Issued Under Office of Naval Research Contract No. Nonr- 1858(16)

EXISTENCE OF STABLE PAYOFF CONFIGURATIONS FOR COOPERATIVE GAMES

Morton Davis and Michael Maschler

Econometric Research Program Research Memorandum No. 38 11 June 1962

The research described in this paper was supported partially by the Office of Naval Research and partially by The Carnegie Corporation of New York. Reproduction, translation, publication, use and disposal in whole or in part by or for the United States Government is permitted.

Princeton University
Econometric Research Program
92-A Nassau Street
Princeton, N. J.

1. Introduction.

In R. J. Aumann and M. Maschler [1], a theory was developed to attack the following general question: If the players in a cooperative n-person game have decided upon a specific coalition-structure, how then will they distribute among themselves the values of the various coalitions in such a way that some stability requirements will be satisfied. Several criteria for the "stable" splits were given, centering upon the idea that a "stable" payoff should offer the players some security in the sense that each "objection" could be met by a "counter objection." A variety of concepts of objections and counter objections were suggested, and one of them was studied in more detail. This one, and some of the others, had the feature that for some coalition-structures there were no stable payoffs, and therefore these coalition-structures could not be used by those players who wished stability in this sense. (See also [6].) Moreover, cases were established in which even a coalition-structure which yields the maximum total amount to all the players had no stable outcome. In particular, an example was given in [1] of a game with a superadditive, non-negative, non-identically zero characteristic function, in which no outcome was stable unless each player received a zero amount.

It is conceivable that many would reject such an outcome on the ground that "rational" players in a superadditive game would always agree on an imputation, because otherwise they can all benefit by switching to an appropriate imputation.

We do not share this opinion, for we feel that often a desire for security is stronger than a wish to make some extra profit. In fact, many profitable coalitions in everyday life are never realized because the "players" do not consider them safe. Nevertheless, we do believe that in

some cases, especially if large profits are at stake, people may be willing to <u>relax</u> their safety requirements in order to make more out of a game.

It is therefore of interest to develop a theory in which safety requirements are so relaxed that there always exist stable imputations in a superadditive game. We shall prove that this is indeed the case for one of the variants proposed in [1]. Moreover, we conjecture that this variant always provides stable outcomes for each choice of a coalition-structure. We are able to prove this conjecture for those coalition-structures in which each coalition does not contain more than three players.

The key theorem, very interesting in itself, states that each outcome induces a partial "order" relation among the players which is asymmetric and never intransitive (however, it is not necessarily transitive).

This phenomenon, which, e.g., does not occur in the von Neumann-Morgenstern concept of domination, is "just enough" for proving various existence theorems.

The necessary definitions are stated to make the paper self-contained.

We are grateful to Dr. Martin Arkowitz for helpful discussions during our research.

2. Basic Definitions.

We consider an n-person cooperative game Γ , described by a set $\mathbb{N} \equiv \{1,\,2,\,\ldots,\,n\}$ of n players and a real function v(B) defined for each non-empty subset B of N . B is called a coalition and v(B) is its value. The function v(B) is known as the characteristic function of the game. It is not necessarily superadditive.

The theory allows also for the possibility that some non-1-person coalitions are not permissible. If B is such a coalition, we simply agree that v(B)=0, and modify slightly the permissible outcomes.

There will be no loss of generality if we assume that

(2.1)
$$v(B) \ge 0$$
 and $v(i) = 0$ for each i, $i = 1, 2, ..., n$.

An $\underline{\text{outcome}}$ of a game Γ is represented by a $\underline{\text{payoff configuration}}$ tion (p.c.)

(2.2)
$$(x; \mathcal{B}) \equiv (x_1, x_2, ..., x_n; B_1, B_2, ..., B_m)$$

Here, $\mathcal{B} \equiv B_1, B_2, \ldots, B_m$ is the <u>coalition-structure</u>, and hence satisfies

(2.3)
$$B_j \cap B_k = \emptyset$$
 for all $j, k, j \neq k$, and $U B_j = N$,

and $x = (x_1, x_2, ..., x_n)$ represents the <u>payoff vector</u> according to which player i receives in the outcome the amount x_i , i = 1, 2, ..., n. We assume that each coalition makes full use of its value, and therefore x is required to satisfy

(2.4)
$$\sum_{i \in B_{j}} x_{i} = v(B_{j})$$
, $j = 1, 2, ..., m$.

We also require that each outcome is individually rational, i.e., that

(2.5)
$$x_i \ge 0$$
 for each i, i = 1, 2, ..., n.

