 defined in (1-1) where Ω_0 is the space of parameters obtained by setting λ alternately equal to 1.0 or 0.0 and Ω is the space of all parameters. A large value of either likelihood ratio leads to rejection of the corresponding hypothesis. Since the asymptotic theorem concerning -2 ℓ alluded to in Section 1 cannot be expected to hold, we will attempt to ascertain critical values by the sampling experiments.

Sampling experiments were carried out for varying values of the number of observations n . Data were generated from (2-1) with a = b = 1.0, σ_u^2 = 20.0. The set of x's used was identical in repeated samples and was chosen from the uniform distribution over the (0,20) interval. The set of z's used was also identical in repeated samples and was chosen to be distributed uniformly over the (0.8, 1.2) interval and independently of x . Error terms were normally distributed with variance σ_u^2 . In the experiments H_1 (i.e., Equ. (2-1)) was true and H_2 was false.

The experiments were replicated as many times as was necessary to produce 30 successful replications. Failures occurred because at the point at which the maximization algorithms terminated the matrix of second partial derivatives was not always negative definite. 11

Table 1 displays the failure rate and the results of testing $\,\lambda\,\,$ directly on the assumption of asymptotic normality.

TABLE 1. Results of Sampling Experiments when H_{1} is True, Using Estimate of Asymptotic Variance of $\hat{\lambda}$.

Sample Size	Failure Rate	Fraction of Cases in Which $\lambda < .5$	Fraction of Cases in Which H is Accepted	Fraction of Cases in Which H is Accepted ²
30	.30	.400	.300	.200
60	.09	.500	.267	.267
90	.26	.067	. 567	.000
180	.29	.000	.633	.000
360	.21	.000	.833	.000

The failures appeared to be caused by flatness of the likelihood surface, making it difficult to get a good estimate of $\vartheta^2 L/\vartheta \vartheta \vartheta \vartheta$ by numerical differencing. The results employing an interval around $\hat{\lambda}$ exhibit the expected qualitative behavior but convergence is not quite as rapid as might be desired; for n = 60, for example, only 26.7 percent of the cases are decided correctly although for n = 90 and greater no wrong decisions are made and the fraction of undecided cases shrinks progressively as n increases. Less formally one might accept

Maximization employed the two algorithms described in [8] and [13].

 H_1 if $\hat{\lambda} > .5$ and H_2 otherwise. The fraction of cases in which $\hat{\lambda} \leq .5$ is also displayed and shows the correct qualitative behavior (but note the reversal between n=30 and n=60) but, again, satisfactory convergence cannot be said to have taken place for n<90.

The conjecture that the sample values of -2ℓ will not have the χ^2 distribution was tested by the Kolmogorov-Smirnov test for χ^2 distributions with, alternately, 1, 2,...,10 degrees of freedom. If the asymptotic theorem concerning -2ℓ were true, one would expect $\chi^2(1)$ to provide a good fit. This null hypothesis is categorically rejected for every value of n . For example, if in the case of n=360 we had employed the appropriate critical value at the .05 level, we would have rejected H_1 when it was in fact true in 80 percent of the cases.

The best-fitting χ^2 distributions are $\chi^2(9)$ for n=30 and, $\chi^2(8)$ for n=60 and 90. For larger values of n one must reject altogether the hypothesis of a χ^2 distribution with degrees of freedom ≤ 10 . Since it appears extremely difficult to determine exactly the distribution of -2ℓ we obtain empirically determined critical values from the sampling experiments. These are displayed in Table 2.