Thus, for each fixed coalition-structure $\mathcal{Z} \equiv B_1, B_2, \dots, B_m$, the set of all possible payoff vectors consists of a cartesian product of m simplices

$$S = S_1 \times S_2 \times \dots \times S_m,$$

where, in view of (2.4) and (2.5),

(2.7)
$$S_{j} = \left\{ \left\{ x_{i} \right\}_{i \in B_{j}} \mid \sum_{i \in B_{j}} x_{i} = v(B_{j}), x_{i} \geq 0 \right\}, j = 1, 2, ..., m.$$

Let $(x; \mathcal{B})$ be an individually rational payoff configuration (i.r.p.c.), (2.2) and (2.5), in a game Γ , and let k and ℓ be two distinct members of a coalition ℓ B, of \mathcal{B} .

This requires, of course, that B contains more than one player.

For a coalition C and a distribution $\{y_i\}$, $i \in C$, of its value among its members, the pair $(\{y_i\}; C)$ is called an <u>objection</u> of k against ℓ in $(\boldsymbol{x}; \mathcal{B})$, if

(2.8)
$$k \in C$$
, $\ell \notin C$, k , $\ell \in B_1$,

$$(2.10)^{1} y_{k} > x_{k}, y_{i} \ge x_{i} for all i, i \in C.$$

Let $(x; \mathcal{B})$ be an i.r.p.c. (2.2) and (2.5), in a game Γ and let $(\{y_i\}; C)$ be an objection of a player k against a player ℓ in $(x; \mathcal{B})$, (2.8), (2.9) and (2.10). For a coalition D and a distribution $\{z_i\}$, $i \in D$, of its value among its members, the pair $(\{z_i\}; D)$ is called a <u>counter objection</u> to the above objection, if

(2.11)
$$\ell \in D$$
, $k \notin D$,

(2.12)
$$\sum_{i \in D} z_i = v(D),$$

$$(2.13) zi \ge xi for all i , 1 \in D ,$$

(2.14)
$$z_i \ge y_i$$
 for all i , $i \in DC$.

Definition 2.1 An i.r.p.c. $(\boldsymbol{x}; \boldsymbol{\mathcal{B}})$ in a game Γ is called stable $(\mathcal{M}_{l}^{(i)}$ - stable), if for each objection there exists a counter objection.

The set of all the stable p.c.'s is called the <u>bargaining set</u> 2

It will be of advantage to introduce a "strength" relation among the players, which corresponds to each i.r.p.c.

No loss of generality will be caused if we assume that all the inequalities are strict.

This is one of several variants mentioned in R. J. Aumann and M. Maschler [1]. Although formulated differently, it is actually the same as \mathcal{M}_1 of [1], with the coalitional rationality requirement being replaced by individual rationality. The definition in [1], however, "sounds" more general. (See [6].)

Definition 2.2 Let $(x; \mathcal{B})$ be an i.r.p.c., (2.2) and (2.5), for a game Γ . Let k and ℓ be two players in a coalition B_j of \mathcal{B} . We say that player k is stronger than player ℓ in $(x; \mathcal{B})$, and we denote this by $k > \ell$, if player k has an objection against player ℓ , which cannot be countered.

We say that a player k is equal to player ℓ in $(x; \mathcal{B})$, and denote this by $k \sim \ell$, if $k \not > \ell$ and $\ell \not > k$. ($\not >$ means "not stronger than").

Obviously, an i.r.p.c. $(x; \mathcal{B})$ is stable in a game Γ if and only if in each coalition of \mathcal{B} , each player is equal to each other player who belongs to the same coalition.

In the next section we shall study some properties of the relation > .

3. Weak Partial Order.

Definition 3.1 A binary relation \mathcal{R} will be called a <u>weak partial order</u>, if it is never intransitive. I.e., if

$$(3.1) \qquad {}^{A_{1}\mathcal{H}} {}^{A_{2}}, \quad {}^{A_{2}\mathcal{H}} {}^{A_{3}}, \quad \dots, \quad {}^{A_{\alpha-1}\mathcal{H}} {}^{A_{\alpha}} \Longrightarrow {}^{\sim} {}^{A_{\alpha}\mathcal{H}} {}^{A_{1}}.$$

It will be shown subsequently that \succ is such a relation, hence this relation may enter everyday situations in a natural way.

Certainly $\mathcal R$ can be imbedded in a partial order relation $\mathcal R^*$ by defining $A_1 \mathcal R^* A_{\alpha}$ whenever $A_1 \mathcal R A_{\alpha}$ or a sequence $A_1, A_2, \ldots, A_{\alpha}$ exists, which satisfies the left-hand side of (3.1). However, it is not always advisable to replace $\mathcal R$ by $\mathcal R^*$, if one wishes to derive theorems concerning $\mathcal R$ itself.

It follows from (3.1) that a weak partial order is an asymmetric and an irreflexive relation.

Let \measuredangle be a binary relation defined by:

(3.2)
$$A_{\nu} \mathcal{L}_{\mu}$$
 if and only if $\sim A_{\nu} \mathcal{R}_{\mu}$ and $\sim A_{\mu} \mathcal{R}_{\nu}$,

then \mathscr{L} is a reflexive and symmetric relation (but not necessarily transitive). Certainly, the relation [\mathscr{H} or \mathscr{L}] is complete.

Let $(x;\mathcal{B})$ be an i.r.p.c., (2.2) and (2.5), for a game Γ , and let C be a coalition. Then the expression

(3.3)
$$e(C) = v(C) - \sum_{i \in C} x_i$$

will be called the excess of the coalition C in $(x; \mathcal{B})$. Clearly, this excess, if it is positive, is the supremum of the amounts with which a player in C can "manoeuvre," if he claims an objection by forming the coalition C.

Lemma 3.1 Let $(x; \mathcal{B})$ be an i.r.p.c., (2.2) and (2.5), for a game Γ , and let k and ℓ be two distinct players in a coalition B_j of \mathcal{B} .

Suppose that player k has an objection $(\{y_i\}; C)$ against player ℓ , and that this objection cannot be countered. Under these conditions, any coalition D for which

(3.4)
$$\ell \in D , e(D) \geq e(C)$$

must contain player k .

Proof: Certainly, by (2.9) and (2.10), e(C) > 0 and therefore e(D) > 0 . If k $\not\in$ D , then (2.11) is satisfied. Player ℓ can then counter-object by ($\{z_i\}$; D) , where

$$\begin{cases} x_i & \text{for } i \in D - C, i \neq \ell, \\ y_i & \text{for } i \in D \cap C \\ v(D) - \sum_{i \in D - \{\ell\}} z_i & \text{for } i = \ell. \end{cases}$$

Indeed, it remains to show that (2.13) is satisfied for $i = \ell$. Actually,

$$z_{\ell} - x_{\ell} = v(D) - \sum_{i \in D - \{\ell\}} z_i - x_{\ell} = v(D) - \sum_{i \in D \cap C} y_i - \sum_{i \in D - C} x_i = v(D)$$

$$v(\textbf{D}) - v(\textbf{C}) + \sum_{\textbf{i} \in \textbf{C} - \textbf{D}} \textbf{y}_{\textbf{i}} - \sum_{\textbf{i} \in \textbf{D} - \textbf{C}} \textbf{x}_{\textbf{i}} \geq v(\textbf{D}) - v(\textbf{C}) + \sum_{\textbf{i} \in \textbf{C} - \textbf{D}} \textbf{x}_{\textbf{i}} - \sum_{\textbf{i} \in \textbf{D} - \textbf{C}} \textbf{x}_{\textbf{i}} = e(\textbf{D}) - e(\textbf{C}) \geq 0 .$$

This contradicts the assumption that the objection cannot be countered.

Theorem 3.1 Let $(x; \mathcal{B})$ be an i.r.p.c., (2.2) and (2.5), for a game Γ ; then the relation \rightarrow in $(x; \mathcal{B})$ (see Definition 2.2) induces a weak partial order (see Definition 3.1) among the members of each coalition in \mathcal{B} .

<u>Proof:</u> Let B_j be a coalition in $\mathcal B$, and suppose that the relation \succ is not a weak partial order among the players in a coalition B_j of $\mathcal B$. Without loss of generality we can assume that B_j contains the players $1, 2, \ldots, t$, and that in $(x;\mathcal B)$,

$$(3.6) 1 > 2, 2 > 3, ..., t-1 > t, t > 1.$$

Example 3.1 Let Γ be a 5-person game with the characteristic function v(123) = 30, v(14) = 40, v(35) = 20, v(245) = 30, v(B) = 0 otherwise; and consider the p.c. (10, 10, 10, 0, 0; 123, 4, 5). In this p.c., 1 > 2, because player 1 can object against player 2 by ((11, 29); 14) and this

objection cannot be countered. Similarly, 2 > 3, the objection being ((11, 1, 18); 245). On the other hand $1 \sim 3$. This example shows that the relation > is not necessarily transitive.

Example 3.2 Let Γ be a 5-person game with the characteristic function: v(123) = 30, v(14) = 30, v(34) = 20, v(25) = 30, v(B) = 0 otherwise. Clearly, $1 \sim 2$, $2 \sim 3$, but 1 > 3 in the p.c. (10, 10, 10, 0, 0; 123, 4, 5). This shows that the relation \sim is not necessarily transitive.

4. Making a Coalition Stable.

Definition 4.1 Let $(x; \mathcal{B})$ be an i.r.p.c., (2.2) and (2.5), for a game Γ , and let B_j be a coalition in \mathcal{B} . We shall say that the coalition B_j is stable with respect to $(x; \mathcal{B})$, if each player in B_j is equal to each other player in B_j .

Clearly, an i.r.p.c. $(x; \mathcal{B})$ is stable if and only if all the coalitions in \mathcal{B} are stable.

Theorem 4.1 Let $(\boldsymbol{x};\boldsymbol{\mathcal{B}})$ be an i.r.p.c. (2.2) and (2.5), for a game Γ , and let B_j be a fixed coalition in $\boldsymbol{\mathcal{B}}$. It is possible to modify the payoffs to the players in B_j , without changing the other payoffs and the coalition-structure, in such a way that B_j will be stable with respect to the modified p.c.