TABLE 2. Empirically Determined Critical Values for 21 for the .05 level

<u>n</u>	Critical Value
30	17.88
60.	14.11
90	19.32
180	13.85
360	14.90

We can now examine the behavior of the likelihood ratio based on $\rm H_2$ when $\rm H_1$ is true. Denote the loglikelihood ratios based on $\rm H_1$ and $\rm H_2$ by $\rm ^{\it l}_1$ and $\rm ^{\it l}_2$. For $\rm n=30$ and 60 the behavior of these two is very similar. For larger values of $\rm n$ the values of $\rm ^{\it l}_2$ become quite large compared to $\rm ^{\it l}_1$. If the empirically determined critical values derived from the actual sample distribution of $\rm ^{\it l}_1$ were used, the test of $\rm ^{\it H}_2$ based on $\rm ^{\it l}_2$ would have resulted correctly in rejection of $\rm ^{\it H}_2$ in 63 percent of the cases for $\rm ^{\it n}=90$, and 100 percent of the cases for $\rm ^{\it n}=180$ and 360. These empirically determined critical values may therefore be useful in performing tests of hypotheses. Since the sample distributions of $\rm ^{\it -2l}_1$ appear fairly stable for varying values of $\rm ^{\it n}$, a better estimate may be given by the average of the values in Table 2 which is 16.01. A corresponding estimate obtained by pooling the samples for different values of $\rm ^{\it n}$ is 18.08

3. Some Economic Examples.

 $\frac{\text{Klein's Model II}}{\text{by}^{12}}. \quad \text{Klein's Model II is a reduced form model which is given}$

$$\frac{y_{t}}{p_{t}} = \alpha_{0} + \alpha_{1} \frac{y_{t-1}}{p_{t-1}} + \alpha_{2} \frac{M_{t-1}}{p_{t-1}} + \alpha_{3} \left(\frac{I_{t} + G_{t} - T_{t}}{p_{t}}\right) + v_{t}$$
(3-1)

where y_t is per capita disposable income, M_t is total per capita deposits and currency outside banks, I_t is gross per capita investment, G_t is per capita government expenditures on goods and services, p_t is the cost of living index; and T_t is per capita GNP_t minus y_t . The parameters α_0 , α_1 , α_2 , α_3

¹²See [11], pp. 80-84.

are related to the original structural parameters but this relationship is of no interest here. We shall contrast the hypothesis expressed by (3-1), referred to as H_2 , with the hypothesis H_1 that the equation is in terms of money terms rather than real terms, 13 i.e., that

$$y_{t} = \alpha_{ol} + \alpha_{ll} y_{t-l} + \alpha_{2l} M_{t-l} + \alpha_{3l} (I_{t} + G_{t} - T_{t}) + u_{t}$$
 (3-2)

Equ. (3-1) is transformed to

$$y_t = \alpha_{02}p_t + \alpha_{12}y_{t-1} + \alpha_{22}M_{t-1} + \alpha_{32}(I_t + G_t - T_t) + W_t$$
 (3-3)

where u_t and w_t are both assumed to be homoscedastic. It will be assumed here that both u_t and w_t have first-order autocorrelation and maximum likelihood estimates will be obtained on this assumption. The results are therefore not directly comparable with those of Klein. Rewrite (3-2) and (3-3) as

$$y_t = f_t + u_t \tag{3-4}$$

$$y_t = g_t + w_t \tag{3-5}$$

where f_t and g_t represent the systematic parts on the right hand side of (3-2) and (3-3). The pdf's for y_t (t=2,...,n) are taken to be

$$h_{1}(y_{t}) = \frac{1}{\sqrt{2\pi}\sigma_{1}} \exp \left\{-\frac{1}{2\sigma_{1}^{2}}(y_{t}-\rho_{1}y_{t-1} - (f_{t}-\rho_{1}f_{t-1}))^{2}\right\}$$
(3-6)

$$h_2(y_t) = \frac{1}{\sqrt{2\pi}\sigma_2} \exp \left\{-\frac{1}{2\sigma_2^2} (y_t - \rho_2 y_{t-1} - (g_t - \rho_2 g_{t-1}))^2\right\}$$
 (3-7)

 $^{^{13}\}mathrm{Klein}$ was primarily interested in whether α_2 is significantly different from zero.