<u>Proof:</u> There is no loss of generality in assuming that the coalition B_j consists of the players 1, 2, ..., t. We know that all the possible payoffs to the members of B_j constitute the simplex S_j defined by (2.7), (j being fixed). To each point $\boldsymbol{z}^* = (x_1^*, x_2^*, \ldots, x_t^*)$ in S_j there corresponds an i.r.p.c. $(\hat{\boldsymbol{z}}; \boldsymbol{\mathcal{Z}})$, where

(4.1)
$$\hat{x}_{i} = \begin{cases} x_{i}^{*} & \text{for all } i, i \in B_{j} \\ x_{i} & \text{for all } i, i \notin B_{j} \end{cases} .$$

Let $E_{\upsilon} \equiv E_{\upsilon}(\{x_{i}\}_{i \notin B_{j}}; \mathcal{B})$, $\upsilon = 1, 2, ..., t$, be the set of points $\boldsymbol{z} *, \boldsymbol{x} * \boldsymbol{\epsilon} S_{j}$, for which player υ is stronger than or equal to $(\boldsymbol{\geq})$ all the players i, $i \in B_{j}$, in the p.c. $(\hat{\boldsymbol{z}}; \mathcal{B})$. The theorem will be proved if we show that $(4.2) \qquad M_{j} \equiv M_{j}(\{x_{i}\}_{i \notin B_{j}}; \mathcal{B}) \equiv \bigcap_{\upsilon = 1}^{t} E_{\upsilon} \neq \emptyset$.

In order to show this, note first that the face $x_{v}=0$ of the simplex S_{j} is contained in E_{v} , $v=1,\,2,\,\ldots$, t. Indeed, if $x_{v}=0$ in $(\hat{x};\mathcal{B})$, then, by (2.1), player v can counter object to each objection raised against him (if such exists) by ({0}; v).

We shall now show that

Indeed, suppose that there exists a point \boldsymbol{z}^* in S_j which is not in this union, then there exist players i_1, i_2, \ldots, i_t in B_j such that in $(\hat{\boldsymbol{z}}; \boldsymbol{\mathcal{B}})$

(4.4)
$$1 < i_1, 2 < i_2, ..., t < i_t .$$

This violates the non-intransitivity property of the relation > . (See Theorem 3.1.) Thus, (4.3) holds. Applying now the lemma of B. Knaster, C. Kuratowski, and S. Mazurkiewicz [4], usually used to prove in a direct way the Brouwer fixed-point theorem (see also Kuratowski [5]), (4.2) follows immediately. This completes the proof of the theorem.

Corollary 4.1 An important consequence of this lemma is that if the characteristic function is superadditive, then there always exists an imputation x, such that (x; N) is stable.

We conjecture that to each coalition-structure ${\cal B}$, there is a payoff vector ${\bf x}$ such that $({\bf x};{\bf B})$ is stable. It seems that in order

We define \prec in the obvious way.

to prove this, one has to know more properties of $\,^{M}_{j}$. We shall state some of the properties we have in mind in the next section, and verify them in some cases.

Theorem 4.2 The set M_j , defined by (4.2), is a union of a finite number of closed convex polyhedra.

Proof: Let $F_{\mu\nu} \equiv F_{\mu\nu}(x_{t+1}, x_{t+2}, \dots, x_n;)$ be the set of points $\mathcal{Z} *, \mathcal{X}^{*} \in S_j$, for which player μ is stronger than or equal to player ν , in the p.c. $(\hat{\mathcal{X}}; \mathcal{B})$ (see (4.1)). μ , $\nu \in B_j$. If we prove that $F_{\mu\nu}$ is a union of a finite number of closed convex polyhedra, then so also will M_j be , because

By a well-known theorem in logic it follows (see [1], Theorem convex 2.1) that $F_{\mu\nu}$ is a union of a finite number of polyhedra. We shall prove that it is closed by showing that its complement is open. Indeed, if \varkappa * belongs to the complement of $F_{\mu\nu}$, with respect to S_j , then player ν has an objection ($\{y_i\}; C$) against player μ , which cannot be countered. Without loss of generality, we can assume that $y_i > x_i$ for all i, $i \in C$. (See footnote to (2.10).) Let z_μ be the maximum amount that player μ can assure himself by paying each other member of a coalition D, $\mu \in D$, $\nu \not\in D$, the amount x_i if this member is in D-C and y_i if he is in $D\cap C$. $0 \le z_\mu < x_\mu$, because the objection cannot be countered. Let $\delta = \min\{x_\mu - z_\mu, y_i - x_i : i \in C\}$, then $\delta > 0$. Any point of S_j which is in a δ/n - neighborhood of \varkappa * also belongs to the complement of $F_{\mu\nu}$, because at such a point ($\{y_i\}; C$) is still an objection which cannot be countered. This completes the proof.

Corollary 4.2 The set $G_{\mu\nu} \equiv G_{\mu\nu}(x_{t+1}, \ldots, x_n; \mathcal{B})$ of points $\boldsymbol{x} *$ in S_j , for which player μ is stronger than player ν in $(\hat{\boldsymbol{x}}; \mathcal{B})$ is open in S_j , ν , $\mu \in B_j$.

5. The Existence Problem.

We shall now generalize somewhat a theorem due to von Neumann [7]. We shall employ Kakutani's method of proof [3], but we shall make use of the S. Eilenberg and D. Montgomery sharper fixed-point theorem [2]:

<u>Lemma 5.1</u> (von Neumann theorem for m = 2).

Let S_1 , S_2 , ..., S_m be m bounded closed acyclic polyhedra n_1 , n_2 in the euclidean spaces n_1 , n_2 , ..., n_m , respectively. Let us consider their cartesian product $T \equiv S_1 \times S_2 \times \ldots \times S_m$ in $n_1 + n_2 + \cdots + n_m$, and let $T_i \equiv S_1 \times S_2 \times \ldots \times S_{i-1} \times S_{i+1} \times \ldots \times S_m$ be the respective cartesian product in $n_1 + n_2 + \cdots + n_{i-1} + n_{i+1} + \cdots + n_m$, $n_1 + n_2 + \cdots + n_{i-1} + n_{i+1} + \cdots + n_m$, $n_2 + \cdots + n_{i-1} + n_{i+1} + \cdots + n_m$, $n_3 + n_4 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_4 + n_5 + \cdots + n_{i+1} + \cdots + n_m$, $n_5 + \cdots + n_5 + \cdots + n_m$, $n_5 + \cdots + n_5 + \cdots + n_5 + \cdots + n_m$, $n_5 + \cdots + n_5 + \cdots +$

<u>Proof:</u> We define a point-to-set mapping $\varkappa \to \phi(\varkappa)$, of T into itself, as follows:

$$(5.1) \quad \phi(x) = \phi(x_1, x_2, ..., x_m) = V^{(1)}(x^{(1)}) \times V^{(2)}(x^{(2)}) \times ... \times V^{(m)}(x^{(m)}).$$

This mapping is upper-semi-continuous because the sets U_1 , U_2 , ..., U_m are closed. The image of each point is a cartesian product of acyclic closed polyhedra; hence it is an acylic polyhedron, and so is T itself.

I.e., connected polyhedra whose homology groups of order ≥ 1 vanish.

This lemma can further be applied for absolute neighborhood retracts.

Therefore, by the Eilenberg and Montgomery fixed-point theorem [2], there exists a point $\xi \equiv \{\xi_1, \, \xi_2, \, \dots, \, \xi_m\}$ in T, such that $\xi \in \emptyset(\xi)$. In other words, the components $\xi_1, \, \xi_2, \, \dots, \, \xi_m$ satisfy $\xi_i \in S_i$, $\xi_i \in V^{(i)}(\xi^{(i)})$, $i=1,\,2,\,\dots,\,m$; therefore, $\xi \in U_1 \cap U_2 \cap \dots \cap U_m$. This completes the proof.

Theorem 5.1 Let $\mathcal{B} = B_1$, B_2 , ..., B_m be a fixed coalition-structure (2.3)

for a game Γ , and let $(\boldsymbol{x}; \mathcal{B})$ be an arbitrary i.r.p.c., (2.2) and (2.5).

Let $M_j = M_j(\{x_i\}_{i \notin B_j}; \mathcal{B})$ be the set of points $\boldsymbol{x} * , \boldsymbol{x} * \in S_j$, defined by (2.7), for which B_j is stable with respect to $(\hat{\boldsymbol{x}}; \mathcal{B})$, defined by (4.1).

If, for each choice of j, $j = 1, 2, \ldots, m$, and for each choice of $(\boldsymbol{x}; \mathcal{B})$, the set M_j is acyclic, then there exists a stable p.c. $(\xi_1, \xi_2, \ldots, \xi_n; \mathcal{B})$ having \mathcal{B} as a coalition-structure.

Proof: Let U_j , $j=1, 2, \ldots, m$ be the set of points \boldsymbol{z} in $S=S_1\times S_2\times \ldots \times S_m$ for which B_j is stable. Clearly, the sets $V^{(j)}$ defined in Lemma 5.1 are now the sets M_j , $j=1, 2, \ldots, m$. Thus, the sets U_j , $j=1, 2, \ldots, m$, have a non-empty intersection. This intersection is precisely the set of points \boldsymbol{z} in S such that $(\boldsymbol{z};\boldsymbol{z})$ is stable.

In some cases we are able to show that $\,^{M}_{j}\,$ is indeed acyclic. The following lemma will be of much use.

Lemma 5.2 Let $\mathcal{B} \equiv B_1$, B_2 , ..., B_m be a fixed coalition-structure for a game Γ , and suppose that B_1 consists of the players 1, 2, ..., t.