The density functions for y_1 are taken to be

$$h_{1}(y_{1}) = \frac{(1-\rho_{1}^{2})^{1/2}}{\sqrt{2\pi}\sigma_{1}} \exp\left\{-\frac{1}{2\sigma_{1}^{2}}(y_{1}-f_{1})^{2}\right\}$$
(3-8)

$$h_2(y_1) = \frac{(1-\rho_1^2)^{1/2}}{\sqrt{2\pi\sigma_2}} \exp \left\{-\frac{1}{2\sigma_2^2}(y_1-g_1)^2\right\}$$
 (3-9)

from which the loglikelihood function is immediately obtained. The results of maximizing it are displayed and contrasted with Klein's results in Table 3. The results

TABLE 3. Results for Klein's Model II

Coefficient	Klein's Result	Klein's Standard Error	Max. Like. Result	Max. Like. Standard Error
α _{Ol}	**	**	85.570	15.651
α_{11}	_**	* *	.073	.044
^α 21	_**	**	170	.042
^α 31	***	***	.701	.008
^α 02	186.53	*	77.310	2.082
^α 12	.30	.13	.176	.004
α22	.13	.10	258	.007
^α 32	2.36	٠35	.695	.018
ρ ₁	* *	**	.269	.341
ρ ₂	**	, **	.678	.037
λ	**	<u></u> **	.765	.116

^{*}Not reported

^{**}Not relevant

of maximum likelihood estimation for the composite pdf differs from those of Klein in that the coefficient of lagged income is negative. The $(\hat{\lambda} - 1.96 \ \hat{\sigma}_{\lambda}^{}, \ \hat{\lambda} + 1.96 \ \hat{\sigma}_{\lambda}^{})$ interval does not contain either zero or one. This suggests that the compound hypothesis should be accepted. The likelihood ratio statistic for the monetary hypothesis, $-2l_{\rm m}$, is 5.02 and for the real hypothesis, $2l_r$, is 0.02. In terms of the empirically established critical values neither pure hypothesis is rejected in favor of the compound one (although the real hypothesis seems better than the monetary one; a view that tends to be confirmed by the very small asymptotic variances associated with the estimates for the real part of the compound pdf). The first type of test suggests that the consumption function is a hybrid between a version expressed in real terms and one expressed in money terms; the second one suggests that the two pure hypotheses and the compound one are of comparable degree of acceptability. Both lend some support to the findings of Branson and Klevorick [3] that money illusion is present in the consumption function.

Chow's Model of Computer Growth. In [4] Chow fitted Gompertz and logistic curves to explain the quantity of computers used in the years 1954-1965.

Approximating derivatives by finite differences, the Gompertz formulation yields

$$\log \frac{y_{t}}{y_{t-1}} = \alpha_{01} + \alpha_{11} \log p_{t} + \alpha_{21} \log y_{t-1}$$
 (3-10)

and the logistic yields

$$\log \frac{y_{t}}{y_{t-1}} = \alpha_{02} + \alpha_{12} p_{t}^{-\beta} + \alpha_{22} y_{t-1}$$
 (3-11)

where y_t measures the quantity of computers and p_t is a price index of computers deflated by the GNP deflator.

In attacking this problem we have assumed that the error term enters both equations additively and that, following Chow, serial correlation of the error term may be disregarded. The parameter λ was associated with the Gompertz formulation. Maximum likelihood estimates as well as the squareroots of the estimated asymptotic variances are given in Table 4.

TABLE 4. Results for Chow's Model

Coefficient	Chow's Result	Chow's Standard Error	Max. Like. Result	Max. Like. Standard Error
α 01	2.950	<u>~</u> ∜	3.144	.681
α ll	364	.173	408	.196
^α 21	253	.0714	279	.070
α ₀₂	*	*	.787	.021
α_{12}	.054	.045	.054	.012
α ₂₂	-1.012x10 ⁻⁵	.608x10 ⁻⁵	-1.022x10 ⁻⁵	2.172x10 ⁻⁶
β	2.500	_ *	2.445	.188
λ	***	***	.540	.204

^{*}Not reported

The coefficients and standard errors estimated from the compound model are quite close (wherever such comparison is relevant) to the corresponding quantities estimated by Chow, particularly for the Gompertz model. The correspondence is more pronounced than for the Klein model and is presumably

^{**}Not relevant

due, at least in part, to the fact that in this case the basic statistical model has not been altered. The value of $\hat{\lambda}$ is greater than .5 and thus gives slight evidence in favor of Chow's conclusion that the Gompertz hypothesis is preferable. The interval $(\hat{\lambda}-1.96~\hat{\sigma}_{\hat{\lambda}}^2,~\hat{\lambda}+1.96~\hat{\sigma}_{\hat{\lambda}}^2)$ does not include either zero or unity and leads to an inconclusive result which is not surprising in the light of the few observations used. The value of the likelihood ratio test statistic -2% is 1.94 for the Gompertz and 19.46 for the logistic hypothesis and on the basis of the empirically established critical values discussed in Section 2 the Gompertz hypothesis is accepted and the logistic hypothesis is rejected.

4. Summary

To test the nonnested hypotheses it is proposed to transform the problem so that it becomes one of testing either pure hypothesis against a compound hypothesis obtained by weighing the pdf's of the pure hypotheses by λ and $1-\lambda$. Maximum likelihood estimates are obtained in sampling experiments and although the maximum likelihood estimates cannot be assumed to be asymptotically normal, the qualitative behavior of $\hat{\lambda}$ as well as of the likelihood ratio test statistic makes the test procedure workable. They have been applied to Klein's Model II and Chow's Model of Growth in computer demand and produce reasonable answers.

Several important questions remain for further research: (1) What is the asymptotic distribution of the maximum likelihood estimates and of the likelihood ratio statistic? (2) Are these distributions invariant with respect to sufficiently large classes of econometric models? (3) Are tests based on asymptotic distributions going to be sufficiently powerful to be useful in concrete examples? (4) What difference will result from different types of embeddings? Successful answers to even some of these may permit testing of models against specific alternatives more routinely than is now possible.

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OPTIMAL CONTROL PROGRAMS: USER'S GUIDE

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Econometric Research Program Research Memorandum No. 141
May 1972

The research described in this paper was supported by NSF Grant GS 32003X.

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OPTIMAL CONTROL PROGRAMS: USER'S GUIDE

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1. <u>Introduction</u>

This writeup describes the operation and use of two closely related programs, OPTCFULL and OPTCDIAG. The mathematical derivations and economic applications of these programs can be found in G.C. Chow, "How Much Could be Gained by Optimal Stochastic Control Policies," Memorandum No. 138, Econometric Research Program, Princeton University, April 1972, to appear in Annals of Economic and Social Measurement, October, 1972, and in G.C. Chow, "Problems of Economic Policy from the Viewpoint of Optimal Control," Research Memorandum No. 139, Econometric Research Program, Princeton University, May, 1972.

Both programs treat a linear econometric model in structural form as

$$(1.1) \quad B_{1}\overset{\sim}{y_{t}} + B_{2}\overset{\sim}{y_{t-1}} + B_{3}\overset{\sim}{x_{t}} + B_{4}\overset{\sim}{x_{t-1}} + \dots + B_{m}\overset{\sim}{x_{t-m+3}} + \overset{\sim}{b_{t}} + \overset{\sim}{u_{t}} = 0$$

where v_t is a p × l vector of dependent variables (including some lagged dependent variables if the system was originally second or higher order in these variables and has been converted to first order as required in using these programs), v_t is a q × l vector of variables subject to control, v_t summarizes the influence of all other exogenous variables which are not subject to control, and v_t is a random vector with mean zero and covariance matrix v_t . The

[&]quot;Alternative derivations for OPTCFULL can be found in G.C. Chow, Optimal Control of Linear Econometric Systems with Finite Time Horizon," <u>International Economic Review</u>, Vol. 13, No. 1 (Feb. 1972, pp. 16-25.