Let $(x;\mathcal{B}) \equiv (x_1, x_2, \ldots, x_t, x_{t+1}, \ldots, x_n; B_1, B_2, \ldots, B_m)$ and $(\xi;\mathcal{B}) \equiv (\xi_1, \xi_2, \ldots, \xi_t, x_{t+1}, \ldots, x_n; B_1, B_2, \ldots, B_m)$ be two i.r.p.c.'s.

Denote by P the set of players i, different from player 2, for which $\xi_i > x_i$. If

By Theorem 4.2, we know that it is a closed polyhedron.

(5.2)
$$\xi_1 \leq x_1, \xi_2 \geq x_2,$$

(5.3)
$$x_1 - \xi_1 \ge \sum_{i \in P} (\xi_i - x_i),$$

(5.4)
$$1 > 2 \quad \underline{\text{in the p.c.}} (x; \mathcal{B}),$$

then

(5.5)
$$1 > 2$$
 also in the p.c. $(\xi; \mathcal{B})$.

Proof: Since $\xi_1 + \xi_2 + \cdots + \xi_t = x_1 + x_2 + \cdots + x_t = v(B_1)$ (see (2.4)), (5.3) is equivalent to

(5.6)
$$\xi_2 - x_2 \ge \sum_{i \in Q} (x_i - \xi_i),$$

where Q is the set of players i , different from player 1 , for which $x_{i} > \xi_{i} \text{ . Intuitively, (5.3) and (5.6) will make it "easier" for player 1}$ to object against player 2, and "more difficult" to counter object.

Let $(\{y_i\}; C)$ be an objection of player 1 against player 2 in $(z; \mathbf{Z})$, which cannot be countered. Thus, (2.8), (2.9) and (2.10) hold for k = 1, $\ell = 2$. We shall form an objection $(\{\eta_i\}; C)$ of player 1 against player 2 in $(\xi; \mathbf{Z})$ as follows:

(5.7)
$$\eta_{i} = \begin{cases} \text{Max}(y_{i}, \xi_{i}) & \text{for all } i, i \neq 1, i \in C \\ v(C) - \sum_{i \in Q - \{1\}} \eta_{i} & \text{for } i = 1. \end{cases}$$

Clearly, (2.8) and (2.9) are satisfied for $k=1, \ell=2$, and so is (2.10) for $i \neq 1$. Checking the case i=1, we find, by (5.7), that

$$\eta_1 = v(C) - \sum_{i \in C - \{1\}} \eta_i = v(C) - \sum_{i \in E} y_i - \sum_{i \in F} \xi_i$$
,

where E (F) is the set of players i, i \neq 1, i \in C, for which $y_i \geq \xi_i$ ($\xi_i > y_i$). Certainly F (P, hence, by (2.9), (2.10) and (5.3),

$$\eta_{\text{l}} - \xi_{\text{l}} = y_{\text{l}} + \sum_{\text{i} \in F} y_{\text{i}} - \sum_{\text{i} \in F} \xi_{\text{i}} - \xi_{\text{l}} > x_{\text{l}} - \xi_{\text{l}} - \sum_{\text{i} \in F} (\xi_{\text{i}} - x_{\text{i}}) \ge 0 \text{.}$$

This objection cannot be countered. Indeed, if $(\{\zeta_i\}; D)$ is a counter objection, then (2.11) - (2.14) are satisfied for $k=1, \ell=2, x_i, y_i, z_i$ being respectively replaced by ξ_i, η_i, ζ_i , $i \in D$. Consider the payoff $\{z_i\}$, $i \in D$, defined by

(5.8)
$$z_{i} = \begin{cases} x_{i} & \text{for all } i, i \neq 2, i \in D - C \\ y_{i} & \text{for all } i, i \in D \cap C \\ v(D) - \sum_{i \in D - \{2\}} z_{i} \end{cases}$$

We shall arrive at a contradiction by showing that $(\{z_i\}; D)$ is a counter objection to the objection $(\{y_i\}; C)$ in $(x; \mathbb{Z})$. Indeed, (2.11), (2.12) and (2.14) are satisfied and so is (2.13) for $i \neq 2$. Checking for i = 2, we find that, by (5.8), (2.11)-(2.14) applied to $(\{\zeta_i\}; D)$, and by (5.6),

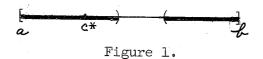
$$\begin{split} & z_2 - x_2 = v(D) - \sum_{i \in D-C} x_i - \sum_{i \in D\cap C} y_i = \sum_{i \in D-C} \zeta_i - \sum_{i \in D-C} x_i - \sum_{i \in D\cap C} y_i \geq \\ & \geq \sum_{i \in D-C} \xi_i + \sum_{i \in D\cap C} \eta_i - \sum_{i \in D-C} x_i - \sum_{i \in D\cap C} y_i = \sum_{i \in D-C} (\xi_i - x_i) + \sum_{i \in D\cap C\cap F} (\xi_i - y_i) \geq \\ & \geq \sum_{i \in D-C} (\xi_i - x_i) \geq (\xi_2 - x_2) - \sum_{i \in Q} (x_i - \xi_i) \geq 0 \end{split}$$

This completes the proof.