structural form (1.1) is converted in the programs to the reduced form:

$$(1.2) \quad \tilde{y}_{t} = -B_{1}^{-1}B_{2}\tilde{y}_{t-1} - B_{1}^{-1}B_{3}x_{t} - \cdots - B_{1}^{-1}\tilde{b}_{t} - B_{1}^{-1}\tilde{u}_{t}$$

$$= \tilde{B}_{2}\tilde{y}_{t-1} + \tilde{B}_{3}x_{t} + \cdots + \tilde{B}_{m}x_{t-m+3} + \tilde{b}_{0,t} + \tilde{u}_{t}.$$

The reduced form (1.2) is further converted into:

$$(1.3) \begin{bmatrix} \tilde{Y}_{t} \\ x_{t} \\ x_{t} \\ x_{t-m+4} \end{bmatrix} = \begin{bmatrix} \tilde{B}_{2} & \tilde{B}_{h} & \cdots & \tilde{B}_{m} \\ 0 & 0 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdot & \cdot & 1 \end{bmatrix} \begin{bmatrix} \tilde{Y}_{t-1} \\ x_{t-1} \\ x_{t-2} \\ \vdots \\ y_{t-m+3} \end{bmatrix} + \begin{bmatrix} \tilde{B}_{3} \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} x_{t} \begin{bmatrix} \tilde{b}_{0,t} \\ 0 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} \tilde{b}_{0,t} \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

or, in a more compact notation.

$$(1.4) y_{+} = A y_{+-1} + C x_{+} + B_{+} + U_{+},$$

where y_t is $p_q \times 1$, x_t remains $q \times 1$ as before, and B_t and U_t are defined by the right-most two vectors of (1.3).

In the notation of (1.4), a linear feedback control equation

$$(1.5)$$
 $x_t = G_t y_{t-1} + g_t$

is to be applied so as to minimize the expectation of the welfare cost

(1.6)
$$W = E \sum_{t=1}^{N} (y_t - z_t)' K_t (y_t - z_t)$$

where K_t is a diagonal weighting matrix, and z_t is a vector of targets to be specified by the user.

The difference between OPTCFULL and OPTCDIAG is that the latter restricts the control policy of equation (1.5) to

$$(1,7) x_t = D x_{t-1}$$

where D is diagonal. Thus each x_{it} is restricted to constant growth at the rate of d_{ii} per period (e.g. 5% growth is $d_{ii} = 1.0 \%$). Also, the OPTCDIAG program is restricted to the case $K_t = K$ in the welfare function (1.6).

2. Job Control Language and Data Requirements

The JCL (including linkage-editor control cards) for the two programs is almost identical. For OPTCFULL, the following four cards are required for use at the Princeton University Computer Center.

```
//_JOB... with T= and REG= as described below.
//OPTC_EXEC_EXFORT, PROG=OPTCFULL, DEN='U.CHOW.OPTCLIB', PARM=4K
//GO.SYSIN_DD.*
(data)
/*
```

Note that "_" indicates that at least one blank space is required. To run OPTCDIAG, simply change "PROG=OPTCFULL" on the second card to "PROG=OPTCDIAG".

The two parameters time (T=) and region (REG=) on the job card depend on the size of the model. We do not have a fixed rule to recommend to the user for setting the numbers to follow REG= and T=. However, examples with p=9, q=2, m=4, and N=10 have been successively run with REG=142K for OPTCFULL or REG=170K for OPTGDIAG, taking less than 6 seconds (on the 360/91), or T=0.10. We would recommend to the user, in case of doubt, to set higher limits for the first run than might be required, and to lower the limits in later runs. If the region is not large enough, at some point the program will run out of space and print "nK REQUIRED", perhaps several times. If the largest n is added to the region size, the program will run successfully. If the region is large enough, after every point in the program at which a block of space is allocated to work areas, "nK UNUSED" will be printed. The smallest such value may be subtracted from the region size.

The data for both programs are read in "blocks". The first block sets the dimensions and control values. Each subsequent block consists of data for one variable. We first provide a list of the dimensions and control values of the first block; the use of the control values will be explained later.