Corollary 5.1 Let $(x; \mathcal{B})$ be an arbitrary i.r.p.c. for a game Γ , and let B_j be a coalition in \mathcal{B} which contains 2 players. Then, the set $M_j = M_j(\{x_i\}_{i \in B_j}; \mathcal{B})$ of the points $x * , x * \in S_j$, which make B_j stable in $(\hat{x}; \mathcal{B})$, defined by (4.1), is a closed interval.

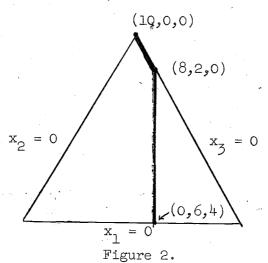
<u>Proof:</u> We may assume that B_j consists of the players 1, 2. Let ab be the simplex S_j , where $x_1 = 0$ at a and $x_2 = 0$ at b. If b is a point in ab having the property that 1 > 2 in (b, b), then, by Lemma 5.2, all the points b is a point. See (2.7), (4.2), and Definition 4.1.

the same property. Thus, the set of points x * with this property is either empty or consists of an interval with a being one of its end points. By Corollary 4.2, this interval is open with respect to $a \cdot b$. Similarly, the set of points x *, having the property that 2 > 1 in $(\hat{x}; B)$ is either empty or consists of an open interval with b as an end point. (See Figure 1.) Since the relation b is asymmetric, this implies that b is a non-empty closed interval; and therefore it is acyclic.



If $\mbox{\ensuremath{B_{j}}}$ contains more than 2 players, $\mbox{\ensuremath{M_{j}}}$ is not necessarily a convex set.

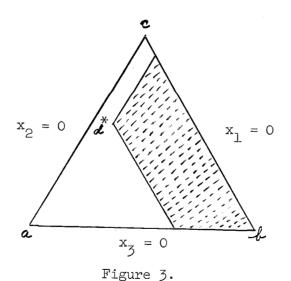
Example 5.1 Let Γ be a 5-person game with the characteristic function v(123) = 10, v(15) = 100, v(24) = 100, v(34) = 98, v(B) = 0 otherwise. It is easy to verify that the coalition 123 is stable both in (10, 0, 0, 0, 0; 123, 4, 5) and in (0, 6, 4, 0, 0; 123, 4, 5), but not in (5, 3, 2, 0, 0; 123, 4, 5), where 2 > 3. Thus, (10, 0, 0) and (0, 6, 4) belong to M = M(0, 0; 123, 4, 5) but (5, 3, 2) does not. (See Figure 2, where the points of M are marked.)



Corollary 5.2 Let $(x; \mathcal{B})$ be an arbitrary i.r.p.c. for a game Γ , and let B_j be a coalition in \mathcal{B} which contains 3 players. Then the set $M_j \equiv M_j(\{x_i\}_{i \notin B_j}; \mathcal{B})$ of the points $x * , x * \in S_j$, which make B_j stable in $(\hat{x}; \mathcal{B})$, defined by (4.1), is an acyclic closed polygon.

 $\frac{Proof:}{j}$ We know by Theorem 4.2 that M is a closed polygon.

(i) Let $B_j = (1, 2, 3)$. Let **abc** be the simplex S_j , where $x_1 = 0$ on the face **bc**, $x_2 = 0$ on **ac** and $x_3 = 0$ on **ab**. If $\mathbf{l}^* = (\mathbf{d_1}^*, \mathbf{d_2}^*, \mathbf{d_3}^*)$ is a point in S_j having the property that 1 > 2 in $(\mathbf{l}; \mathbf{l})$, draw parallels through \mathbf{l}^* to the faces **ac** and **bc**. By Lemma 5.2, all the points $\mathbf{x}^* = (\mathbf{x_1}^*, \mathbf{x_2}^*, \mathbf{x_3}^*)$ in the shaded region of Figure 3 have the same property. (Actually, by Corollary 4.2, there exists a neighborhood of this region whose points have the same property.)



(ii) We shall first show that M_j is always a connected set. Indeed, if this is not the case, let ℓ * and f* be the two nearest points in two nearest distinct components of M_j . By definition, $1 \sim 2$, $1 \sim 3$, $2 \sim 3$ hold both in $(\hat{\mathcal{L}}; \mathcal{B})$ and in $(\hat{\mathcal{F}}; \mathcal{B})$.

Characterized by $x_1^* \le d_1^*$, $x_2^* \ge d_2^*$.

Case A. Suppose that ℓ^* and f^* lie on a line parallel to a l-face, (Figure 4.) say ℓ^* , and let ℓ^* be any point of the segment ℓ^* , f^* . If ℓ^* lin ℓ^* , then in view of (i), ℓ^* also in ℓ^* , contrary to our assumption. If ℓ^* lin ℓ^* , then ℓ^* lin ℓ^* lin ℓ^* lalso in ℓ^* , lin lin line in view of (i), ℓ^* lalso in ℓ^* , line contrary to our assumption. In a similar fashion one proves that no strong relation holds between any other pair among the players 1, 2, and 3. Thus the segment ℓ^* , ℓ^* belongs to ℓ^* , contrary to the assumption that ℓ^* and ℓ^* belong to distinct components of ℓ^* .

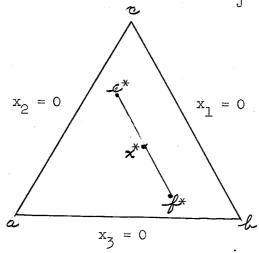
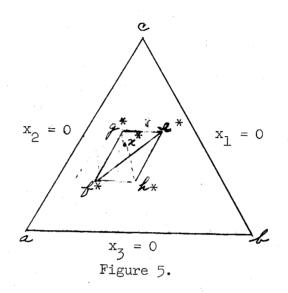


Figure 4.

Case B. Draw the straight line joining ℓ^* and ℓ^* , now assuming that it is not parallel to any of the faces of the triangle. There exists exactly one side, say ℓ , of the triangle, which forms both angles greater than 60° with this line. From each of the points ℓ^* and ℓ^* we draw lines parallel to the 2 sides other than ℓ , and consider the parallelogram formed by them. We may assume that the situation is as shown in Figure 5. Obviously, the parallelogram ℓ^* and ℓ^* belongs to ℓ^* By applying the results stated in (i), one observes immediately that ℓ^* and ℓ^* and ℓ^* lies in this closed parallelogram. Moreover, ℓ^* in ℓ^* lies in this closed parallelogram. Moreover, ℓ^* in the parallelogram and joins the points ℓ^* and ℓ^* . Then, in view of Corollary 4.2,

and the fact that \succ is an asymmetric relation, it follows that there exists a point x * on the path with the property that $2 \sim 3$ in $(\hat{x}; \mathcal{B})$. Therefore, $x * \in M_j$. Obviously, x * is closer to $x * \in M_j$ and this contradicts our assumption. Therefore, M_j is connected.



(iii) We shall now show that any 1-cycle in M_j bounds. Indeed, if α is a 1-cycle of M_j which does not bound, then there exists a point $\mathcal{L}*$ in S_j , which is surrounded by the carrier $\alpha*$ of α , and $\mathcal{L}*$ M_j . If, say, 1>2 in $(\hat{\mathcal{L}};\mathcal{B})$, then, by the result stated in (i), there is a region of points x* having the property that 1>2 in $(\hat{\mathcal{L}};\mathcal{B})$. This region connects $\mathcal{L}*$ to the face $x_1=0$ and hence it intersects $\alpha*$. This is impossible, since $\alpha*$ M_j , and we have arrived at a contradiction. This completes the proof of the Corollary.

From Theorem 5.1, Corollaries 5.1 and 5.2, we deduce:

Theorem 5.2 Let $\mathcal{B} = \mathbb{B}_1$, \mathbb{B}_2 , ..., \mathbb{B}_m be a coalition structure (2.3) for a game Γ , such that each \mathbb{B}_j , $j=1,2,\ldots,m$, does not contain more than 3 players. Then, there exists a payoff $z=x_1,x_2,\ldots,x_n$ such that $(z;\mathcal{B})$ is $\mathcal{M}_1^{(i)}$ -stable.

Assuming that M_j is now triangulated.

6. Miscellaneous.

Let \mathcal{D} be a fixed coalition-structure for a game Γ , and let $(\boldsymbol{z};\mathcal{B})$ be an i.r.p.c. We shall show that any intersection of the form $H \equiv \bigcap_{s=1}^r F_{\mu\nu_s}$, μ fixed, $\mu\nu_s \in B_j$, $B_j \in \mathcal{B}$, $r \geq 1$, (see Theorem 4.2), is acyclic. In particular, E_{μ} is acyclic. Indeed, if a point \boldsymbol{z} * belongs to H, then, by decreasing \mathbf{x}_{μ} and increasing the other components of \boldsymbol{z} * in any arbitrary way, we always get points of H, because, by Lemma 5.2, μ will remain stronger than or equal to each ν_s , $s=1,2,\ldots,r$. Moreover, the face $\mathbf{x}_{\mu}=0$ obviously belongs to H. Hence H is contractible over itself to a point, and therefore it is acyclic. By similar considerations, one can prove that the set I of points \boldsymbol{z} * having the property that a player μ is weaker than or equal to the players ν_1 , ν_2 , ..., ν_r is acylic.

Princeton University and
The Hebrew University of Jerusalem