For OPTCFULL, the values which may be set are:

- P = number of \tilde{y} variables; default = 1
- Q = number of x variables; default = 1
- M = degree of the model (subscript of B_{m} in (1.1)); default = minimum = 3

N = number of time periods; default = 1

EPS = convergence criterion (ratio); default = 0.0001

EXKCAP = growth rate to be used for K, i.e.,

K_t = (growth rate).K_{t-1}; default = 1.0 (no growth)

OSUP = 1 or 2, where 2 suppresses the output of G_t and g for each period except the last and next to last; default = 1 (full output)

IU = 1 or 0 , where 0 suppresses the computations for the
 welfare cost W ; default = 1 (compute welfare)

BT = F or T, where F indicates \tilde{b}_t is a constant over t; default = F (b_t = \tilde{b})

KCS = F or T , where F indicates that only one K is provided; default = F (one K).

For OPTCDIAG, the values which may be set are:

P,Q,M,N,IU,BT,KCS: same as for OPTCFULL

DEPS = convergence criterion (ratio); default = 0.001.

The values above will be read using the "NAMELIST" feature of FORTRAN. To demonstrate the use of this feature, we give the following example:

_&DIMENS_P=9,Q=2,M=4,N=10 _EPS=0.00005 _BT=T &END

Besides "&DIMENS" on the first card and the "&END" card, one can list freely the values for P, Q, M, etc. as indicated using as many cards in between as he pleases. However, make certain not to use column 1 in punching the above cards, and leave no space on either side of the "=" signs.

Each subsequent block of data consists of a header card (giving the variable name, the format of the data cards, and comments) followed by as many data cards as are required for that variable. Matrices are read in by row. A format can be specified to make each row begin on a new card. The size of a vector or matrix is given in parentheses in the descriptions below, e.g. Bø is a vector of p elements, Bl is a p by p matrix, and B3 is a matrix with p rows of q elements. The format of the header card is

```
cc. 1-8: name, e.g. "B\phi", left-justified.
```

- cc. 9-40: (optional) format, default = (8F10.4); parentheses are not required.
- cc. 41-80: (optional) comments, which will be printed when the data is read.

The data required for OPTCFULL are as follows:

```
B/p = \tilde{b}_{t}(p) in eq. (1.1) if BT=F,

B1 = B_{1}(p,p) in eq. (1.1),

B2 = B_{2}(p,p) in eq. (1.1),

B3 = B_{3}(p,q) in eq. (1.1),

:

:

:

:

:

:

:

:

:
```

KCAP = main diagonal (p_q) of the weighting matrix K_0 in eq. (1.6) if KCS=F (note: $p_q = p + (m-3) \times q$),

 $Z\dot{p}$ = initial targets $z_0(p+q)$ in eq. (1.6), and

ZRATE = rates of growth (p+q) for the current components of z_t , i.e. $z_t = (ZRATE).z_{t-1}$. If IU=1 is used (default), two more data blocks are required next:

$$Y_0 = Y_0(p_q)$$
 in eq. (1.4) = $[\tilde{y}_0(p), x_0(q), ..., x_{-(m-4)}(q)]$
in eq. (1.5),

$$V = \tilde{V}(p,p) = E(\tilde{u}_t^T \cdot \tilde{u}_t)$$
.

If KCS=T is specified in the &DIMENS block, it indicates that more than one K is to be used for the same model and data. In this case the data for K is not put in its regular place but is placed behind all other data blocks. Each K to be used must be in a separate data block, headed by a separate header card. The header card for each block is printed as a sub-title on each page of the output, inviting the user to put comments on the header card as he wishes.

If BT=T is specified in the &DIMENS block, it indicates a time-variant intercept for equation (1.1). We have chosen to express \tilde{b}_t as

$$\tilde{b}_{t} = F / + BINCR \times BFACT_{t}$$
.

The B\$\phi\$ data is now the B\$\phi\$ in the above equation. Two more data blocks follow the B\$\phi\$ blocks:

BINCR = BINCR(p) above, and

BFACT = BFACT(N)=(BFACT₁(1),...,BFACT_N(1)) above.

The data required for OPTCDIAG is the same as that for OPTCFULL except that Y/p is always given (following ZRATE) and initial estimates of the main diagonal of D in eq. (1.7) must be given after Y/p as follows:

 $D\phi$ = initial estimates (q) of D in eq. (1.7).

The data for V is still conditional on IU as with OPTCFULL.

3. Output

As the data block for each variable is read, the header card and data are printed. Following this is the printout of the reduced form, as both equations (1.2) and (1.4), where the Y vector includes all the X_t, X_{t-1}, \ldots vectors except the last, i.e. up to $X_{t-(M-4)}$.

The OPTGFULL program solves for $G_{\mathsf{t}}(\mathsf{GCAP})$ and $g_{\mathsf{t}}(\mathsf{G})$ by the following equations:

$$HCAP_{N} = KCAP_{N}$$
 $H_{N} = KCAP_{N} Z_{N}$

For t = N, N-1, ..., 1:

$$CTHC_{t} = (C^{T} * HCAP_{t} * C)^{-1}$$

$$CH_{t} = CTHC_{t} * C^{T}$$

$$GCAP_{t} = CH_{t} * HCAP_{t} * A$$

$$G_{t} = CH_{t} * (H_{t} - HCAP_{t} * B_{t})$$

Output Gt, Ht, GCAPt HCAPt

$$R_t = A + C * GCAP_t$$

It then calculates the \bar{y}_t resulting from this policy using eq. (1.4) and eq. (1.5), omitting the random residuals, i.e.,

$$\ddot{y}_{t} = A \cdot \ddot{y}_{t-1} + C(G_{t} \ddot{y}_{t-1} + G_{t}) + B_{t}$$

Finally, the program calculates the estimated covariance matrices $\Gamma_{\mbox{t}}$ and welfare, both stochastic and deterministic using

$$\begin{split} &\Gamma_{\text{O}} = \text{O} \\ &R_{\text{t}} = \text{C} * \text{GCAP}_{\text{t}} + \text{A} \\ &\Gamma_{\text{t}} = R_{\text{t}} * \Gamma_{\text{t-1}} * R_{\text{t}}^{\text{T}} + \text{V} \\ &\text{stochastic} \quad \textbf{W}_{\text{t}} = \text{tr} \left(\text{KCAP}_{\text{t}} * \Gamma_{\text{t}} \right) \\ &\bar{\textbf{u}}_{\text{t}} = \bar{\textbf{y}}_{\text{t}} - \textbf{z}_{\text{t}} \\ &\text{deterministic} \quad \textbf{W}_{\text{t}} = \bar{\textbf{u}}_{\text{t}}^{\text{T}} * \text{KCAP}_{\text{t}} * \bar{\textbf{u}}_{\text{t}} \\ &\text{total} \quad \textbf{W}_{\text{t}} = \text{stochastic} \quad \textbf{W}_{\text{t}} + \text{deterministic} \quad \textbf{W}_{\text{t}} \end{split} .$$

The OPTGDIAG program uses GRADX to minimize the average deterministic welfare over the N periods. The \bar{y}_t , estimated covariance matrices, and welfare are then printed as for OPTCFULL above.

4. Programmer's Guide to OPTCFULL and OPTCDIAG

The structure of OPTCFULL is:

OPTGF1 reads the &DIMENS data block and calls the following subroutines to read the rest of the data:

READBS : read BØ, Bl....

READKC: read KCAP

READZS : read ZØ, ZRATE

READY ϕ : read Y ϕ READV: read V

After all the data have been read (unless KCS=T) the computation proceeds by calling the following subroutines:

BSOLVE : solve for reduced form

GENACB : set up A, C, B

EXTNDZ : extend z

GENZTS : generate z_t

OPTGF6 : compute policy

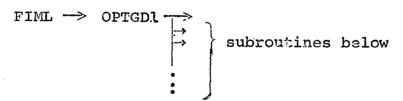
GENV : extend \tilde{V} to V

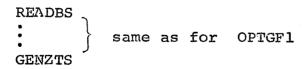
OPTGF7 : generate \bar{y}_t

WLFARE : compute welfare

PLOTYZ : plot \bar{y}_t vs. z_t

The structure of OPTCDIAG is similar:





OPTGD6
$$\rightarrow$$
 OPGD62 \rightarrow INFUNC : initialize f(D)
 \mid GRADX \rightarrow FUNC : minimize f(D)

GENV
WLFARE } same as for OPTGF]
PLOTYZ

For an explanation of the calling technique for GRADX, see the Appendix "The FUNC subroutine for POWELL or GRADX".

Several subroutines used by OPTCFULL and OPTCDIAG were originally written for the FIML program, as described in "Full-Information Maximum Likelihood Program: User's Guide," by Douglas R. Chapman and Ray C. Fair, issued as Research Memorandum No. 137, Econometric Research Program, Princeton University, April, 1972. Those subroutines used without any modifications are PRMAT8, DFORM, CLEAR, AMOVE, and CUTIME. Those adapted for OPTC are MNALOC (MNCHEK), LINECK (NEWPG, SBTITL) and PLOTYZ. The Appendix "Dynamic allocation using \mbox{MNALOC}^n explains the FIML main program and the use of the vector MAINAR and the subroutine MNALOC. The routines BINBCD and MOVSTR are assembler language routines taken from the F 14STAT package. Extensive use is made of the MATOPS package of matrix operators (actually written for the OPTC programs) which is described in the Appendix "The MATOPS matrix operators." GRADX subroutine used is a version originally modified for FIML and used by OPTC without further modification. The only changes for FIML were to put variable dimensions throughout the routine.

In order to link-edit either OPTCFULL or OPTCDIAG, four libraries must be used:

- 1. "U.CHOW.OPTCLIB", containing all OPTC subroutines and those taken from F4STAT or modified from FIML,
- 2. "U.CHOW.MATOPS", containing the MATOPS package,
- 3. "U.FIML.LIBRARY", containing the subroutines used from FIML without modification, and
- 4. "U.FIML.GRADX", containing the version of GRADX modified for FIML (required only for OPTCDIAG).

Subroutines in these libraries are link-edited individually using the "NCAL" option (see the appendix "Compiling programs into a Library"). The JCL and linkage-editor control cards to combine the subroutines into OPTCFULL are as follows:

```
//OPTCLINK_EXEC_FORTGL
//LKED.SYSLIB_DD_DISP=SHR, DSN=U.CHOW.OPTCLIB
//_
              DD DISP=SHR, DSN=U, CHOW, MATOPS
//_
              DD DISP=SHR, DSN=U.FIML.LIBRARY
//_
              DD_DISP=SHR, DSN=U.FIML.GRADX
              DD_DISP=SHR, DSN=SYS1.FORTLIB
//LKED.SYSLMOD_DD_DISP=OLD, DSN=U. CHOW. OPTCLIB, SPACE=
//LKED.GETMAIN_DD_DISP=SHR.DSN=U.FIML.GETMAIN
//LKED.SYSIN_DD_*
_CHANGE_FIML(OPTCFULL)
_CHANGE_FIML1(OPTGF1)
_INCLUDE_GETMAIN(FIML)
_ENTRY_FIML
NAME OPTCFULL(R)
/*
```

To link-edit OPTCDIAG, the LKED.SYSIN cards should be:

```
_CHANGE_FIML(OPTCDIAG)
_CHANGE_FIML1(OPTGD1)
_INCLUDE_GETMAIN(FIML)
_ENTRY_OPTCDIAG
_NAME_OPTCDIAG(R)
```

5. List of Appendices

The following Appendices can be obtained from the Econometric Research Program, Princeton University, 207 Dickinson Hall, Princeton, New Jersey,

- A. The FUNC Subroutine for POWELL or GRADX
- B. Dynamic Allocation Using "MNALOC"
- C. The MATOPS Matrix Operators
- D. Compiling Programs into a Library